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Mechanical & Mechanics Engineering

Leakage and Cavity Shape

Study of Minor Loss Coefficient

Highlights

Bonding of Silicon Carbide

Transient Liquid Phase Diffusion

Discovering Thoughts, Inventing Future

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The Effect of the Eccentric Loading on the Components of the Spine

By Samir Zahaf, Hamani Habib, Bensamine Mansouri, Abderrahmane Belarbi & Zitouni Azari *University of Sciences and Technology*

Abstract- The objective of this work is to study the effect of the backpack on the components of the spine system of a child, know the effect of an eccentric load on the intervertebral discs, the creating a 3D model of the spine of child of 80 kg overall weight under the effect of three eccentric load (P2, P3, P4) plus P1 compression load and calculated by the element method ends, For the boundary conditions we fixed the sacrum (Embedding the sacrum). We propose in this section to draw up a comprehensive study of the distributions of stresses and normal elastic strain of Von Mises in the intervertebral discs based on loads supported.

Keywords: child; herniated discs; lumbar-thoracic; intervertebral discs; finite element; biomechanics; von mises stress-strain; disc degeneration.

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The Effect of the Eccentric Loading on the Components of the Spine

Samir Zahaf^a, Hamani Habib^o, Bensamine Mansouri^e, Abderrahmane Belarbi^{co} & Zitouni Azari[¥]

Abstract- The objective of this work is to study the effect of the backpack on the components of the spine system of a child, know the effect of an eccentric load on the intervertebral discs, the creating a 3D model of the spine of child of 80 kg overall weight under the effect of three eccentric load (P2, P3, P4) plus P1 compression load and calculated by the element method ends, For the boundary conditions we fixed the sacrum (Embedding the sacrum). We propose in this section to draw up a comprehensive study of the distributions of stresses and normal elastic strain of Von Mises in the intervertebral discs based on loads supported. The results show that the stress and strain of Von Mises are highest and concentrated in four intervertebral discs (D1, D15, D16 and D17), which causes a problem that calls (herniated disc). We concluded that the cause of the posterior load, a 350 mm lever arm with a 200N load present maximum Von Mises stresses concentrated in four intervertebral discs (D1, D15, D16, D17), which justifies the distance between the load which is the point of application of the load and the axis of the spine plays a very important role in increasing the solicitation of the latter.

Keywords: child; herniated discs; lumbar-thoracic; intervertebral discs; finite element; biomechanics; von mises stress-strain; disc degeneration.

I. INTRODUCTION

he spine or rachis consists of a movable column of 24 free vertebrae and a fixed column formed of fused vertebrae: the sacrum and coccyx \"(Fig. 2) \" ;it is the fixing strut of many essential muscles in the posture and locomotion and protects the spinal cord located in the vertebral canal ; it supports the head and transmits the weight of the body to the hip joints; with a length of about 70 cm in men (60 cm in women), its reduction may reach 2 cm when standing [1].

Intervertebral discs connect the vertebral bodies, provide the mobility of the column and amortize them pressure and shocks. Each consisting of a peripheral annulus (annulus) containing a gelatinous core (nucleus). Disc degeneration begins, after a phase of asymptomatic dehydration, with tears in the fibrous ring. The core can then migrate into the thickness of the ring and cause acute or chronic back pain. If it moves further through the ring, the ring may protrude to the rear side of the disc while forming a HERNIATED DISC this is indicated in \"(Fig. 1) \" and \"(Fig. 2) \". This hernia can migrate into the spinal canal and even exclur leaving the disc. This disc herniation can come compress or "stuck" in one or more nerve roots located near the drive. It is the cause of symptoms: pain is sciatica when the back of the thigh, cruralgie when the pain is in front of the thigh [2] see Figure 1 and figure 2.



Fig. 1: Normal disc (top). Herniated disc (bottom) shows the gel-filled nucleus escapes through a tear in the disc annulus and compresses the spinal nerve [3].

It is the cause of symptoms when sciatic pain is in back of the thigh, crural when pain is in front of the thigh. It comprises variably pain in the lower limbs, defourmillements or tingling sensation (paraesthesia), the sensitivity to disturbance of sensation (dysesthesia) up to a complete loss of feeling (anesthesia), loss muscle strength or partial or complete paralysis or sphincter disorders. continuously exerted, the pressure of the herniated disc can cause irreversible damage [2].

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Fig. 2: Evolutionary forms of the herniated disc. (a) back pain. (b) - crack the annulus, (c) -progression the disc material, (d) – prolapse [4]. & www.espalda.org

Every year it is the same finding, schoolchildren satchels or bags to back are too heavy and can cause long-term back problems and deformities of the spine that is to say students complain of back pain, shoulder pain, muscle pain, knee pain, pain in the neck, numbness pain, bad posture, poor balance and falls due at the port of a backpack overloaded view \"(Fig. 3) \" [5].



Fig. 3: A school child wears a backpack.

Worse, their weight increases over the years from 6.5 kg in 1997 to 8 kg today in the best case. This would amount to carry to an adult of 80 kg weight 17 kg Yet the official circular of 2008 National Education clearly

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advocates that the weight of the backpack should not exceed 10% of the weight of the child, ie, primary, about 2.5 kg ... we're off!! It is between 8 and 15 years back is the most fragile, and scientific studies have demonstrated imaging (MRI), the risk of joint damage and intervertebral disc are real [5].

Yet the official circular of 2008 National Education clearly advocates that the weight of the backpack should not exceed 10% of the weight of the child, either primary, about 2.5 kg ... we're off!! It is between 8 and 15 years back is the most fragile, and scientific studies have demonstrated imaging (MRI), the risk of joint damage and intervertebral disc are real [5].

During this period of school age, the spine of children is particularly rough ride. With their school bags too heavy, students are real porter, causing stiffness and pain, which are themselves a source of bad posture on often inadequate seating.

It is in this context daily, as well as family education, the accumulation, repetition of these situations will cause joint damage, common causes such as scoliosis. This explains the fact that 67% of students suffer from muscle tension, 50% of back pain, 24% falling asleep during classes and 15% of pain in the shoulders [5]. The schoolbag defined as an eccentric load \"(Fig. 3) \", the load represented by the mass (P4), in other words, this load created a moment of posterior bending which tends to bend the spine and causes a problem called lumbar disc herniation is the most common cause of low back pain.



Fig. 4: Model biomechanics of the spine (A school child wears a backpack).

The diagram "(Fig. 4) " represents a child to age 10 years of overall specific weight 38 kg to wear a backpack, backpack is the mass of 15 kg representing the weight P4.

The MRI study [6], alerts of this overweight effect in the development of degenerative disc disease, back pain and then herniated disc $\ \$ (Fig. 5) $\$.

In this work, the simulation of the disc degeneration, based on a finite element model of the spine depending on the mechanical properties were established ; the boundary condition has been applied in the frontal plane to define restriction on movements of translation and rotation of the spine.

We propose in this work to draw up a comprehensive study of stresses and strains in the spinal discs distributions based on supported loads. The results show that the level of degeneration increased in all intervertebral discs but concentrated in the four disks D1, D15, D16 and D17.

Fig. 5 shows two vertebrae of the spinal column with an intervertebral disc under the effect of the compound loading (compression P1+ bending moment P4). The compressive load P1 creates an internal pressure in the nucleus, this pressure will there after generate the disc degeneration or degenerative disc disease \"(Fig. 5)\" and \"(Fig. 7)\", as regards the forward flexion P4, if the load of the schoolbag increases, automatically distance between the point of load application and the axis of the spinal colum increases, we see that the posterior portion of the annulus fibrosis is compressed and the other front portion is tensioned, that is to say the nucleus pulposus

burst back (posterior compression), this compression produced by disc protrusion comes into contact with a nerve root called herniated disc this mentioned in "(Fig. 2)".



Fig. 5: The intervertebral disc with (a): compression [7]



Fig. 6: Load distribution at the disc D1 according to his state [8].



Fig. 7: The intervertebral disc with (b): bending [7].

II. MATERIAL AND METHODS

The objective of this study was to investigate the effects induced by an eccentric load of the backpack on the back of a child, know the effect of an eccentric load on the intervertebral discs, cortical bone, cancellous bone, posterior bone, sacrum, basin, created a 3D model of spine, the total mass of person standing of specific global 80kg under the effect of three eccentric loads (p2, p3, p4) plus a p1 compression load and calculated by the finit element method, the boundary conditions we fixed the sacrum (incorporation of the sacrum) see \"(Fig. 4) \".

The analysis of biomechanical problems includes several steps.

The first is to study the form to define the geometrical configuration of the object, which allows the reconstitution of the vertebra, the ligament and bone using CAD programs.

The result is a 3D geometric model including these three components will then be prepared for use in finite element analyzes for the study of stresses and strains distribution in the system.

The steps for the execution of the 3D vertebra model $\(Fig. 8)$ are as follow:

- a) Draw cortical bone that is the upper hinge and the lower hinge, then make the smoothing process; this gives a solid body called the vertebral body.
- b) Secondly, draw the posterior arch (blade with the pedicle) with the spinous process.
- c) Finally we draw the transverse process.



Fig. 8: Lumbar vertebras.

The simulation of the disc degeneration is based on a finite element model of the healthy spine. Fig. 9 shows a spine model, this consists of five lumbar vertebrae (L1, L2, L3, L4 and L5) plus the sacrum and the basin, twelve thoracic vertebrae (TH1, TH2, TH3, TH4, TH5, TH6, TH7, TH8, TH9, TH10, TH11, TH12) and 17 inter vertebral discs between (S1-L5, L5-L4, L4-L3, L3-L2, L2-L1, L1-TH12 TH12-TH11, TH11, TH10, TH10-TH9, TH9-TH8, TH8-TH7, TH7-TH6, TH6-TH5, TH5-TH4, TH3-TH4, TH3-TH2 TH2-TH1) and various ligaments thoracic lumbar spine (anterior longitudinal ligament, posterior longitudinal ligament, ligament interspinous, ligament supraspinatus, yellow ligament and capsular ligament), ligaments of the basin (sacroiliac posterior ligament, sacrotuberous ligament and interosseous ligament).



Fig. 9: Spine studied.

(a): Lateral (left) view. (b): dorsal view. (c): front view. (d): lateral (right) view

In static loading conditions, the model of the reconstructed spine is used in an analysis for studying the role of the inter vertebral discs and the stress distribution in these disks as well as its supporting structures. The spine is reconstructed in 3D to study the system dimensions (IVD - ligament-bone) \"(Fig. 10)\".



Fig. 10: Vertebra and sacrum dimensions.

In order to define the boundary conditions, restriction on movements of translation and rotation of the spine has been applied in the lower plane, and defined as having zero displacements. Several charges in the anterior direction were applied as follows:

- The application of the load on the upper side of the thoracic vertebra TH1.
- The fixed part applied to the body of the basin.
- The interfaces between the different components of the system of the spine, the cortical bone, the inter vertebral disk and ligament are treated as perfectly bonded interfaces \"(Fig. 10)\".

Fig. 9 shows an isometric view of an explored assembly of the spine and each component of the spine system is denoted by letters.

ABBREVIATIONS

- D4: intervertebral disk upstairs four.
- N4: nucleus in the intervertebral disc upstairs four.
- D2: intervertebral disk upstairs two.
- N2: nucleus in the intervertebral disc upstairs two.
- L2: lumbar vertebra is on level two.
- D4: intervertebral disk upstairs four.
- N4: nucleus in the intervertebral disc upstairs four.
- AF1: annulus fibrosus one.
- AF2: annulus fibrosus two.



Fig. 11: 3D modeling thoracic vertebra L3, D4 disc of the lumbar spine (SOLIDWORKS 2016 software).



Fig 12: Model details of basin and sacrum (ligaments). *Table 1:* Mechanical characteristics of disc tissue [9].

Authors	σ _r (MPa)
BROWN (axial direction)	1.4
GALANTE (horizontal direction)	3.5 ± 0.3
GALANTE (fiber direction)	10.7 ± 0.9
WU	3.7

The selection of constitutive equations of the vertebral bone is defined as the part of the bone which carries the inter vertebral disc, composed of cortical bone, cancellous bone, the posterior arch, with a Young's modulus of about 12000 MPa. It is well known that cortical bone has better load capacity than the cancellous bone. Cortical bone is considered as an isotropic material, and homogeneous linear elastic. Table 1 shows the tensile strength of the structure annulus fibrosis according to different authors. These materials are anisotropic and non-linear elastic.

The behavior of inter-transverse ligament and inter-spinous ligament is nonlinear viscoelastic as in

previous studies [10]; a linear elastic model is chosen to represent this behavior.

Ansys Workbench software was used for analyzing this geometry and generate the most suitable mesh. For the studied behavior, we used tetrahedral elements, type Solid187 conforming to defined parametric surfaces interfaces \"(Fig. 13) \".

It is necessary to mesh the components of the spine with small and confused elements to ensure optimum accuracy of the results of stresses and strains in the inter vertebral discs.

The material properties of the spine components were selected after a careful review of the published literature "Table 2"; it was considered appropriate to define the cortical and cancellous bone as homogeneous and isotropic. The magnitudes of 12000 MPa and 100 MPa (cortical and cancellous. respectively) were observed in all studies by various researchers.

Material	Young Modulus (Mpa)	Poisson Coefficient	References				
Cortical Bone	12000	0.3	[11,13,14,15,16,17,18,19,20,21,22,27,36]				
Cancellous Bone	100	0.2	[11,14,15,17,18,19,21,22,24,25,26,27,36]				
Posterior Bone	3500	0.25	[13,14,15,18,19,21,22,24,27,28,37]				
Cartilage Endplates	12000	0.3	[21,23,25,29]				
Annulus Ground Substance	4.2	0.45	[11,14,17,19,20,21,22,23,25,33,31,32,35,36,37]				
Nucleus Pulposus	1	0.499	[12,14,15,16,18,20,21,27,30,33,34,35,36,37]				
Anterior Longitudinal Ligament	20	0.3	[14,15,17,18,19,37]				
Posterior Longitudinal Ligament	20	0.3	[14,15,17,18,37]				
Ligamentum Flavum	19.50	0.3	[14,15,17,18,37]				
Intertransverse Ligament	58.7	0.3	[14,15,17,18,37]				
Inter-Spinous Ligament	11.6	0.3	[14,15,17,18,37]				
Supra-Spinous Ligament	15	0.3	[14'15'17'18'37]				
Capsular Ligament	32.9	0.3	[14,15,17,18,37]				
The basin			[38]				
Sacrotuberous Ligament	40	0.3	[38]				
Sacroiliac posterior Ligament	40	0.3	[38]				
Interosseouse Ligament	40	0.3	[38]				

Table 2:	Material	Properties	Specified	in the	Model.
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Since physiologically the nucleus is fluid filled, the elements were assigned low stiffness values (1MPa) and near incompressibility properties (Poisson's ratio of 0.499). Biologically, the annulus fibrosus is comprised of layers of collagen fibers, which attributes to its nonhomogenous characteristics. However, due to limitations in modeling abilities, the annulus was defined as a homogenous structure with a magnitude of 4.2 MPa.

This was based on the modulus of the ground substance (4.2 MPa) and the collagen fibers reported in the literature, taking into account the volume fraction of each component. The complete model of the spine \"(Fig. 13)\" was realized by the SOLIDWORKS SOFTWARE VERSION 2014 and was then transferred to the software Calculates each element ends ANSYS 16.2 WORKBENCHE generated the default mesh then generated linear global custom mesh tetrahedra 10 nodes conform to surface.

The three views of spine model with condensed mesh are shown in \"(Fig. 13)\". All element and node numbers are specified in "Table 3".

Fig. 13 shows a complete model that consists of 1178694 elements and 2005025 nodes. Cortical bone

Table 3. Element and	l node numbers	in the column	vertebral s	evetem com	nonente
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COMPONENT	NODES	ELEMENTS	Thickness
Cortical Bone	961810	644683	3mm
Cancellous Bone	244460	164441	3mm
Posterior Bone	226389	132464	3mm
Cartilage endplates	160055	87710	3mm
Annulus Ground Substance	244800	114036	3mm
Nucleus Pulposus	42449	26112	3mm
Anterior Longitudinal Ligament	45798	24467	3mm
Posterior Longitudinal Ligament	14414	6607	3mm
Ligamentum Flavum	30226	13447	3mm
Transverse Ligament	285328	131648	3mm
Inter-Spinous Ligament	28968	13158	3mm
Supra-Spinous Ligament	17833	8279	3mm
Capsular ligament	51816	24072	3mm
Sacrotuberous Ligament	20878	10128	3mm
Sacroiliac posterior Ligament	5876	3280	3mm
Interosseouse Ligament	13756	8306	3mm
TOTAL	2005025	1178694	3mm



Fig. 13: Spine 3D finite element modeling (ANSYS 16.2 software).

The posterior arch was modeled with tetrahedral elements to 10 nodes contains (132464 elements, 226389 nodes), the nucleus pulposus in the annulus fibrosus were modeled with tetrahedral type elements 10 nodes (26112 elements 42449 nodes), the annulus fibrosus were modeled with elements of type tetrahedral to 10 nodes (114036 elements, 244800 nodes).

The gelatinous cartilage modeled with a tetrahedral element to 10 nodes (87710 elements, 160055 nodes). Finally, the different types of ligaments generated by a tetrahedral mesh to 10 nodes "Table 3". The diagram in \ "(Fig. 4) \" shows a person standing of specific global 80kg weight, the overall mass (Head, Neck, Arm (left + right), Forearm (left + right), hand (left + right)) is 13,4517kg to divided by the top surface of the thoracic vertebrae Th1 representing the pressure P1, P2 load represents the mass of the body superior Trunk is 12,768kg, the distance between the point of application of the load and axis (yy ') is 200 mm \ "(Fig. 14) \".

The total mass of the lower trunk of the human body is equal to 22 kg; represented by P3, the distance between the point of application of the load and the axis (yy ') is 250 mm \ "(Fig. 14) \" P4 represents the maximum mass of the backpack is (20 kg), the distance between the point of load application and the axis (yy ') of the spine is (350 mm) \ "(Fig. 14) \".

For the boundary conditions we fixed the sacrum (Embedding the sacrum) \"(Fig. 14) \". We propose in this section to draw up a comprehensive study of the distributions of stresses and elastic strain in the intervertebral discs, the cortical bone, cancellous bone, the posterior arch, anterior longitudinal ligament and posterior according to the supported loads. Distributions of global stress state for each component of our model were presented.

A quantitative analysis was performed based on a scale of progressive visual colors predefined by the software used (ANSYS Workbench 16.5), ranging from dark blue to red.



Fig. 14: Model biomechanics of the spine (posterior loading).

III. Results

Fig (15) shows a histogram of stress and maximum strain of Von Mises, we notice that the spine undergoes a concentration of maximum stresses in the thoracic region, in the order word the stresses in the thoracic vertebrae (Th3, Th4, Th5, Th6, Th7) are respectively equal to (995,68MPa, 754.61 MPa, 467.09 MPa, 483.08 MPa, 369.65 MPa) as mentioned in \ "(Fig. 17) \".

Fig 16 shows a load applied to the upper surface of the thoracic vertebra TH1 of the spinal column causes a high concentration of maximum Von Mises strains in the anterior part of vertebral bodies (red section) this is mentioned in $\ "(Fig. 17) \"$.

On the other hand, Fig 17 shows that the posterior arch of the thoracic vertebrae (Th3, Th4, Th5, Th6, Th7) absorbed the maximum von Mises stresses, these stresses were observed on a posterior side of the spine (red contour) with respect to other components of the system of the spine. Proceeding from the fact that the Fig (17) and (16) that watches the posterior load presents greater strains within two thoracic vertebrae (Th3, Th4) which are equal to (0.29194, 0.21867), which means that the so-called vertebrae are the most stressed in the case of posterior bending.

Fig (18) shows that the posterior loading presents maximum stresses and strains concentrated in the intervertebral disc D1 that is to say between the sacrum and the lumbar vertebra L5, in the order word the \ "(Fig. 19) \" clearly shows that the loading posterior with a lever arm equal 350mm presents maximum Von Mises stresses and strains concentrated in the disc D1 and are respectively equal to (6,9797MPa, 1,7347mm / mm).







Fig. 16: Distributions of stresses and strains in the thoracic vertebrae (Th3, Th4) for a load of 20kg.







We see in Fig (18) the intervertebral discs (D1, D15, D16, D17) absorbed the maximum stresses that equal (6,9797MPa, 4,4374MPa, 4,7858MPa, 2,7365MPa), On the other hand the posterior loading presents of maximum strains concentrated in the intervertebral discs (D1, D15, D16, D17) which are respectively equal to (1.7347, 1.0586, 1.1463, 0 66065) as mentioned in \ "(Fig. 19) \". Figure (9) shows that the mixed loading (P1 compression + bending moment (P3)) has a contour of maximum red part stresses in the disc D1 and we see in this figure the front part of the

disc D1 is pulled and another compressed part, other hand figure (9) clearly shows that the backpack is a repeated effort back into everyday life ultimately cause disc problems, particularly at the lumbar region (lumbar disc herniation).



Fig. 19: Distributions of stresses and strains in the DIV for a load of 20kg.



Fig. 20: Distributions of stresses and strains in the intervertebral disc D1 for a load of 20kg.

Fig (20) shows that the mixed loading (P1 compression + bending moment (P3)) has a contour of maximum stresses red part in the disc D1 and we see in this figure the front part of the disc D1 is pulled and another compressed part, other hand \ "(Fig. 20) \" clearly shows that the backpack is a repeated effort to back into everyday life ultimately cause disc problems, particularly at the lumbar region (lumbar disc herniation).

We see in Fig 21 that the backpack it's a very dangerous loading and with time creates pain in the 1st, 2nd intervertebral disc and causes sciatica or cruralgia, regarding the spinal nerve compressed by the two disks (D1, D2) and the pressure causes intense pain radiating throughout the leg, the path of pain follows closely the

path of the nerve. In extreme cases, this results in partial or complete paralysis of the leg.

A load applied to the upper surface of the thoracic vertebra TH1 of the spinal column causes a high concentration of normal maximum von Mises stresses in the anterior and posterior part of the cortical bone (S1, Th12, Th5, Th1) (parts by red) this is indicated in "(Fig. 22) ".



Fig. 21: Images of a girl 17 years old suffering back pain so severe, she was unable to walk. TDM spine lumbosacral axial section (a, b) and sagittal reconstruction (c) showing a double HD L4-L5 and L5-S1 (d) Standard radiography spine profile lumbosacral showing a pinch last intervertebral disc L5-S1.



Fig. 22: MRI of the lumbar sacral spine of a 16-year-old boy showing: (a) MRI weighted sagittal sequence T1, T2, (b) weighted axial T2, (c) showing a herniated disc L5-S1 posterolateral left side and migrated down.



Fig. 23: Histogram of stresses and deformations in the cortical bone for load of 20kg.

On the other hand, \ "(Fig. 22) \" shows that the maximum von Mises stresses in the cortical bone (S1, Th12, Th5, Th1) are equal to (40,069MPa, 140.15 MPa 223.82 MPa 496, 69 MPa) as compared to other components of the system of the spine see \ "(Fig. 24) \". A loading of the posterior backpack applied on the upper surface of the thoracic vertebra TH1 of the spinal column causes a high concentration of maximum normal strains in the anterior part of the thoracic vertebra Th (red part) this is mentioned in \ "(Fig. 23) \", with regard to the said vertebra supported Von strain value set which are equal to (0,041791mm / mm) relative to the other components of the system of the spine.

Fig (25) shows a histogram of the stresses and strains Von put supported by the cancellous bone and it is noted that the maximum stress is concentrated in the cancellous bone of the thoracic vertebra Th1 as shown in "(Fig. 26) ".

The posterior load \ "(Fig. 3) \" shows clearly that the stresses and strains of Von Mises are concentrated in the two cancellous bone (Th1, Th5) and are respectively equal to (4.6282Mpa, 5.7386MPa) and (0.049594, 0.057685) this is mentioned in the (Fig 26)



Fig. 24: Distributions of stresses and strains in the cortical bone for load of 20kg.



Fig. 25: Histogram of stresses and strains in the cancellous bone with a load of 20kg.



Fig. 26: Distributions of stresses and strains in the cancellous bone with a load of 20kg.





Fig. 27: Histogram of stresses and strains in the posterior arch for a load of 20kg.



Fig. 28: Distributions of stresses and strains in the posterior arch for a load of 20kg.

The posterior loading of the backpack with a 350mm lever shown that increased stresses and strains of Von Mises illustrated in the face of upper and lower articulation of the posterior arch of the thoracic vertebrae (Th3, Th4, Th5, Th6, Th7) (red outline) $\ "(Fig. 27) \,"$, on the other hand $\ "(Fig. 28) \"shows clearly legend stress and strain of Von Mises put in the thoracic region (Th3, Th4, Th5, Th6, Th7) are respectively equal to (995,68MPa, 754,61MPa, 467,09MPa, 483,08MPa, 369,65MPa) and (0.29194, 0.21719, 0.16183, 0.21867,$

0.21867) compared to other components of the system spine. We see in Figure 18 the role of the basin to transmit the load to the lower part of the human body and absorbation stresses and strain Von bets (red outline), we note that the two bodies (basin, sacrum) supported stresses and normal elastic deformations which are equal to (46,069MPa, 28,201MPa) and (0.012947, 0.0187) relative to the other components of the system of the spine.





IV. Discussion

In sum, we concluded that the posterior loading is certainly an aggravating factor, and may cause long term back problems and strains of the spine, the 3D model of the spine of a child under the effect of an eccentric load and calculate by the FEM provokes stress and strains maximum of Von Mises concentrated in the intervertebral disc (D1) and are equal to (6,9797MPa, 1,7347mm / mm) as noted in the \ "(Fig. 18) $\$, with regard to $\$ (Fig. 19, 20, 21) $\$ show that the intervertebral disc (D1) is the most damaged which is disc degeneration often occurs after a phase asymptomatic dehydration cracks, tearing of annulus fibrosus (D1), the nucleus (N1) can then along these cracks migrate into the ring thickness (D1), and cause acute or chronic back pain, If the core (N1) move around more through the ring (D1), the core can project to the posterior surface of the disc while forming a lumbar disc herniation, this hernia can complete rupture of the ring, migrate laterally into the vertebral canal, or up or down, and even exclude leaving the disk, herniated disc that can come be compressed one or more nerve roots "stuck" near the disc, causing the symptoms of pain "sciatica" when the rear seat of the thigh or "cruralgie" when the seat of pain in the front of the thigh. This justifies that the distance between the load which is the point of application of the load and the axis of the spine plays an important role in increasing stresses at the intervertebral discs.

V. CONCLUSION

In sum, we concluded the case of posterior loading 350mm lever arm with a load 200N posterior indicate normal maximum Von Mises stresses in four intervertebral discs (D1, D15, D16, D17) and are equal to (6,9797MPa, 4,4374MPa, 4,7858MPa, 2,7365MPa) these mentioned in \ "(Fig. 18) \", on the other hand \ "(Fig. 19) \"clearly shows the elastic strain is higher in the four intervertebral discs (D1, D15, D16, D17) that are equal (1.7347, 1.0586, 1.1463, 0 66065), which justifies that the distance between the load which is the point of application of the load and the axis of the spine plays a very important role in increasing the solitation of the latter.

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Leakage and Cavity Shape Studies of Labyrinth Seals

By R Mohana Rao & Dr. Manzoor Husain

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Keywords: labyrinth seal, CFD, ansys workbench, canted shape

GJRE-A Classification: FOR Code: 290501

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Leakage and Cavity Shape Studies of Labyrinth Seals

R Mohana Rao^α & Dr. Manzoor Husain^σ

Abstract- Labyrinth seals are a non-contacting sealing device consists of a series of cavities connected by small clearances. They are used in many places in gas turbine engine to optimize and improve their design using CFD, is of interest to this study with newer designs of labyrinth seal. Preliminary investigations were carried out to establish the baseline capability for CFD analysis of labyrinth seals using Fluent and also to finalize the turbulence model with mesh type, thereafter detailed 2-D axi-symmetric analyses with different geometries and configurations. The applications of the new labyrinth seal designs are important to meet future performance of gas turbine goals. This paper presents improved design of canted seal design using RANS equations, with Turbulence two equations k-w turbulence model using Computational Fluid Dynamics (CFD).

Keywords: labyrinth seal, CFD, ansys workbench, canted shape

Nomenclature

ε - Dissipation of turbulent kinetic energy

- κ Turbulent Kinetic energy
- s- Tooth pitch, mm
- A: Area [m2]
- H: Step height [mm]
- h: Teeth height [mm]
- k: Specific heat ratio
- m: Mass flow rate [kg/s]
- N: Number of teeth
- Po: Total pressure [kPa]
- PR: Pressure ratio, Poin/Pout
- s: radial clearance [mm]
- To: Inlet total temperature [K]

Abbreviations

RANS – Reynolds-Averaged Navier- Stokes

I. INTRODUCTION

viation industry face challenges when crude oil price increase that influence the economic conditions of world. This will directly impact on the engines running on crude oil products which convert mechanical chemical energy into energy for etc., transportation, power generation lead to optimization of turbo machinery future fuel conservation requirements. Studies show that reducing the high pressure turbine seal leakage of engine airflow would produce significant improvement of engine specific fuel consumption.

Gas path sealing is therefore a fundamental area of interest when seeking improvements in the efficiency and performance of aircraft engines. By reducing the level of leakage from the gas flow, efficient sealing helps retain the energy. As the performance improvement becomes marginal, reduction in leakage flows becomes more important. Therefore, labyrinth seals are used more intensively, their clearances are more tightly designed hence configurations are evolving continuously. Therefore, the requirement for an accurate leakage prediction is becoming more crucial. Labyrinth seals are the most common flow path seals applied to turbine engines. They consist of several knife edges in close clearance in a number of Configurations. Labyrinth seals rely on controlled leakage across the seal driven by the pressure difference between the seal ends. The design of the seal forces the flow to separate at the knife edge causing loss of kinetic energy and pressure from the gas flow.

II. Present Work

In order to finalize the combination of parameters to be changed to improve the seal design. the experimental case of advanced seal configuration, Design 5; reported by H. L. Stocker in [3] is considered as baseline case. In the present work, the authors have conducted а CFD investigation on different configurations of canted teeth. The design evolved while conducting a parametric study on teeth height, teeth tip thickness, stepped teeth, inclined teeth etc. The baseline configuration is a simple sharp teeth labyrinth seal. The results obtained for the baseline configurations using this methodology were validated by comparing against 2D and 3D experimental data on stationary labyrinth seals with smooth land.

a) Baseline geometry: Canted Sharp Teeth

Fig. 1 shows labyrinth seal geometry with dimensions. The labyrinth seal test section consists of an upper part, stepped, and a lower part with teeth. In a real engine, the upper and lower parts correspond to the stationary and rotating parts, respectively, have 4 teeth with inclined called Canted Seals. The two seals have almost similar teeth dimensions. Geometry definition:

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Pitch – 7.62 mm; step height – 3.05 mm; Knife height – 3.81 mm and seal canted angle 50 deg



Fig.1: Base line teeth with 50 degree canted

b) New geometry: Canted Advanced Teeth

Fig.2 depicts the advanced sharp teeth are modified to increase the base of seal called Canted Advanced teeth. Except base width rest of parameters are kept same as original design.



Fig.2: Modified advance seal teeth with 50 degree canted

c) Performance Parameters

The performance of a seal can be described by the relation between the pressure ratio and a flow parameter. The most common flow parameter is the following flow function:

$$\frac{m\sqrt{T_o, in}}{A_c P_O, in}$$

III. ANALYSIS

a) Numerical analysis

Computational Fluid Dynamics (CFD) is extensively used because its capability to analyze a large number of design configurations and parameters in a relatively short period of time. Therefore, with the development of commercial codes, the use of CFD analysis has been increasing rapidly in recent years in 2 or 3 dimensional analysis. The test cases adopted in this work are two-dimensional with number of different operating conditions are analyzed.

b) Boundary Conditions

A commercial finite volume code, Ansys Workbench with Fluent 16.1v [10] is used. This commercial tool has wave linking geometry that

eliminates loss of geometry while importing from CAD model to Fluent, manages entire problem in project charter. It was assumed that air was an incompressible ideal gas and the flow was steady and adiabatic. Various turbulence models available in Fluent [10] were considered for the current simulations.

A realizable two-layer k- ϵ turbulent model was used closest to Stocker [3], This model combines the realizable k- ϵ turbulent model with the two-layer approach. The realizable k- ϵ turbulent model uses equivalent kinetic energy and dissipation rate equations, but has additional flexibility of all y+ wall treatment that gives reasonable results for intermediate meshes where the cell falls in the buffer layer. Polyhedral mesh elements were used to create unstructured meshes in the entire domain. Fig.3 & 4 shows an example of generated computational grids.

The grid density in the clearance area was refined to locate sufficiently large number of meshes, this is done using inflation of smooth transition with 8 \sim 10 layers. For a given geometry, the inlet temperature is kept ambient and the exit pressure was essentially ambient (99.5kPa) and inlet pressure is varied to corresponding inlet total pressure was obtained thru calculation.

c) Mesh



Fig. 3: Baseline geometry mesh (Model A)



Fig. 4: Modified Advance seal mesh (Model B)

d) Mesh Sensitivity



Fig. 5: Grid dependence of the CFD result

Grid dependence was checked to produce *e*) sufficiently converged solutions according to mesh size. Fig. 5 shows an example of grid dependence in the case of the Base geometry seal, presenting a variation of pressure ratio with the number of meshes for a given mass flow rate. The number of meshes ranges from th 26,000 to 220,000 for the sharp teeth seal and from pr 43500 to 250,000 for the modified stepped seal, so depending on the clearance size.

e) Single Vs Double Precision Solver Comparison Study To study use of single and double precision solvers, baseline case was analyzed using single precision solver. The results from single precision solver were similar to those obtained except inlet velocity from the double precision solver. The CPU time for single precision solver was found more than double precision solver.

			At Inlet		At Exit						
S.no	Analysis Description	No. of Cells	Mass flow (m/s)	V (m/s)	Temp (k)*	V (m/s)	Mass flow (m/s)	Pt (psa)*	Temp (k)	Del. T (k)	Pr = Pt(in)/ Ps(out)
1	Single Precision Solver	177644	0.0073	9.5577	295.14999	14.203	-0.007	99500	323.14679	27.997	2
2	Double Precision Solver	177644	0.0077	10.047	295.14999	12.977	-0.008	99500	323.14999	28	2



Fig. 6: Convergence plot for Double Precision


Fig. 7: Convergence plot for single Precision

f) Model A case with Experimental data
The Model A and Model B are run through by rarying inlet pressure with ambient temprature and at

exit ambient pressure. Models are run the pressure ratio reaching $\mathbf{3.0}$



Fig. 7: Model A velocity contours

The model A results are plotted with experimental results. This is in line with the data. Refer

the fig. for the graph showing experimental results CFD data which is \sim 5% variation.



Fig. 8: Model a results with Experimental results

a) Turbulence Model Study

2D axi-symmetric analysis of the modified

Labyrinth Seal geometry (with rotation speed of 10,000

rpm) was first carried out. The objective was to establish

baseline capability to run lab seal CFD analysis using

Fluent and validate the experimental results.

IV. Results and Discussion

Analysis of Results with different Seal Configurations

In this paper following studies are carried:

- Various Turbulence Models Studied
- Model A case with canted angle:70, 60, 40
- Step height: 2.0 mm and 3.05 mm
- Knife-edge clearance: (0.25 and 0.51 mm)
- Rotor speeds (rpm): 0,10000, 20000, 30000

At Inlet At Exit Del. T Pr =Analysis No. of S.no Pin Mass Vin Vout (deg R) Pt(in)/ Tout Description Cells temp Ps(out) (Pas Cal) flow (m/s) (m/s) (k) Std. k-e (T.I-1 10%.L.s-2 197061 199200 295.14999 0.00754186 10.37968 15.023524 300 4.85001 5%),2layer zornal model Std. k-e (T.I-2 3%,L.s-197061 199200 295.14999 0.00753624 10.37896 15.023502 300 4.85001 2 3%),2layer zornal model 3 Std. k-e (T.I-1%,L.s-197061 199200 295.14999 0.00754114 10.38819 15.04188 300 4.85001 2 3%),2layer zornal model 4 Spalant (T.I-Allmaras 3% | s-197061 0.00475953 11.53694 300 4.85001 199200 295.14999 6.729263 2 3%),strain Vorticity based production 5 K-omega (T.I-3%,L.s-2 3%),Compress 197061 199200 295.14999 0.00600749 8.296661 39.94806 300 4.85001 ibility effects. shear flow correction 6 R.S.M (T.I-3%,L.s-B.C 3%),Wall from 197061 199200 295.14999 0.00613915 9.127268 28.85895 300 4.85001 Κ 2 equation, Wall reflection effects

Table 2: Turbulence Models

The Fluent results matched with the experimental results. This analysis was followed by turbulence models studies. The baseline model was analyzed first with Standard $k-\epsilon$ model (Turbulence Intensity = 10% and Length Scale = 5%). The same model was then analyzed with standard k- ϵ turbulence model but for different turbulence parameters, namely, Turbulence Intensity (T.I.) of 3% & 1%, and Length Scale (L.S.) 3% & 1% respectively. Standard k-ε, Spalart-Allmaras, k-omega, Reynolds's Stress Model were tried out with the baseline geometry. All the turbulence models showed consistent results except RSM & Spalart-Allmaras, with less mass flow and low velocities. It was decided to use Standard k- ε model for all future analyses.

b) Model A case with Canted angle

For Base line case (Model A) the canted angle is varied with 40, 60 and 70 degree and the analysis is carried with same boundary condition but the results show no improvement in flow parameter. Flow parameter values are much higher (15 % to 60%) compared with base line canted 50 degrees. Refer fig. 9 for velocity contours. The studies reveal that 50 degree is optimal canted angle for seal design for leakage flow.



Fig. 9: Model A with various canted angles of velocity contours

c) Model B studies with step height and clearance

Analyses with step height and wall clearance between fixed wall and rotating wall are carried. Refer Fig. 10, 11,12, 13 with wall clearance (0.25, 0.51) and step heights (2.0 & 3.05) are analyzed based on review of minor differences in flow feature, the spacing of 0.25 was finalized for future axi-symmetric analyses. The models are analyzed for 10000 rpm. This analysis was considered as baseline analysis for all subsequent analyses. To improve the sealing efficiency, several labyrinth seal designs with varying geometries were analyzed



Fig. 10: Model B with .51 clearance and 3.05 step height- velocity contours



Fig. 11: Model B with .25 clearance and 3.05 step height- velocity contours



Fig.12: Model B with .25 clearance and 3.05 step height- velocity contours of Tooth 1 and 2.



Fig. 13: Model B with .25 clearance and 3.05 step height- velocity vectors (stream function) of Tooth 2. Comparing Figures 7, 10 and 11 the model B with .25 with step height 3.05 has created more turbulence in the flow thereby creating frictional flow resistance. Also since the stepped walls are inclined in the direction opposing the flow, there is direct resistance created for the flow to move downstream.

As observed in Figures 12 and 13 vortices are formed in the stepped wall zone at the outermost portion of the cells between sharp teeth also the vortices in the lower zone of the cells appear to be intensified. The step disrupts flow entering the clearance region and increases flow lockage upstream of and in the clearance area thereby reducing the exit pressure at each tooth (following the second tooth) overall leakage as compared to the baseline sharp teeth design.

Fig. 14 shows the seal performance of various models. Model B with .51 clearances has not shown much improvement. The flow parameter vs pressure ratio for this case is very high compared to base line sharp teeth model but Model B with .25 clearances is shown much higher improvement than any model.

Model B with .25 clearances shows 14.9% improvement when compared to Baseline Model A.



Fig.14: Seal performance of various models

The high performance seal Model B is further studied with various speed parameters. It shows the speed increase performance further improved this is because of radial velocity creates turbulence flow in the flow path that restricts movement. Refer Fig. 15 for seal performance at various speeds.



Fig. 15: Seal performance of various models with different speeds

V. Conclusions

- a) Standard k-ε, Spalart-Allmaras, k-omega, and RNG k-ε models give similar flow field for the analyzed lab seal configuration. Reynolds Stress Model gives elevated temperature field inside the domain. RNG k-ε turbulence model predicted less temperature rise and more pressure drop. The effect of throttling process in tooth clearance and the vortex flow are two main factors which influence flow resistance and leakage in seal.
- b) The solution time is more with single precision solver than double precision solver
- c) Model B with .25 clearance shows 14.9% improvement than baseline Model A.

Further work may be carried out for honeycomb wall with various diameters. Also air injection study with holes (modeled as slots in the 2d axi-symmetric analysis) to introduce in between the knife-edges in order to disturb the jet studies may be carried out.

VI. Acknowledgment

The authors wish to thank Kondalarao N and Suresh B for their contributions during case studies.

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Study of Minor Loss Coefficient of Flexible Pipes for Different Bend Angles and Different Bend Radius by Experiment and Simulation

By M. S. Islam, Avizit Basak, M. A. R. Sarkar & M. Q. Islam

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Abstract- The aim of this work is to investigate the minor loss for locally available bended flexible pipes of different dimensions. Minor loss coefficients for different bend angles and different bend radius of these pipes are ascertained, using both experimental method and numerical analysis. Different parameters on which Minor Loss depend were observed and their relations to the Minor Loss were analyzed. Minor loss coefficient for different bend angles and two bend radiuses were determined. Minor losses were measured under different flow rates. The Minor Loss Co-efficient was also determined by solving Navier-Stokes Equation, with the help of standard computer program. For Turbulent Stresses Boussinesq assumption is used. As Turbulence model $k - \varepsilon$ is implemented. Navier-Stokes equations for viscous, incompressible flow shows mixed elliptic-parabolic behavior. So, semi-implicit method for pressure linked equation (SIMPLE) was used.

Keywords: Minor Loss Co-Efficient, Bends, \overline{k} - ε Turbulence Model. GJRE-A Classification: FOR Code: 091399p

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Study of Minor Loss Coefficient of Flexible Pipes for Different Bend Angles and Different Bend Radius by Experiment and Simulation

M. S. Islam^{\alpha}, Avizit Basak^{\alpha}, M. A. R. Sarkar^{\alpha} & M. Q. Islam^{\overline}

Abstract- The aim of this work is to investigate the minor loss for locally available bended flexible pipes of different dimensions. Minor loss coefficients for different bend angles and different bend radius of these pipes are ascertained, using both experimental method and numerical analysis. Different parameters on which Minor Loss depend were observed and their relations to the Minor Loss were analyzed. Minor loss coefficient for different bend angles and two bend radiuses were determined. Minor losses were measured under different flow rates. The Minor Loss Co-efficient was also determined by solving Navier-Stokes Equation, with the help of standard computer program. For Turbulent Stresses Boussinesg assumption is used. As Turbulence model k-ε is equations implemented. Navier-Stokes for viscous. incompressible flow shows mixed elliptic-parabolic behavior. So, semi-implicit method for pressure linked equation (SIMPLE) was used.

Keywords: minor loss co-efficient, bends, \bar{k} - ϵ turbulence model.

I. INTRODUCTION

The losses that occur in pipelines due to bends, elbows, joints, valves etc are called minor losses. Minor loss in a bend is due to flow separation on the curved walls and a swirling secondary flow arising from the centripetal acceleration. Since the flow pattern in valves, bends and fittings are quite complex, the theory is very weak. The losses are usually measured experimentally and correlated with the pipe flow parameters. In turbulent flow, the Minor Loss varies as the square of the velocity. The form of Darcy's equation used to calculate minor losses of individual fluid system components is expressed by the equation

$$h_m = k v^2/2g$$
(1)

Where, h_m = minor loss for a fitting, k = minor loss coefficient, v = velocity of the fluid for the time. Bends are provided in pipes to change the direction of flow through it. An additional loss of head, apart from that due to fluid friction, takes place in the course of flow through pipe bend. The fluid takes a curved path while flowing through a pipe bend as shown in figure 1. Whenever a fluid flows in a curved path, there must be a force acting radially inwards on the fluid to provide the inward acceleration, known as centripetal acceleration. This results in an increase in pressure near the outer wall of the bend, starting at some point A and rising to a maximum at some point B. There is also a reduction of pressure near the inner wall giving a minimum pressure at C and a subsequent rise from C to D.

Therefore, between A and B and between C and D the fluid experiences an adverse pressure gradient (the pressure increases in the direction of flow).



Figure 1: Flow through bend pipe

Fluid particles in this region, because of their close proximity to the wall, have low velocities and cannot overcome the adverse pressure gradient and this leads to a separation of flow from the boundary and consequent losses of energy in generating local eddies.

Losses also take place due to a secondary flow in the radial plane of the pipe because of a change in pressure in the radial depth of the pipe. This flow, in conjunction with the main flow, produces a typical spiral motion of the fluid which persists even for a downstream distance of fifty times the pipe diameter from the central plane of the bend. This spiral motion of the fluid increases the local flow velocity and the velocity gradient at the pipe wall, and therefore results in a greater frictional loss of head than that which occurs for the same rate of flow in a straight pipe of the same length and diameter.

In the context of our study, there are some contributions of particular importance. Khan and Islam [1] made an experimental investigation of flow through flexible pipes and bends. In their work they used metal made pipes. Two manometers were used: one for trough to trough and one for crest to crest readings. Khan, Ahmed, Jonayat [2] determined friction factor of

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flow through flexible pipes and minor loss coefficient of flexible bends. Ahmed, Chakraborty and Fattah [3] did their work on locally manufactured PRR pipes bends to measure friction factor and minor loss coefficient respectively. In 1895 Reynolds [4] rewrote Navier-Stokes equation in time averaging form. Jones and Launder [5] and Harlow and Nakayama [6] developed k $-\epsilon$ turbulence around 1970 model. In 1972 Caretto, Patanker and Spalding [7] introduced SIMPLE algorithm for solving Navier-Stokes Equations for viscous, incompressible flow. Jaiman, Oakley and Adkins [8] did CFD modeling of corrugated flexible pipes. In their work they constructed a numerical model of the corrugated flexible pipes and did simulation to show variation of velocity distribution throughout the pipe, 2011).

II. SETUP & DATA COLLECTION

a) Experimental Setup



Figure 2: Schematic Diagram of Experimental Setup

b) Specimen Preparation

- At first flexible pipes are trimmed into required length using a hack-saw.
- One PVC pipe (1 inch) is selected corresponding to the diameter of reducer and threads were cut at the end of the PVC pipe to be fitted with reducer.
- The end of the PVC pipe which was to be matched with the flexible pipes was smoothened and chamfered.
- Now using drill machine, two drills transverse to the flexible pipe's length were made at two modes where manometer are required to be connected with pipe nipples With help of two pipe tubes (1.5mm diameter).
- Steps 1 to 4 were repeated for pipe bends. To hold the bended flexible pipes in the desired position stand were used.
- Now that required machining operations are done; specimen were properly washed and cleaned to eliminate dirt, oil and other undesirable internal surface matter.

- c) Construction Setup
- One end of the flexible pipe was connected with the corresponding PVC pipe with the help of reducer (reducer is fitted with the gate valve).
- Thread tapes were used to ensure proper sealing in different connections.
- The other end of the flexible pipe was directed to the bucket.
- After preparing the manometer, manometric fluid (CCl4) was injected to it.
- The limbs of manometer were connected to the nipples attached to the specimen through flexible tubes (1.5mm diameter) and fine wires were used to ensure proper sealing.
- > Priming of the manometer was performed.
- Two stands were used to maintain the specimen horizontal and wood piece was used to keep the discharge end at elevated height to ensure full flow of water.
- d) Data Collection Procedure

In order to collecting data working fluid (water) was allowed to flow through the experimental setup for three different dimensions of the flexible pipe. Differential Manometer was used to measure pressure drop through the bend. As manometric fluid, Carbon Tetra-Chloride (CCL4) was used.

- At first, the inner diameter of the specimen was measured.
- The room temperature was observed.
- Mass of empty bucket was measured.
- ✤ The zero level of the manometer was checked.
- By opening the gate valve water was allowed to flow through the testing section and all the sealing was checked.
- Now stop-watch was turned on and water flowing through the pipe was collected to the bucket.
- Steady state manometer readings were collected.
- After a time, stop-watch was turned off and mass of water filled bucket was measured by platform scale.
- Stop-watch reading was taken.
- By changing the gate valve opening flow rate was varied and reading were taken at these flow rates by repeating step six to nine. These way four readings were taken for each bend angle.
- The above procedure was performed for three different diameters and two different bend radius.

III. Theory

The simulation of water flow in a flexible bend pipe of different diameter, bend radius and angle was done by solving the Navier-Stokes Equation, with the help of commercial simulation software ANSYS 13 (WORLBENCH and FLUNET).

The fluid flow phenomenon is governed by the Navier-Stokes Equations. As the temperature change was slight during the experiment. So the simulation was done assuming constant temperature. This simplified the process by decoupling Continuity and Momentum equation from Energy equation. Now, Reynolds Timeaveraged Navier-Stokes equation,

Continuity equation:

$$\frac{\partial \bar{u}}{\partial x} + \frac{\partial \bar{v}}{\partial y} + \frac{\partial \bar{w}}{\partial z} = 0$$
 (2)

Momentum Equation:

x-component:

$$\rho\left(\frac{\overline{u}(\partial\overline{u})}{\partial x} + \frac{\overline{v}(\partial\overline{u})}{\partial y} + \frac{\overline{w}(\partial\overline{u})}{\partial z}\right) = -\frac{\partial\overline{p}}{\partial x} + \frac{\partial}{\partial x}\left(\mu\frac{\partial\overline{u}}{\partial x} - \rho\overline{u'v'}\right) + \frac{\partial}{\partial y}\left(\mu\frac{\partial\overline{u}}{\partial y} - \rho\overline{u'v'}\right) + \frac{\partial}{\partial z}\left(\mu\frac{\partial\overline{u}}{\partial z} - \rho\overline{u'w'}\right)(3)$$

y-component:

$$\rho(\bar{u}\frac{\partial\bar{v}}{\partial x} + \bar{v}\frac{\partial\bar{v}}{\partial y} + \bar{w}\frac{\partial\bar{v}}{\partial z}) = -\frac{\partial\bar{p}}{\partial y} + \frac{\partial}{\partial x}\left(\mu\frac{\partial\bar{v}}{\partial x} - \rho\overline{u'v'}\right) + \frac{\partial}{\partial y}\left(\mu\frac{\partial\bar{v}}{\partial y} - \rho\overline{v'^{2}}\right) + \frac{\partial}{\partial z}\left(\mu\frac{\partial\bar{w}}{\partial z} - \rho\overline{v'w'}\right) (4)$$

z-component:

$$\rho\left(\bar{u}\frac{\partial\bar{w}}{\partial x} + \bar{v}\frac{\partial\bar{w}}{\partial y} + \bar{w}\frac{\partial\bar{w}}{\partial z}\right) = g - \frac{\partial\bar{p}}{\partial z} + \frac{\partial}{\partial x}\left(\mu\frac{\partial\bar{w}}{\partial x} - \rho\overline{u'w'}\right) + \frac{\partial}{\partial y}\left(\mu\frac{\partial\bar{w}}{\partial y} - \rho\overline{v'w'}\right) + \frac{\partial}{\partial z}\left(\mu\frac{\partial\bar{w}}{\partial z} - \rho\overline{w'^{2}}\right)$$
(5)

Here the terms $\rho \overline{u'}^2$, $\rho \overline{u'v'}$ etc are called turbulent stresses.

According to Boussinesq assumption^[9]

$$\rho \overline{u'_i u'_j} = 2\mu_T S_{ij} - \frac{2}{3} \delta_{ij} \left(\mu_T \frac{\partial u_k}{\partial x_k} + \rho \overline{k} \right)$$
(6)

Where, $S_{ij} = \text{mean strain tensor} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$, $\mu_T = \text{Turbulent viscosity}, \ \bar{k} = \text{Kinetic energy of turbulence}, u = (u, v, w)$ Fluctuating velocity vector, x = (x, y, z) = Position Vector.According to \mathbb{K} - ε model ^{[5][6]}

$$\mu_T = \frac{C_\mu \rho(\bar{k})^2}{\varepsilon} \tag{7}$$

Here, ε = Dissipation rate.

The transport equation for kinetic energy of turbulence $\bar{k},$

$$\rho\left(\bar{u}\frac{\partial\bar{k}}{\partial x} + \bar{v}\frac{\partial\bar{k}}{\partial y} + \bar{w}\frac{\partial\bar{k}}{\partial z}\right) = \frac{\partial}{\partial x_i}\left[\left(\mu + \frac{\mu_T}{Pr_k}\right)\frac{\partial\bar{k}}{\partial x_j}\right] - \rho\varepsilon + \left(2\mu_T S_{ij} - \frac{2}{3}\rho\bar{k}\delta_{ij}\right)\frac{\partial u_i}{\partial x_j}$$
(8)

The transport equation for Dissipation rate ϵ ,

$$\rho\left(\bar{u}\frac{\partial\bar{\varepsilon}}{\partial x} + \bar{v}\frac{\partial\bar{\varepsilon}}{\partial y} + \bar{w}\frac{\partial\bar{\varepsilon}}{\partial z}\right) = \frac{\partial}{\partial x_i}\left[\left(\mu + \frac{\mu_T}{Pr_{\varepsilon}}\right)\frac{\partial\bar{\varepsilon}}{\partial x_j}\right] + C_{\varepsilon 1}\frac{\varepsilon}{\bar{k}}\left(2\mu_T S_{ij} - \frac{2}{3}\rho\bar{k}\delta_{ij}\right)\frac{\partial u_i}{\partial x_j} - C_{\varepsilon 2}\rho\frac{\varepsilon^2}{\bar{k}}$$
(9)

Where, C_{μ} , $C_{\varepsilon 1}$, $C_{\varepsilon 2}$, Pr_k are constant. The values used in simulation are 0.09, 1.44, 1.92 and 1.0 respectively. And

water density and viscosity used are 995.325 kg/s and $7.9 \times 10^{-4} Ns/m^2$ respectively. Boundary condition for simulating water flow in bends are listed below,

- 1. At velocity inlet u=w=0;v=0.625 m/s
- 2. At pressure outlet p(gage)=0;
- 3. At wall no-slip condition.

Navier-Stokes equations for viscous, incompressible flow shows mixed elliptic-parabolic behavior. So, semi-implicit method for pressure linked equation (SIMPLE) [7], [12], [13] was used.

The under-relaxation Constant and Spatial Discretization Method are as follows,

Parameter	Under- relaxation	Spatial Discretization Method
Pressure	0.3	Second Order
Momentum	0.7	Second Order Upwind
Turbulent Kinetic Energy	0.8	Second Order Upwind
Turbulent Dissipation Rate	0.8	Second Order Upwind

And the Stopping Criterion for different equation are given below,

Equation	Residual	
continuity	0.0001	
x & y - momentum	0.00001	
z-momentum, kinetic energy, dissipation rate	0.001	

IV. Results

The values of Minor Loss Co-efficient are tabulated for different Pipe Diameter, Bend Radii and Bend Angles. Both data from experiment and simulation are mentioned below.

a) Experimental Results

Table 1: Minor Loss Co-efficient (simulation data) at an inlet velocity of 0.625 m/s

No	Bend RadiD	Pipe Dia.	Rati o	Minor Loss Co-efficient k			icient
110.	(mm)	d (mm)	$\frac{d}{D}$ 30°	30º	60º	120º	180º
1	80	5.2	0.065	7.063	5.935	7.028	8.796
2	80	7.2	0.090	6.859	7.928	7.511	7.640
3	80	8.3	0.104	3.545	3.621	3.719	3.556
4	120	5.2	0.043	6.033	6.061	7.856	7.815
5	120	7.2	0.060	7.918	9.345	8.183	7.065
6	120	8.3	0.069	76.31	0.919	4.034	8.500

b) Simulation Results

Table 2: Minor Loss Co-efficient curve fitted at an inlet velocity of 0.625 m/s

No.	Bend RadiD	Pipe Dia.	Ratio	Minor Loss Co-efficient k			ient
	(mm)	d (mm)	$\frac{n}{D}$	30º	60º	120 ⁰	180 ⁰
1	80	5.2	0.065	7.494	4.568	12.38	20.01
2	80	7.2	0.090	5.221	2.830	6.066	10.68
3	80	8.3	0.104	4.465	2.128	5.240	11.69
4	120	5.2	0.043	1.156	1.696	2.718	3.734
5	120	7.2	0.060	0.773	1.127	1.827	2.532
6	120	8.3	0.069	0.654	0.963	1.531	2.123

V. DISCUSSION

a) Error Analysis

The experimental data has some inevitable errors which affects the result in a little degree. These errors can be classified into two types

- Error in experimental procedure
- Error due to inaccuracy of measuring Devices

The susceptible reasons for the error in experimental data are described briefly below

- (a) The pipes used for the experiment may have variable roughness and cross-sectional area. This may have caused error.
- (b) Basically, the channels to fit the pipes were made by curving the wooden structure and these channels were not smooth enough to ensure precise data readings.
- (c) Traditional Multiple-lever weighting system (bucket platform) was used for measuring water mass. This method has very poor accuracy.
- (d) Priming of manometer was one of the major concerns. As inaccurate priming leads to erroneous pressure drop reading. It is a difficult task. Every time the pipe was changed, manometer had to be primed. It was very time consuming. Even after all the efforts, may be priming was not accurate to its desired level.
- (e) Despite all the effort, experimental setup wasn't leak proof. This introduced additional pressure in the system. And in this type of experimental thesis work

a small pressure variation can induce a large discrepancy from standard value.

- (f) The water flow was controlled by a Gate valve, incorporated with the main water supply line of the laboratory. It is not quite accurate method for flow control. Moreover, while the data was taken from Bend Radius = 120mm, the flow was fluctuating. This induced large error which can be clearly seen from the large difference between experimental and simulation data.
- (g) Pipes were flexible. When bend was formed with them, there cross-sectional area got distorted slightly, from uniform circular section to elliptical section. This also caused variable cross-sectional area in the bend.
- (h) As CCl4 has low density, it showed large deflection due to small pressure variation. In the setup Manometer scale has limited range. This forced to limit the flow rate to narrow range, as manometric deflection increased with flow rate.
- (i) Experiment was done with limited number of pipe, bend radius and bend angle. All the graphs, both experimental and simulation, presented in this paper are best fitted curve, based on quadratic regression.
- (j) For simulation temperature variation is not considered, as it complicated matter immensely with only a little change in result. Besides, during our experimentation temperature remained nearly constant.

b) Graph Analysis

i. Minor Loss Co-efficient Vs. Reynolds Number





Following observation can be made from the above graph between Minor Loss Co-efficient Vs. Reynolds Number for Pipe of 5.2 mm diameter and Bend Radius and angle of 8 cm and 900.

The Minor Loss Co-efficient decreases with increase in Reynolds Number. An inverse relation between Minor Loss Co-efficient and Reynolds Number is observed which is in accordance with Ito's formula for Minor Loss Co-efficient.

$K = constant \times Re^{-0.17}$

At low Reynolds Number (2000-4000) Minor Loss Co-efficient diminished at high rate. But At large Reynolds Number (above 4000) the curve becomes flatter. This is may be due to transition from laminar to turbulent flow.

ii. Minor Loss Co-efficient Vs. Bend Angle

Minor loss coefficient (k) vs. Bend angle Pipe Diameter=5.2mm, Bend radius=8cm 18 2 16 coefficient 14 12 10 loss 8 Minor. k (exp) vs. Bend angle 6 k (sim) vs. Bend angle 160 'n 20 40 60 100 120 140 180 80 Bend angle (Degree)

Figure 4: Minor Loss Co-efficient Vs. Bend Angle

The points that can be noticed are listed below:

The Minor Loss Co-efficient increases with Bend angle, for both experimental and simulation data. These show a power relation between Minor Loss Co-efficient and Bend Angle.

$$(k = constant \times \theta^n)$$

- The experimental data closely matches with the simulation data.
- The differences between simulation and experimental data are due by many errors and limitation in both experiment and simulation which are briefly discussed in Error Analysis.
- iii. Minor Loss Co-efficient Vs. Ratio between Pipe Diameter and Bend Radius



Figure 5: Minor Loss Co-efficient Vs. Ratio between Pipe Diameter and Bend Radius

Discussed below are some observable points,

- The Minor Loss Co-efficient rises until it reaches the maximum (between $\frac{d}{R} = 0.06$ to 0.08) then it diminishes to lower value.
- The experimental data simulation data are similar.
- The Minor Loss Co-efficient has a parabolic relation with the Ratio of Pipe Diameter and Bend Radius.

VI. Conclusion

This section concludes the study of the minor losses in locally available flexible pipes of diam_{eter} 5.2mm, 7.2mm and 8.3mm for bend angle of 300, 600,900,1200,1500,1800 and bend radius 12cm and 8cm.

- Minor loss coefficient in general shows a decreasing trend with respect to Reynolds number for a given angle and pipe diameter.
- For a given Pipe Diameter and Bend Radius increase in bending angle increases Minor loss coefficient.
- For a given Bend angle Minor loss coefficient increases with the ratio of Pipe Diameter and Bend Radius until it reaches a maximum value, then it decreases.

VII. Scope for Future Works

Some guideline for future work is as follows,

1. The thesis work center on the minor losses occurred in locally available flexible pipes. Therefore it will be beneficial to determine total head loss, both minor and frictional loss, developed in a piping system using flexible pipes and finally required power of the piping system.

- The simulation was done using SIMPLE solution 2. method, other solution method can be employed to see whether more accurate results are obtained or not.
- 3. \bar{k} - ε turbulence model is utilized in simulating the flow. Different other model like k-w, Spalart-Allmaras can be used and compared with experimental to find the best model suitable for this specific fluid flow problem.
- Manometric fluid other than Carbon-tetrachloride (CCl₄) should be used, as CCl₄ manometer shows very large deflection due to small change in pressure.
- 5. The traditional Platform-Scale method is an outdated measuring technology. It has been a prime source of experimental error. It should be replaced by more modern measuring device like Turbine Flow Meter etc.
- 6. Further experiment must be conducted on more Pipe Diameter (d), Bend Angle (O) and Bend Radius (R). So that an empirical co-relation between Minor Loss Co-efficient (K) and Reynolds Number (Re), d/R and Θ can be developed. Present study concluded that K has an inverse relation with Re, parabolic relation with d/R and quadratic relation with **O**.
- 7. Further experiment should be conducted to find out the velocity profile. Present study provides with simulated velocity profile.

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Symbol	Meaning	Unit
р	Pressure	(Pa)
V	Velocity	(m/s)
Z	Elevation	(m)
g	Acceleration due to	(m/s²)
d _o	Outside diameter of pipe	(m)
d	Inside diameter of pipe	(m)
t	Time	(sec)
R	Bend radius	(m)
θ	Bend angle	(degree)
γ _m	Specific weight of manometric fluid	(kN/m³)
Т	Temperature	(⁰ C)
H _m	Deflection in manometer	(m)
γ	Specific weight of water	(kN/m ³)
ρ	Density	(kg/m³)
μ	Absolute viscosity	(Ns/m²)
h _{f(total)}	Total head loss	(m)
h _{f(major)}	Major head loss	(m)
h _{f(minor),} h _m	Minor head loss	(m)
Q	Volumetric flow rate	(m ^{3/} s)
Q _m	Mass flow rate	(kg/s)

Nomenclature



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Numerical Investigation of Spring Back on Sheet Metal Bending Process

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Abstract- Spring back is the main defect in sheet metal bending process. The spring back of sheet metal bending, which is defined as elastic recovery of the part during un loading conditions. It should be taken in to considerations so as to produce bent sheet metal parts within acceptable quality. Spring back is affected by the factors such as; sheet thickness, tooling geometry, friction condition; material property and processing parameters. In this research the numerical investigation of Spring back on edge bending die process is done.. The numerical Analysis is done using ANSYS[™] LS-DYNA[™]. The influence of sheet metal thickness, sheet metal type, friction, tool radius and tool shape on spring back for Aluminium, copper, mild steel and High strength steels, sheet metal have been considered for investigations.

Keywords: sprint back, sheet metal, banding process, elastic recovery, numerical investigation.

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NUMERICALINVESTIGATIONOFSPRINGBACKONSHEETMETALBENDINGPROCESS

Strictly as per the compliance and regulations of:



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Numerical Investigation of Spring Back on Sheet Metal Bending Process

Alie Wube Dametew^a & Tafesse Gebresenbet^o

Abstract- Spring back is the main defect in sheet metal bending process. The spring back of sheet metal bending, which is defined as elastic recovery of the part during un loading conditions. It should be taken in to considerations so as to produce bent sheet metal parts within acceptable quality. Spring back is affected by the factors such as; sheet thickness, tooling geometry, friction condition; material property and processing parameters. In this research the numerical investigation of Spring back on edge bending die process is done.. The numerical Analysis is done using ANSYS[™] LS-DYNA[™]. The influence of sheet metal thickness, sheet metal type, friction, tool radius and tool shape on spring back for Aluminium, copper, mild steel and High strength steels, sheet metal have been considered for investigations.

Keywords: sprint back, sheet metal, banding process, elastic recovery, numerical investigation

I. Introduction and Background of the Study

any sheet metal components are produced in different size and accuracy using various sheet metal forming processes. In order to obtain consistent and accurate product dimensions is crucial in manufacturing industry. In sheet metal forming process, a major factor preventing accurate final product dimensions is spring back in the part. Spring back is shape deviation from the design intended geometry which is due to the elastic recovery that occurs after the elastic plastic forming process. Factors that affect the amount of spring back for sheet metal forming process, including both process and material parameters such as; tooling geometry, friction condition; forming speed, die temperature, mechanical properties of materials, sheet metal type and sheet metal thickness. To obtain the desired geometry of the part; spring back prediction and optimizing is a considerable issue in sheet metal bending because tooling design primarily relies on accurate prediction of spring back.

a) Statement of the problem

The Bending process needs repeated experiments to reach the final accurate product. Some sheet metal products are produced still with defects and poor product quality. One of the main accuracy problems is due to elastic spring back effects. In this thesis investigation will be conducted to identify spring back effect of wiping die bending process and analysis will be yield the spring back reduction.

- b) Objectives
- i. General Objectives

The main objective of this study is to investigate the factors influencing spring back formation in sheet metal forming for optimizing the sheet deformation process.

- ii. Specific Objectives
- To investigate factors that influence spring back during wiping die bending.
- To analyze and simulate bending variables using analytical and finite element methods.
- To validate variables obtained from analytical and numerical modeling.
- Predict spring back and.
- To optimize sheet bending operation.
- c) Metrology of the research

The research methodologies adopted in this study to achieve the stated objectives are presented as following: Initially a detailed survey of published literature review was conducted, This study was conducted to study spring back formation in sheet bending and predict factors affecting this phenomenon, using Numerical Analysis is done. A simple 2D and 3D bending process were investigated through numerical simulations for four sheet metal types i.e. aluminum, copper, mild steel and high strength steel, The parameters investigated in this study include; die geometry, sheet metal thickness, sheet metal type and friction condition. For the prediction and analysis of these factors done using Ansys10[™] and LS-DYNA[™]. The analytical results were spring back for further numerical simulation analysis, since it was found that there are a number of issues which requires further study. Comparison of analytical and numerical results was also conducted, and lastly Conclusion and recommendations for a future work was provided.

II. LITERATURE REVIEW

A great deal of research has been conducted in order to reduce spring back, which would optimize the sheet forming process by reducing geometrical and material variables in the formed part. Finite element technique has played a major role in carrying out sheet

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metal forming and spring back analysis in order to gain accurate results. This chapter tries to summarize some key background references and their contributions to the problem of spring back. [Fahd Fathi Ahmed Abdi, 2000] presented the work which was concerned with the spring back experienced by the deformed sheet following the punch release stroke. He used several numerical techniques which enabled to define and determination of spring back.

A 3D hybrid membrane/shell method [Jeong-Whan, 2002] was developed in order to perform spring back analysis from the membrane mid-plane solution and also to reduce computational cost for sheet metal forming simulations. In the hybrid method, the bending strain and stresses were numerically calculated as postprocessing considering incremental shape changes of the sheet obtained from the membrane finite element analysis beforehand. The stress and strain were passed on to a shell model to calculate spring back. With regard to verification purpose, the hybrid method was applied to predict the spring back of a 2036-T4 Aluminum alloy square blank is formed into a cylindrical cup. The spring back prediction was in good situation with the experimentally measured data and also with the results obtained using a shell model to simulate both loading and unloading conditions. For a bending-dominant problem, the method was also applied for the unconstrained cylindrical bending of a 6111-T4 aluminum alloy sheet, which exposes large spring back. According to W.P. Carden (2002) was the Measurement of spring back in Draw-bend have been carried out and analysed to investigate the role of typical process variables on spring back. The investigation leads to conclude that friction in the normal range encountered in sheet metal forming has little effect on spring back, This conclusion departs for fact of friction effect, most likely due to the fact that in many experiments the sheet tension cannot be controlled independently of friction. Ridha Hambli (2003) develops the effects of the die radius on the spring back angle obtained by simulation with and without the influence of damage. It can be observed that with the damage influence the spring back is lower as a consequence of the material parameters variation especially, the Young's modulus and the strain within the fibers. The difference between the curves decreases with increasing die radius. The decrease is attributed to the damage reduction within the sheet for higher die radius values. To estimate and reduce spring back of ax-symmetric part manufactured by Flex forming process was developed by [Hariharasudhan Palaniswamy, 2004] using combined optimization and FEM technique. Finite element simulations were performed in order to study the interrelationship of the blank dimensions and interface conditions on the spring back for an Axisymmetric conical part manufactured by flex forming. Sensitivity analysis are done using the finite element method (FEM)

demonstrated that the magnitude of spring back and the overall dimensional quality are highly influenced by the initial dimensions of the blank. A conventional optimization method combined with FEM was used to obtain optimum blank dimensions that can reduce spring back. Finite element simulations of the forming process were conducted by Taylan Altan (2004) to study the influence of interface conditions on spring back. In the simulations, the Coulomb friction coefficient between the blank and die was varied from $\mu = 0.05$ to 0.15, within constant dimensions. FE results on the influence of friction are shows that a very small increase in spring back with increase in interface friction is observed, it implying that friction has a negligible effect on spring back formed part. They conclude that Interface friction to have negligible effect on spring back for flex forming process of the conical part considered in study.

[Buranathiti and Jian Cao, 2004] develops an effective analytical model to predict spring back for a straight flanging process to effectively predict spring back for a potential application in determining optimal tooling shapes and process parameters, understanding the mechanics of spring back, a mainly elastic recovery process, is essential. Spring back optimization of bending processes was proposed by [Daniel Lapidate, 2005] using the concept of experimental design and response surface methodology .this work described a sheet metal bending process optimization method for spring back minimization by combined finite element analysis, response surface method and gradient Several optimization techniques. work-hardening models were evaluated by [M.C. Oliveira a, 2006] in order to determine their influence on the numerical prediction of the spring back phenomenon. Variation simulation analysis method [Peng Chen b,2007] was developed for the effects of variations in material (mechanical properties) and process (blank holder force and friction) on the spring back were investigated for an open-channel shaped part. [T. Meindersa, I.A. Burchett, 2007] Proposed in the product design of spring back prediction, spring back compensation and optimization by Finite Element (FE) Analysis. The accuracy of the spring back prediction is improved; the FE simulation can be used to adapt the geometry of the forming tools and the process parameters to compensate for spring back.

III. Results and Discussions

This section is developed for the discussion and analysis of the results obtained in the Conducted numerical investigations. The developed model is used prior to implementation by utilizing different analyses to examine the effect of each parameter in the sheet metal bending process. The analysis conducted to examine the effect on the process is using the following ways

- 1. Conducting analysis in the developed numerical and analytical model to analyze and investigate the effect of each parameter.
- 2. Analytical predictions is compared with the previous studies, and then, we discuss the result and the recommendations are done.

a) Numerical predictions of spring back

Finite element analysis of wiping bending process was conducted using two types of element types such as; Plane element 182 and shell element 163. Spring back of sheet should be bent depends on the yield strength of the material. As the materials yield strength increases the spring back after unloading also increase. The spring back will occur where the yield stresses of the material is greater than the stress after unloading condition. If the yield stress is equal the stress after deformation, there is no spring back. For stress- strain diagram the materials beyond yield stress it deforms plastically. The spring back is determined from numerical results using the following formulas *Energy Dissipation Method*

Consider elastic stretching of sheet metal up to a strain of ε . The energy required in this stretching operation can be expressed as

$$W_{\min} = \int_{0}^{\varepsilon min} dW = \int_{0}^{\varepsilon min} F dI = \int_{0}^{\varepsilon min} \sigma x A dI = V \int_{0}^{\varepsilon min} \frac{\sigma mindI}{l} = V \int_{0}^{\varepsilon min} \sigma min * d\varepsilon min)$$

 $\begin{aligned} & \mathbb{W}_{\max} = \int_{0}^{\varepsilon max} dW = \\ & \int_{0}^{\varepsilon max} F dI = \int_{0}^{\varepsilon max} \sigma max A dI = V \int_{0}^{\varepsilon max} \frac{\sigma max dI}{l} = \\ & V \int_{0}^{\varepsilon max} \sigma max * d\varepsilon max \end{aligned}$

W spring back=W max-W min

When the loads are removed from this specimen, this elastic energy will be released again. The *energy dissipation*, i.e., the applied energy per unit of volume of material, hence can be expressed as

 $\begin{array}{ll} Umin = \frac{W}{V} = \int_{0}^{\varepsilon min} \sigma mind\varepsilon min & \text{And} & Umax = \frac{W}{V} = \\ \int_{0}^{\varepsilon max} \sigma max * d\varepsilon max \end{array}$

U spring back=U max-U min

For in the case of elastic deformations only, this energy dissipation can alternatively expressed as

$$U = \int_{0}^{\varepsilon \min} E\varepsilon \min d\varepsilon \min = \frac{1}{2} (E\varepsilon^{2}) \min = \frac{1}{2} (\sigma * \varepsilon) \min$$
$$U = \int_{0}^{\varepsilon \max} E\varepsilon \max d\varepsilon \max = \frac{1}{2} (E\varepsilon^{2}) \max = \frac{1}{2} (\sigma * \varepsilon) \max$$
$$\bigcup_{\text{spring back}} = \bigcup_{\text{max}} \bigcup_{\text{min}}$$

The above formula predict that the amount of spring back in different conditions. The variation between maximum deformation stress and un-loading stress in different region are large the spring back increase. If the maximum and un-loading stress/strain variation is small and close to the maximum deformation stress, the spring back will be reduced. The amount of spring back is equal to the amount of these stress variations. Hence, using these information the amount of spring back are predicted from numerical results in the following way.

i. Effect of sheet metal thickness

$$U = \int_0^{\varepsilon \min} E\varepsilon \min d\varepsilon \min = \frac{1}{2} (E\varepsilon^2) \min = \frac{1}{2} (\sigma * \varepsilon) \min$$

$$U = \int_0^{\varepsilon max} E\varepsilon max d\varepsilon max = \frac{1}{2} (E\varepsilon^2) max = \frac{1}{2} (\sigma * \varepsilon) max$$

U spring back=U max-U min

At 0.8mm of aluminium sheet metal energy dissipation is

$$\bigcup_{\min=\frac{1}{2}} [\sigma minxemin = \frac{1}{2} [-0.699948 * (-0.702)] = 0.24$$

$$\bigcup_{\max=\frac{1}{2}} [\sigma max \varepsilon max = \frac{1}{2} [0.865889 * (0.0327)] = 0.0141$$
$$\bigcup_{\text{spring back}} = \bigcup_{\max} \bigcup_{\min=1}^{\infty} 0.0141 - 0.24 = -0.22$$

✤ At 4.5mm of aluminium sheet metal energy dissipation is

$$\bigcup_{\min=\frac{1}{2}} [\sigma minxemin = \frac{1}{2} [-0.303525 * (0.851 * 10^{-3})] = -0.1291 * 10^{-3}$$

$$\bigcup_{\max=\frac{1}{2}} [\sigma max \varepsilon max = \frac{1}{2} [0.123278 * (0.206)] = 0.01602$$

U spring back=U max-U min=
$$[0.01602 - (-0.1291 * 10^{-3})] = 0.016149$$

From the numerical result the minimum (SMN), and maximum stresses/ strain (SMX), in different coordinate system the results are display. On the result shown Figure 6.6 (a-h) indicates that, with the smaller sheet metal thickness the energy dissipation due to elastic deformation is large. But when increasing of sheet thickness from (0.8 mm to 4.5mm) the energy dissipation due to stress/strain variation is reduced from -0.22 to 0.01615, this implies that maximum energy dissipation is close to the minimum energy dissipation value. When the minimum energy dissipation approach to the maximum value the material is deform plastically. Hence, the spring back is reduced while increasing of sheet metal thickness. Hence, increasing of the thickness from 0.8mm 4.5mm within this range the spring back is reduced 20.35%



a) Nodal solution x-component (0.8 mm thickness)



b) Nodal solution y-component (0.8 mm thickness)



c) Nodal solution z-component (0.8 mm thickness)



d) Nodal solution x - component (4.5 mm thickness)







f) Nodal solution z-component (4.5 mm thickness



g) Elastic Strain and Element solution for Aluminum sheet metal (at 0.8mm)





Fig. 6.6: The effect of sheet metal thickness

- ii. Effect of sheet metal Type
- ✤ At 0.8mm of aluminium sheet metal energy dissipation is

$$U_{\min=\frac{1}{2}}[\sigma minx\varepsilon min = \frac{1}{2}[-0.699948 * (-0.702)] = 0.24$$
$$U_{\max=\frac{1}{2}}[\sigma max\varepsilon max = \frac{1}{2}[0.865889 * (0.0327)] = 0.0141$$
$$U_{\text{spring back}} = U_{\max} - U_{\min=} 0.0141 - 0.24 = -0.22$$

At 0.8mm of high strength steel sheet metal energy dissipation is $\dot{\mathbf{v}}$

> $\bigcup_{\min=2}^{1} [\sigma minxemin = \frac{1}{2} [0.202x10^{-3} * (-0.201x10^{-3})] = -0.0203x10^{-6}$ $\bigcup_{\max=2}^{1} \left[\sigma max\varepsilon max = \frac{1}{2} \left[0.433x10^7 * (0.004196)\right] = 0.908x10^4$ $U_{\text{spring back}} = U_{\text{max}} - U_{\text{min}} = 0.908 \times 10^4 - (-0.0203 \times 10^{-6}) = 0.91$

The numerical results of Aluminium, copper, mild steel and high strength steel sheet metal figure.6.6.and figure .6.7 (a-d) shows that for constant sheet metal thickness (0.8mm), the energy dissipation variation is range from -0.22 to 0.91 .Result clearly show that increasing the sheet metal strength (Aluminium to High strength steel) the variation increases. High strength steel needs a considerable higher amount of maximum punch load than the aluminium sheet metal. As we know increasing of sheet metal ultimate strength the punch load is increase. Due to this higher strength, the material is not easily deformed plastically. As a result, the material returns to the original shape and spring back occurs. Hence, the spring back increases from Aluminium to High strength sheet metal.



a) Element solution for Aluminum sheet metal (at 0.8mm)







C) Element solution for High strength steel sheet metal (at 0.8mm)





Fig. 6.7: The effect of sheet metal Type

b) The effect of Tool geometry

i. Tool radius (Rp)

The analysis is to examine the effect of varying the punch radius on spring back. For this purpose the punch is having a different radius Rp, = 10mm, 16mm and 23mm are utilized. The spring back results obtained from numerical analysis in figure6.8 (a-c) shows that Smaller values of the punch radius (Rp=10mm), for the same blank thickness result in smaller spring back values in the deformed sheet metal. From the figure clearly indicates that for reducing of tool radius from23 mm to 10mm the spring back is reduced.



a) Element solution for punch radius (Rp) =10mm







c) Element solution for punch radius (Rp) =23mm

Fig. 6.8: The effect of tool radius (Rp)

ii. Effect of Tool Shape

In the case of edge bending die observed in fig 6.8 variation of the result range from -0.25to 0.0739 and in the case of differential die the variation ranges from 0.16 to 0.23 .these result shows that in the case deferential die the result close to the maximum value. The reason is in deferential die the pressure is applied in different cross sections of the blank. Due to this the material is deformed plastically. Hence, tool Shape is a significant factor for spring back formation and spring back is highly reduced in the case of differential die bending.



a) Element solution x -component (with 0.8mm thickness AI sheet metal)



b) Element solution y-component (with 0.8mm thickness AI sheet metal)

Fig. 6.9: The effect of tool shape

- iii. The effect of friction
- ✤ At 0.01 friction coefficient the energy dissipation is

$$\bigcup_{\min=\frac{1}{2}} [\sigma minx \varepsilon min = \frac{1}{2} [61211 * (0.181x10^{-8})] = 0.26$$
$$\bigcup_{\max=\frac{1}{2}} [\sigma max \varepsilon max = \frac{1}{2} [0.433x10^7 * (0.311x10^{-6})] = 0.67$$
$$\bigcup_{\text{spring back}} = \bigcup_{\max} \bigcup_{\min=0.67} 0.67 - 0.26 = 0.19$$

At 0.50 friction coefficient the energy dissipation is

$$U_{\min=\frac{1}{2}}[\sigma max \varepsilon max = \frac{1}{2}[-0.433x10^7 * (-0.122x10^{-6})] = 0.524$$
$$U_{\max=\frac{1}{2}}[\sigma max \varepsilon max = \frac{1}{2}[-821.995 * (0.122x10^{-6})] = -0.05x10^{-3}$$
$$U_{\text{spring back}} = U_{\max} - U_{\min=} -0.05x10^{-3} - (0.524) = -0.5205$$

Numerical result conducts that, the coefficient friction varies from $\mu = 0.01$ to 0.50, with constant dimension and the same sheet metal type. The result increases from 0.19 to 0.52 these needs for maximum bending force. During increasing of the bending force the material will be deformed plastically. But this higher amount force is removing from the material it is highly returned to the original position. Due to this fact the spring back is increased by increasing of friction coefficient for certain limit.



a) Element solution y-component (at $\mu = 0.01$)



b) Element solution y-component (at $\mu = 0.05$)



c) Element solution y-component (at μ =0.15)



d) Element solution y-component (at $\mu = 0.50$)



e) Stress and Nodal solution y-component (at $\mu = 0.01$)



f) Stress and Nodal solution y-component (at $\mu = 0.5$)

Fig. 6.10: The effect of friction

IV. Implicit Results

The implicit numerical results have the same effect with explicit result but the difference is the amount of values for the parameters.

a) The effect of sheet metal thickness

The implicit result shows in Figure 6.11 with the smaller sheet metal thickness the stress and strain

variation are large. But when increasing of sheet thickness from (0.8 mm to 4.5mm) the stress variation is reduced from 2.12 to - 0.0154. This implies that increasing of the thickness from 0.8mm 4.5mm the spring back is reduced.



a) Mean strain at (0.8mm thickness)







b) Material type

The effect of sheet metal type shows that in figure 6.12 for constant sheet metal thickness, the stress variation is range from - 0.0154 to 0.212. The results clearly show that increasing the sheet metal strength (Aluminium to High strength steel sheet metal) the variation increases. This is due to the yield stress of the sheet metals that is spring back of sheet should be

bent, depends on the yield strength of the material. As the materials yield strength increases the spring back after unloading also increases. The spring back will occur where the yield stresses of the material is grater than the stress after Un-loading condition. If the yield stress is equal the stress after deformation, there is no spring back .hence the spring back increases from Aluminium to High strength sheet metal.



a) Mean strain (Aluminum sheet metal)



b) Mean strain (High strength steel sheet metal) *Fig. 6.12:* the effect of thickness

c) The effect of angle

Fig 6.13 shows that the bending angle increases the variation will be reduced, when the

variation of spring back angle decrease the spring back also decrees.





Fig. 6.13: Effect of bending angle

d) The Effect of tool Radius

The numerical results shows in figure 6.14, For Small punch radius the numerical result have smaller spring back values in the deformed sheet metal. From this result predicts that for increasing of tool radius from 21 to 47 mm the spring back is increase from 0.01 to 1.2.



a)





Fig. 6.14: The effect of tool radius

V. VALIDATION OF THE MODE

Under this topic Analytical predictions are compared with the previous studies. In the second method, we compare the Analytical investigations with the finite element predictions. It is an effective result in comparing for the validation of the attained results.

a) Comparison of our investigation with the previous studies

The Stepped Binder Force Trajectory and Neural Network Control proposed by Jian Cao and Brad Kinsey in order to predict and control spring back in forming process. Regarding the sheet thickness and binder force as possibly the most significant process parameter, the robustness of their control system was tested against variations in the friction coefficient, and excellent results were obtained. However, the effect of material type in the material properties and sheet thickness were not investigated in their work. Therefore, further closed-loop control simulations with these variations were conducted here in order to form a comparison with the neural network control system. The spring back angle values from these neural network control system have wider difference comparing to our result. The resulting spring back angle from the process was calculated within a range of 0.29° to 1.8°. For sheet metal thickness range from 0.8-4.5mm.but in the case of our result within the same thickness range the spring back angle values are 019-0.03. This indicates that the spring back angle of our analysis was considerably less and closer to the original angle. Though the method we have to use and developed are required producing accurate and sufficient results for predicting and controlling of spring back comparing with natural network control method. Recep Kazan (2008) was also conducted to predict spring back in wipe-bending process of sheet metal using artificial neural network (ANN). Here, several parameters were considered to predict spring back. The important parameters they considered for the analysis were sheet thickness and tooling geometry are used. In order to investigate the effect of die radius and blank thickness on the spring back angle of flanging process, models were done with the sheet metal thickness are taken as 0.7mm to 5.0mm and die radius also 0.7 to 5.0mm should considered. However the results with variations in sheet thickness (0.8-4.5mm) spring back angle by artificial neural network were investigated 1.763°. -1.24°.

For constant thickness with different sheet metal type the Variations of radius was investigated 1.2764.-1.89 but in our result the spring back is predicted with 0.08-0.49°.and 0.557-1.333 angle and tool radius respectively. From these analysis our parameter selection and prediction method (analytical and FEM) is better for prediction of spring back and optimization of bending process.

VI. CONCLUSIONS AND RECOMMENDATION

a) Conclusion

In this research work a detailed study of the parameters that influencing on spring back was conducted. The conducted literature review revealed that, although similar studies were conducted in the previous developed models were unable to consider simultaneously all the parameters influencing spring back formation. Accordingly this work is an attempt to study spring back by including more parameters at a time in order to study spring back and predict the amount of spring back in sheet deformation process, thereby optimizing the sheet bending process. However a numerical investigation of spring back is conducted using ANSYS™ LS-DYNA™. The developed implicit and explicit numerical models are used for prediction of spring back formation by varying parameters such as: sheet metal material and thickness, coefficient of friction between the die and the material, and tool radius and tool shape .

The results were compared with the previous study results and, the following conclusions were drawn from this study;

The result shows that increasing sheet metal thickness from 0.8mm to 4.5 mm the spring back is reduced by 20.35 %.

- When increasing of sheet metal strength spring back increases however, in these cases more maximum required punch loads are needed. Aluminium exhibits lower spring back than mild steel and high strength sheet metals. Using Aluminium sheet metal instead of High strength sheet metals spring back is reduced by 56. %
- For decreasing of the tool radius leads to spring back is reduced.
- Modifying tool shape also changes spring back. i.e. using deferential die instead of edge bending die the spring back is reduced by 12 %
- Increasing of friction coefficient from 0.01 to 0.50 the spring back is increase by 52%.
- Hence, an optimum value of sheet metal thickness, material type and tool radius should be chosen for reducing of spring back. Finally utilizing and compensation of tool geometry is considered for optimizing of bending process, when the spring back is reduced, this is also helps to obtain quality sheet metal product manufacturing.
- b) Recommendation and future works

Some of the suggestions for further investigations are:

- To verify the spring back prediction through an experiments
- To compensate of spring back in the die design using FE simulations
- Development of spring back prediction is conducted in warm and cold sheet metal conditions are also considered.

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Performance of Composite Structures Subjected to High Velocity Impact – Review

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Abstract- In recent years, breakthrough in the development of modelling techniques and impact analysis of composite materials subjected to high velocity has been made. The study methodically reviews the modelling techniques for the structural response of composite materials under high velocity. Although, report gives numerical model as widely used method, yet experimental test is always required to validate both analytical and finite element designs. The assessment shows that all modelling methods are suitable for application based on loading conditions of the composite structure. Lastly, the reference list provides databank for future researchers and engineers on composite structure subjected to high velocity impact.

Keywords: analytical approach, experimental method, finite element simulation, high velocity impact, composite materials.

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Performance of Composite Structures Subjected to High Velocity Impact – Review

Enock A. Duodu^a, Jinan Gu^o, Wei Ding^o & Shixi Tang^o

Abstract- In recent years, breakthrough in the development of modelling techniques and impact analysis of composite materials subjected to high velocity has been made. The study methodically reviews the modelling techniques for the structural response of composite materials under high velocity. Although, report gives numerical model as widely used method, yet experimental test is always required to validate both analytical and finite element designs. The assessment shows that all modelling methods are suitable for application based on loading conditions of the composite structure. Lastly, the reference list provides databank for future researchers and engineers on composite structure subjected to high velocity impact.

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I. INTRODUCTION

arbon fibre-reinforced composites are known for their high weight-specific stiffness and strength properties, which make them a preferred alternative in the material selection for modern lightweight structures in aeronautic and automotive engineering. However, these materials are susceptibility against impact loads. Internal damage formed in composite laminates spreads beyond the impacted area, and significantly reduces the strength and stiffness of the composite [1]. Composite materials response to impact loading and also the dissipation of the incident kinetic energy of the projectile is different when compared to metals. In traditional materials energy is absorb through elastic and plastic deformation which result in permanent structural deformation [2]. However, the capability of the composites to undergo plastic deformation is extremely limited as the resultant energy is frequently absorbed to create large zones for fracture with resultant reductions in both strength and stiffness [3].

Composite materials are extensively used in industrial applications such as aerospace, marine, locomotive and civil engineering structures due to their superior material properties. However, these materials tend to involve many microscopic damages including stiffness reduction due to impact which often leads to catastrophic failure. Currently, the extent of fiberreinforced composites applied in aircraft structures has become one of the most important targets making the

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advancement of modern structural design. Nevertheless the applications in aerospace industry, composites are increasingly used in other industries such as civil, sporting equipment, medical fields, automotive, railways and in marine vessels specifically for masts, hulls, desks and propellers. Unlike traditional materials, composites offer an endless array of design variations with flexibility accompanied by complications in modelling and analysis. This performance attracted transportation industries to develop structures replacing metallic material with the lighter structures. However, composite structures are poor to impact resistance owing to cyclic loading conditions, which results in inelastic behavior and poor damage resistance. Composite structures can develop local failures or exhibit local damage such as matrix cracks, fiber breakage, fiber-matrix debonds, and delaminations under normal operating conditions which may contribute to their failure.

High velocity impact is defined as local wave dominated response independent of boundary conditions ranging above 10 m/s, and characterized as dynamic events [4] with high speed and small mass. High velocity impact produces a short duration, steeply rising loading pulse when impacting the structure. It is dominated by inertial forces, wave propagation and changes in material stiffness, strength and fracture energy due to a high strain rate [5]. There are many parameters which influence the response of composite materials under high velocity impact, and these include: type, architectures and volume fraction of the reinforcement, laminate thickness, matrix system, projectile geometry and mass [6]. At high incident impact energies, target perforation may occur and the passage of the impactor naturally results in petalling, cracking and spalling. Although such damage reduce the load-bearing ability of the structure, its effects can generally be predicted using fracture mechanics principles [7].

In a high velocity impact, the response of the structural element is governed by the local behaviour of the material in the neighbourhood of the impacted zone; the impact response of the element being generally independent of its support conditions; and in most cases, impact test is carried out experimentally using a single stage gas gun. In recent years, researchers [8-10] have used sensors and transducers, however, residual velocity is difficult to measure as a result of shear plugs while other researchers have adopted a high-speed

video cameras [11] due to its consistency and precision. As a result of focus on the impact response, it is important to understand the material's behaviour and the mode of assessment when subjected to impulsive loading.

Nowadays, composites are believed to have superior potential applications as the primary loadbearing structure in many industries, thus, studies on impact behaviour of carbon fibre composite have attracted much attention and become a hot research interest in the discipline of composite materials. This work is a bit of that endurance to establish numerical models capable for structural optimization in diverse engineering applications especially aeronautics and astronautics design. Therefore, the main objective of this paper is to review recent models used to analyze impact response of composite materials subjected to high velocity. Depending on the nature of the structure and the impact threshold, numerous studies have adopted analytical, experimental and numerical methods to analyze the structural behavior. On like metals, composite materials are anisotropic or orthotropic in nature and their mechanical behaviors under impact are complicated to predict, and therefore presents distinctive and demanding task for researchers and engineers to study in order to predict the impact response during static and dynamic loading conditions for safe used. This work endeavor is part of that endurance and aims to review the methodologies capable to predict structural performance in diverse engineering applications.

II. METHODS OF ANALYSIS

a) Experimental technique

Lahuerta et al. [12] used an experimental technique to measure the delamination length in mode *I* tests based on video image processing. A nondimensional formulation of an analytical model proposed in a previous work of García Castillo et al. [13] was redeveloped by [14] based on energy criteria to study the ballistic behaviour of composite plates made from woven laminates of E-glass fibers. This model allows for estimation of the residual velocity of the projectile, the ballistic limit, the energy absorbed by different mechanisms during the penetration of the laminate, and the contact time between the projectile and the laminate. Good agreement was found for residual velocities, contact time and ballistic limit for two geometry ratios.

Hosur et al. [15] conducted experimental study on response of stitched/unstitched woven fabriccarbon/epoxy composite laminates subjected to high velocity impact loading. The ensuing damage is characterized through ultrasonic NDE. Result of the study indicates that the damage is well contained within

Garcia-Castillo et al. [16] examined the damage preloaded glass/vinylester composite panels in subjected to high-velocity impacts. In their study, three representative structural cases (no, uniaxial and biaxial loadings) was analyzed. The result shows that the damage area was localized in the center of the panel; and gualitatively the damage area was largest on the non-loaded laminate of impact velocity of 136 m/s followed by 130m/s velocity uniaxial loading with the least being the 98m/s impact loading of the biaxial laminate. The study reveals that the impact energy and damage area was greater in the non-preload laminates than in the uniaxial and biaxial preloaded laminates. This difference occurs due to the increment of effective stiffness in panels subjected to membrane loads, which decreases the displacement of the panels, and accordingly reduces the damage area. This phenomenon is more significant at the perforationthreshold energy, where the bending of the panels is the greatest. High velocity impact response of sandwich structure composite laminated plates, Kevlar-29/epoxy and 60 61-T6 aluminium was experimentally investigated by [17] using a nitrogen aas aun. Adopting the same approach, high velocity projectile impact through different thickness of polyurea AA5083-H116 aluminium alloy plates was coated assessed by [18].

Jabbar et al. [19] presented experimental study to compare the mechanical and ballistic performance of composites reinforced with single-layer and double-layer inter-locked woven fabrics low and high velocity impacts. The energy absorption and mechanical failure behavior of composites during the impact event were found to be strongly affected by the weave design of the reinforcement. The composites reinforced with doublelayer interlocked woven fabrics were found to perform better than those comprising single-layer fabrics in terms of impact energy absorption and mechanical failure. Similarly, Sultan [3] prescribed a study to examine the effect of thickness on fiber glass reinforced epoxy matrix subjected to high velocity impact loading. Their results show that the mechanical properties, damage characterization and impact resistance of g/m² possess better type C-glass/Epoxy 600 toughness, modulus and penetration compared to type C-glass/Epoxy 200 g/m². Moreover, as the plate thickness increases, the maximum impact load and impact energy increases relatively. The result clearly reveals that impact damage was in the form of perforation, fiber breakage and matrix cracking.

Sabet et al. [20] presented experimental study on high velocity impact performance of glass reinforced polvester (GRP) resin composite plates with different type of reinforcement between the velocity range of 80 to 160 m/s. Result shows higher ballistic limit velocity (velocity at which samples fully penetrated the target plates with zero residual velocity) for 3 mm GRP plates with cross-ply unidirectional reinforcement followed by unidirectional reinforcement and plain weave, the plates with satin weave and chopped strand mat (CSM) reinforcements were almost in same level. The report added that thicker specimens (6 mm), plates with plain weave reinforcement showed better ballistic performance towards sharp tipped conical projectile impact, followed by cross-ply unidirectional, satin weave, unidirectional and CSM reinforced plates. Experimentally, the study reveals that the ballistic limit velocity for all specimens correlate well with estimated ballistic limit values obtained in full perforation tests. Findik et al. [21, 22] have investigated experimental study on impact performance of some polymer-based composites and observed the contact mechanism as well as dynamic response of composite laminates. Pol et al. [23] performed experimental study on the influence of nano-clay Closite 30B on ballistic impact behavior of 2D woven E-glass/epoxy laminated composites.

The standard material characterization under compression and fracture modes was assessed by [24] under experimental study of high velocity impact fracture of ice. The failure of fiber reinforced thermoplastic composites (polypropylene made of hybrid E-glass/PP yarns) was investigated under medium and high velocity impact loading conditions by electromagnetic and acoustic emission signal measurements [25].

Hazell et al. [26] presented experimental study on the response of a bonded carbon–fiber-reinforced plastic composite panel to impact, penetration, and perforation by a high-velocity steel sphere. Hou et al. [27] identified and discussed the ballistic performance, quasi-static and impact perforation of metallic sandwich structures with aluminum foam and studied the effects of several key parameters as impact velocity, skin thickness, thickness, density of foam core, and projectile shapes on the ballistic limit and energy absorption of the panels during perforation of impact loading.

To elucidate the penetration and failure mechanisms, an experimental test using the JH-1 ceramic model of the projectile penetrating into a silicon carbide-faced polycarbonate is implemented in the hydro-code Autodyn-2D [28]. Übeyli et al. [29] have experimentally studied the ballistic behavior of laminated composite having alumina front and dual phase steel backing layers using 7.62 mm armor piercing (AP) projectiles under normal impact. The results showed that utilization of a 6 mm thick alumina front layer which

is bonded to dual phase steel enhanced the ballistic resistance of the dual phase steel remarkably.

A study of the high velocity impact response of thick composite plates under tensile preload using a glass sphere projectile and an impact velocity is presented in [30], where less delaminations compared to the unloaded case are obtained under tensile preloads. Ballistic impact tests on thick woven Eglass/vinyl ester plates with compressive preload and variable velocities are performed by [31]. The authors report a detrimental effect on the residual strength of the composite plate.

b) Analytical study

Talib et al. [32] formulated analytical model to predict the performance of hybrid composite made of woven fiber Kevlar-29 and Al₂O₃ powder/epoxy subjected to high velocity impact. The relationship between the ballistic limit with the thickness and energy absorption with thickness for Kevlar-29 fiber and Al₂O₃ powder-reinforced composite materials was established. It was found that the proposed equation is suitable for this type of composite materials after comparing the behavior of the theoretical analyses with the experimental work. The experimental results showed good agreement compared with the theoretical work. The results indicate that the improvements in the performance target for bullet-proof applications are achieved.

Extensive parametric studies were carried-out on woven fabric thick composites and the energy absorption to predict the ballistic impact behavior of thick composites [33, 34]. Also, a normal impact and perforation of conically-tipped hard steel cylinders was done on laminated Kevlar-29/polyester targets and pneumatic and powder guns, with a 12.7 mm barrel diameter are used for dynamic testing where ballistic limits, terminal velocities and perforation are determined on target plates [35, 36].

An analytical formulation by Sheikh et al. [37] to predict the residual velocity of cylindrical projectiles under high velocity impacts on carbon epoxy laminates is investigated. Similarly, Udatha et al. [38] proposed analytical model to predict the performance of 3D woven composites under high velocity impact. For comparison, studies are also presented on the performance of twodimensional plain weave E-glass/epoxy composites. A good match is observed between the analytical predictions and experimentally obtained limit velocities for complete penetration. It is observed that limit velocity for complete penetration for three-dimensional woven composite is higher than that of two-dimensional plain weave composite.

Mishra et al. [39] formulated mathematical model based on theory of single yarn impact and implemented in MATLAB code to calculate the energy absorption and strain induced in the Kevlar and leather layers composites under high velocity impact. Results of the study shows that the stored energy increases and strain decreases with increase in impact time due to initially high kinetic energy utilizing of impactor for deformation than the absorbed in layers. As the impact time increases, tendency of deformation reduces and energy absorption improves. Again, the strain energy is high at the time of impact inception, due to kinetic energy of impactor is more than the energy absorbing capacity of layers which results in maximum damage of the layers; and the cone area developed in the Kevlar layer is more in comparison to leather layer has absorb more energy than leather layers. The study concludes that outcome of the results may be used as preliminary design tool for an assembly of rigid and semi-rigid materials in an armor system to reduce the experimental cost and time.

Ravi kumar et al. [40] presented analytical method to predict the compressive strength at high strain rate of 5000 s⁻¹ loading of a typical woven fabric E-glass/epoxy composite L2R. The result is compared with the experimental tests using compressive split Hopkinson pressure bar apparatus, which observed that the compressive strength is enhanced at high strain rate loading compared with that at quasi-static loading.

Pernas-Sánchez et al. [41] proposed a simplified analytical model of carbon/epoxy tape quasiisotropic laminates to assess the different energy absorption mechanisms and predict the residual velocity of the projectile subjected to high velocity impacts. The model is validated by experimental test using destructive and non-destructive techniques.

Hossein et al. [42] studied the variation of the ballistic limit with areal density in a woven fabric made from Kevlar fibers. The model allows variation of spacing between laminas in order to study their effect on the ballistic limit. Again, the models based on energyconservation laws consider that the kinetic energy of the projectile at impact should be consumed during the perforation process by the elastic deformation of the panel, by the failure process of the laminate (which includes several mechanisms), by friction and heating of the laminate, and by accelerating the panel after impact [14].

Garc'ia-Castillo redeveloped an energy model based on the proposals of Naik, et al. [43] to study laminate plates subjected to ballistic impact with and without in-plane preloads [44, 45]. The authors' model assumes that the plate absorbs the energy by three mechanisms: the elastic deformation of the fibers, the acceleration of the plate, and the generation of damage in the laminate. This damage may be due to the failure of fibers, delamination, and matrix cracking. This model is later used in a non-dimensional formulation to analyze the influence of several ratios in the ballistic behavior of thin laminates [46].

Fatt et al. [47] presented analytical solution to predict the residual velocity of a hemispherical-nose cylindrical projectile impacted on a composite sandwich panel at high velocity range of 75-325m/s. The analytical approach was mechanistic without any detailed account of progressive damage due to delamination and debonding but changes in the load-bearing resistance of the sandwich panel due to failure and complete loss of resistance from the face sheets and core during projectile penetration. The study indicated that the predicted transient deflection and velocity of the projectile and sandwich panel compared fairly well with results from finite element analysis. Again, analytical predictions of the projectile residual velocities were found to be in good agreement with experimental data found in literature.

Using an existing model [48], Feli and Pour [49] presented a new analytical model for perforation process of composite sandwich panels with honeycomb core subjected to high-velocity impact of cylindrical projectile. The redefined model is validated by comparing with [48] experimental tests and numerical model. A good agreement between the residual velocity of projectile in the new analytical model and experiment tests was established.

Mamivand et al. [50] developed analytical technique for the ballistic behaviour of 2-dimensional (2D) woven fabric composites. Similarly, Feli and Asgari [51] have presented analytical approach for perforation of ceramic/multi-layer woven fabric targets by blunt projectiles. This model was used to model back-up woven-fabric material and deformation of yarns during perforation where the kinetic and strain energy of yarns ware determined. Feli et al. [52] developed analytical model and FE simulation based on FE code in LS-DYNA for normal penetration of cylindrical projectiles onto the ceramic-composite targets. Liaghat et al. [53] presented analytical technique to determine the ballistic limit velocity of metallic honeycombs impacted by cylindrical projectiles. This method is based on the assumption that the total kinetic energy of the projectile is dissipated in folding and crushing of honeycomb, tearing of cell walls, forming and shearing of the plug.

López-Puente et al. [54] formulated analytical application to predict residual velocity after the impact onto a thin carbon/epoxy woven laminate. Their model considers three different energy absorption mechanisms for the laminate. The study used experimental impact test to validate the model and the results clearly shows a very good correlation between the results obtained from both experimental and numerical simulations in literature.

A non-dimensional formulation of an analytical model proposed in a previous work of García Castillo et al. [13] was redeveloped by [14] based on energy criteria to study the ballistic behaviour of composite plates made from woven laminates of E-glass fibers. This model allows for estimation of the residual velocity of the projectile, the ballistic limit, the energy absorbed by different mechanisms during the penetration of the laminate, and the contact time between the projectile and the laminate. Good agreement was found for residual velocities, contact time and ballistic limit for two geometry ratios.

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c) Finite element method

A numerical model with appropriate erosion criteria for impact analysis of hybrid-fiber engineered cementitious composites (ECC) panels using LS-DYNA commercial software under high velocity is investigated by [55]. The study shows that the tensile stress-strain relationship of the developed numerical model compared with the experimental test in reference [56] is in good agreement.

Prakash et al. [57] developed FE model to study the influence of adhesive thickness on high velocity impact (HVI) performance of ceramic $(Al_2O_3^{-1})$

99.5)/aluminum (Al5083 H116) composite laminate through a detailed numerical investigation using the AUTODYN software platform. The result of the study discloses that interface layer plays a significant role in the impact performance. The result is validated by experimental analysis for optimum designs of the target plates. Park et al. [58] performed numerical analysis using the commercial software tool LS-DYNA on high velocity impact of shear thickening fluids (STF) impregnated Kevlar fabric. The simulation results are in good agreement with empirical data obtained. The empirical and numerical study on the energy absorption characteristics of neat Kevlar and STF impregnated Kevlar fabrics suggest a positive effect by the STF impregnation on the energy absorption.

Pernas-Sánchez et al. [59] developed finite element model to predict the behavior of composite unidirectional laminates under high velocity impact. The numerical model is validated by C-Scan images which exhibit very good correlation with reference to penetration and the damaged area. Wang et al. [60] conducted FE analysis on CFRP laminates subjected to high velocity impact. The predicted numerical results are validated by experimental measurement; and the study shows that thin CFRP laminates have higher energy absorbing efficiency (EAE) under higher velocity (energy) while thick CFRP laminates have higher EAE under lower velocity (energy) impact. The energy absorbing efficiency comparison shows that impact velocity range of EAE-CFRP laminates is higher than that of stainless-steel. Therefore, CFRP laminates are seen as a potential advantage to substitute the metal plates in higher velocity impact resistance structures.

Ivañez et al. [61] formulated a user material VUMAT subroutine and implemented into ABAQUS/Explicit finite element platform to predict the high-velocity impact response of sandwich plates. The accuracy of the finite-element model is determined by comparing experimental data with numerical predictions in terms of ballistic limit and residual velocity. Satisfactory agreement with the experimental results was established. The comparison of the damaged area in sandwich and spaced plates revealed that the suppression of the foam core in the sandwich structure affects the size of the damaged area. Buitrago et al. [48] formulated а model and implemented into ABAQUS/Explicit through user-written VUMAT subroutines finite element to predict the behaviour of sandwich panels made of carbon/epoxy laminate skins with aluminum honeycomb core under high-velocity impacts. The model is validated with experimental tests by comparing numerical and experimental residual velocity, ballistic limit and contact time.

Heimbs et al. [62] have carried out an experimental and numerical study of the influence of tensile and compressive preloading impact on the performance of carbon/epoxy plates at high velocity.

Ultrasonic C-scans and micrographs are used for the post-test damage inspection, where matrix cracking and delaminations are observed as the major impact damage modes. Tensile preloading is found to reduce the extent of delaminations, while compressive preload increased the extent of delaminations resulting from a higher bending deflection of the impact plate. The study shows that preloading has an influence on the impact response of laminated composite plates and is relevant in the structural design analyses.

Silva et al. [63] presented experimental and numerical application to predict the ballistic impact on composite laminated plates reinforced with Kevlar-29/Vinylester. The analysis is performed using a commercial code based on finite difference hydrocode AUTODYN and values obtained are compared with the experimental data to evaluate the performance of the simulation. Good correlation between numerical simulation and experimental results is achieved for deformation and damage of the laminates. Tham et al. [64] conducted a combined experimental and 3D dynamic nonlinear finite element (FE) approach to study damage in composite beams subject to ballistic impact. The influence of tensile and compressive preloads on the soft body impact behaviour of composite laminates has been studied experimentally and numerically in [65], where the researchers used gelatine projectile as a substitute material.

Bürger et al. [66] formulated a model based on Lagrangian and implemented into an explicit solver in the commercial FEA software ABAQUS/Explicit to simulate the ballistic impact of an armor-piercing projectile in hybrid ceramic/fiber reinforced composite armor. The ballistic limit prediction velocity shows that global damage and residual velocity are very accurate when experimentally compared. Sastry et al. [67] developed numerical model and implemented into the commercial software ABAQUS/Explicit to study the effect of ballistic impact on the composite plate madeup of woven fabric CFRP, the E-glass/epoxy and the Kevlar/epoxy for different ply stacking sequences. The result indicates that the Kevlar/epoxy absorbs a maximum kinetic energy of energy compared to the other the two materials. The numerical simulation provides quick estimation with good accuracy and reliability as compared to experimental results.

Sevkat et al. [68] presented a combined experimental and numerical approach to study the ballistic impact response of S2-glass fiber toughened epoxy composite beams using a high speed gas gun. Again, a hybrid particle finite element algorithm for high velocity impact based on the Generalized Particle Algorithm (GPA) is formulated [69-71] and compared to the other computation algorithm.

Mohotti et al. [72] formulated a bird strike-like projectile simulation using explicit finite element code in LS-DYNA to investigate the behaviour of multi-layered composite plate coated with polyurea and aluminium alloys under high velocity impact. The study shows that the application of polyurea coatings resulted in a higher residual velocity reduction per unit areal density than aluminium alloys. This indicates the feasibility of polyurea to be utilised in layered composite armour systems in mitigating ballistic threats.

Kumar et al. [73] have numerically study the effect of impactor and laminate parameters on the impact response and impact-induced damages in graphite/epoxy laminated cylindrical shells using 3D finite element formulation. The numerical results compared with experimental data showed good correlation. Zhao and Cho [74] investigated the impactinduced damage initiation and propagation in the laminated composite shell under low-velocity impact. The study employed a three dimensional eight-node non-conforming element with Taylor's modification scheme to analysis the interlaminar stress distribution and damage propagation.

Ghosh and Sinha [75] developed a finite element model to predict the initiation and propagation of damage laminated composite plates under forced vibration and impact loads. Tarfaoui et al. [76] presented a FEA of static and dynamic tests on thick filament wound glass/epoxy tubes. The material characteristics of the models are validated to predict the static and dynamic elastic behavior. Kim et al. [77] have numerically proposed a damage model based on continuum damage mechanics for the progressive damage analysis of a composite structure. The damage model is implemented in the user material subroutine of the ABAQUS/Explicit program. The impact response and damage from the numerical analysis are comparable with results obtained through experimental test.

III. CONCLUDING REMARKS

This paper reviews the modelling techniques to analysis the impact response of composite structures subjected to high velocity. Three approaches; experimental, analytical and numerical methods were successfully employed to predict the impact behaviour. The report shows that numerous researchers assessed the impact behaviour of composite edifice through experimental method due to the simplification of use and does not need detail parameter on actual damage mechanisms. But, this method is costly and difficult to extend towards more general loading conditions, where multi-axial stress conditions are imposed. Finite element simulations have been applied to structural analysis under high velocity impact loadings for accurate estimation of results under both static and dynamic conditions. On the other hand, computational cost is very high, which requires high performance computers to model complex impact events. Again, numerous

researchers and engineers have applied analytical models due to low computational cost and time, and capable to define the physical behaviour of the composite materials. Noticeably, analytical formulations are only applicable to simple models. The report shows that all methods for analysis are suitable for application based on loading conditions of the composite material. Nonetheless, numerical simulation offers the most detailed information on the spatial and temporal distribution of damage during impact which is more flexible and powerful alternative and widely used compare to analytical formulations and experimental tests.

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Characterization and Simplified Modeling of the Failure Behavior of Spot Welds from Extra-High Strength Steels for Crash Simulation

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Keywords: finite element; spot weld; weld characterization; EHSS steel; T section specimen; B-PILLAR component IIHS testing.

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Characterization and Simplified Modeling of the Failure Behavior of Spot Welds from Extra-High Strength Steels for Crash Simulation

Sachin Patil^a & Hamid Lankarani^o

Abstract- Vehicle collision characteristics significantly influenced by spot welded joints in vehicle steel body components. In engineering practice, spot welds are normally not modeled in detail, but as connection elements which transfer forces and moments. Therefore a proper methodology for the development detailed weld model to study structural response of the weld when the applied load range is beyond the yield strength discussed in this paper. Three-dimensional finite element (FE) models of spot welded joints are developed using LS-Dyna. Simple spot weld models are developed based on the detailed model behavior developed earlier. In order to generate testing data, virtual tensile testing simulations are carried out with mesh sensitivity in the necking zone. This high mesh resolution around necking zone is required to capture the steep gradients in the pressure and stress tri-axility, etc. Once the stress strain curve are generated in the simulations examined damage function and evolution to represent failure. Various EHSS steels grades used in this study. The results from this study shows reasonable agreement between the simulations and the test results. Hence, spot weld model obtained should be considered for crash analysis applications to understand behaviors of structural parts.

Keywords: finite element; spot weld; weld characterization; EHSS steel; T section specimen; B-PILLAR component IIHS testing.

I. INTRODUCTION

pot welding is the primary joining method used for the construction of the automotive body structure made of steel. A major challenge in the crash simulation today is the lack of a simple yet reliable to modeling approach characterize spot weld Various approaches separation. for Numerical simulation of spot welding has been discussed by [1, 2, 3, 4]. A study of a spot weld for numerical analysis of automotive applications under crash loading conditions using validation model 3 point- bend test were studied by Sebastian et al [5]. Hardness in the heat-affected zone and stresses are studied [6,7,8,9] that exhibit sharp hardness change adds to brittleness and notch sensitivity. Lee et al [10] and Chao [11] have studied the ultimate tensile strength of resistance spot welds in mild steel subjected to combined loading tension and shear loads. Detailed solid element simulations of local spot weld deformation under various loads provide rationale for the experimental observations and model simplifications discussed in paper by Deng et al [12]. Schweizerhof K et al [13] has discussed mesh sensitivity in spot weld modeling. Failure model parameters are derived from Finite element method (FEM) test simulations [14] since it's difficult to measure of local properties in spot welds.

The present work deals with a complete study on identification and modeling of spot weld connections. Relatively few studies have been conducted on the failure model of a spot weld under impact loading conditions whereas quasi-static cases are found more often. Most of studies are based on AHSS, DP 600 material as spot-weld and those sources do not show that EHSS steel materials sheet metal spot welding. In this study, the mechanical properties and spot weldability of newly developed EHSS steels are discussed which are widely used in automotive crash area with high energy intake e.g., front rails, sill, crash box, etc. The separation criteria are implemented into a commercially available explicit finite element code. This work is further focuses on acceptance of a B-pillarrail components subjected to axial impact. B-pillar commonly used hat section rails spot welded from end The key to end to integrate side structure. methodological evolution on the spot weld behavior is combined with a study on weld of Hat beam specimen of a prototypical B-pillar system. Thus improving crash safety through virtual prototyping is best approach to lessen cost and time.

II. Finite Element Modeling, Parameter Identification

Reliable modelling of deformation and damage behavior are necessary for the assessment of weld failure in automobile components. In this study, the mechanical properties and spot weld-ability of newly developed steels are discussed [15]. All of the specimens are made of high-strength steel (EHSS) sheet metal of the same thickness of 1.2 mm. This steel is having a yield strength 368 Mpa close to Dual phase

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DP600 but lower tensile strength. The high-strength steel materials HSLA340 showed a mutually comparable strength at quasi-static loading [16]. Uniaxial tensile tests and shear tests were made and studied to evaluate the mechanical properties of the material. In order to generate testing data, virtual tensile testing simulations were carried out with mesh sensitivity (30636 nodes and

30151 elements) in necking zone, as shown in Fig 1(a). This high mesh resolution around necking zone is required to capture the steep gradients in pressure and stress tri-axility, etc. A yield curve is defined to consider effect of strain rate due to dynamic event and to consider the deformation mechanism.



Fig.1: (a) FE simulations of tensile tests on smooth flat specimens, (b) Detail meshing of weld zone

The deformation of spot weld in HSS steel were numerically investigated under the relevant loads tension, shearing and bending specimens to develop reference model for validation and to avoid high costs for experimentation. Different properties are needed to consider for different zones to predict plastic flow localization and failure in steel spot weld. Failure strain are scaled to maintain the same strain energy to fail in various regions [17]. The spot welds are modeled by using fine solid mesh, as shown in Fig 1(b), to analyze the localized deformation. Fine solid mesh allows one to consider spot weld geometry and hardness gradient of its material [18]. This approach is also suitable for the spot welds rupture, which will be modelled in the crash analysis by element elimination. Safer car with improved spot weld rupture definition will provide realistic results compared to physical situation. Brittle fracture produces disastrous consequences as it occurs without warning. This necessitates that we propose a proper failure damage model in this study.

To demonstrate the proposed approach, simulation results of Extra High Strength Steels (EHSS) for lap-shear and coach peel specimens were used. [19. 20]. Characterization and deformation relevant to weld specimen loading were analyzed for the assessment of weld failure. The failure loads were used as the reference loads to determine the loads applied for other tests such as the fatigue tests, torsion test, etc. Vonmises stress and plastic strain experienced by the weld as well as strain rate corresponding to materials defined in various regions of weld were validated in terms of output result. This suggests that the predicted material constitutive laws using the inverse FE modelling for different zones is accurate. The deformation and failure behavior of weld joints were investigated on small scale specimens under tension and shear loading and KS-2 loading [21]. Spot weld models are developed in FE code LS-Dyna and its parameters identified. Detailed description about the modeling can be referred from [22-23].Damage in weld initiated is the function of failure function defined in the FE program Ls-Dyna. Identification of the material parameters for the elasticplastic region including damage and failure is an iterative process to follow physical testing.

*MAT_SPOTWELD_DAMAGE-FAILURE_TITLE (MAT_100_DA)									
mid	ro	е	pr	sigy	et	dt	tfail		
1	7.80E-09	2.00E+05	0.3	368	784	1e 6	0		
\$\$ Failure Parameter EHSS steel grade									
efail	nrr	nrs	nrt	mrr	mss	mtt	nf		
0	11030	25033	25033	16547	37548	37548	0		
rs	opt	fval	true_t	beta					
0	0	5	1e-6	0	0				
*DEFINE_SPOTWELD_FAILURE_RESULTANTS									
id	dsn	dss	dlcidsn	dlcidss					
1	0.9E+02,	1.80E+02	1.00E+04	1.00E+04					

Table 1: Spot Weld Material Parameters EHSS Steel Material

*MAT SPOTWELD DAMAGE-FAILURE predicted the accurate weld failure patterns consistent with all three experimental test modes[24]. Potential issues could happen if the material properties are not properly treated in the spot weld material card.

III. VALIDATION OF AUTOMOTIVE COMPONENTS

In order to model vehicles involved in automotive crashes, the structural components of these vehicles may need to be modeled in detail. Square beam parts are very common in automotive systems for absorbing energy during impact events like front and rear rails, cross members in the B-pillar structure, bumpers and B and C pillar reinforcements. Structural integrity of these welded structures are generally controlled by the strength of the spot welds which commonly fail under combined loading. Component level analyses and tests were conducted to establish the material properties of the spot weld.

a) T-Section Specimen Analysis

The T-joint specimens were used for the stress in the transverse direction also under load speeds simulating of 1 m/s. For this purpose also identified a slide mass in the amount of 192 kg to realize the failure of spot welds as shown in figure 2(a).





In baseline, artificial nature of contact forces disturbs the internal spot weld forces and stresses. Strain plots for critical welds are shown below. This is done to check for possibility of weld tearing. There is failure of shell elements due to high localized strain without any failure of spot welds causing unphysical deformation. Validation of simulation model was done as described in the following section. The simulations were compared out with new spot weld parameters as shown in Figure 3.



Fig. 3:(a) Force response of simulation loading (Baseline and New spot weld), (b) New spot weld post deformation

Comparing with baseline, the main failure mode encountered for weld on front and side of vertical rail. The force amplitude for these welds is between 2 kN and 12 kN, which avoid tearing of sheet metal with tail formation of these spot weld (Figure 9).Also high strain observed in this region of weld. This is more realistic deformation when compared to physical test. Overall weld force level changed slightly from baseline. Based on this information, it can be conclude that given EHSS steel are comparable with test specified HL340 steel results as referenced below figure 4 .Many simulations were carried out changing the weld material parameters and mesh sensitivity to improve the performance.



(b)



Also the representation of the local spot weld forces from the simulation under a loading rate of 1m/s and a slide mass of 192 kg are shown in Figure 5 below.



Fig. 5: (a) Location of spot weld on specimen, (b) weld failure captured from the simulation

Spot weld ID	Deformation mode	Max force kN	Time in Max (ms)
1	fails	13	27
2	fails	12.8	28
3	partial failure	11.6	24
4	partial failure	10.8	23
5	OK	10.1	29
6	OK	9.5	27

Table 2: T-section specimen weld deformation for 30 milli-sec

T-section specimen weld deformation for 30milli-sec observed and result shown in table 2. Two partial damage spot weld, two ruptured and two without damage. All weld forces for no tearing mode are below allowable force level 12596N ,however weld ID 1 and 2 observed complete failure due to exceeding allowable force level.At macroscopic scale, the mechanical performances of this new steel configuration spot weld are excellent in term of energy absorption. The final total internal energy of the T- joint rail component with new spot weld model is 127 kJ which is greater than baseline 116.7 kJ. Initial lower peak load implies a better performance of the energy collapsible structure in terms of safety design. The oscillations in the calculated force curve occur .These oscillations are caused by the immediate removal of the hexahedron is reached caused the failure criterion, since the elimination of the stored elastic energy at the Area around the spot weld is suddenly released. It is clear that the behavior of the force - time curves from simulation and experiment approach lesser peaks after the first force peaks. The force levels vary little from each other. This suggests that on a good set of failure criteria close. The performance, can be grown in individual spot weld forces, with mechanical properties comparable to experimental investigation carried out by literature even though the material involving spot weld differs. Figure 5 shows the post deformation of specimen in this simulation study as well as experimental loading [25]. It can be seen that the deformation pattern is comparable to the experiment on similar grade steel. A considerable

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amount of experiments have been performed to investigate the failure behavior of spot weld in similar setup [22]. In general, new spot weld model prediction is on conservative side and these spot weld model has been well characterized by this component model. The material data for the vehicle spot weld simulation can be adjusted to fit the results from this component simulation.

IV. B-PILLAR IIHS COMPONENT TESTING

The automotive industry continues to face the challenge of developing efficient side body structures that meet the performance requirements for multiple crashworthiness test modes. B-pillar. Roof and Side sill are the key structural members that help reduce the risk of injury to the occupants during a side impact crash event. Insurance Institute for Highway Safety (IIHS) evaluates a vehicle's crashworthiness with the help of Side impact test. Protecting people in side crashes is challenging because the sides of vehicles have relatively little space to absorb energy and shield occupants. The side crushing deformation is crucial to maintain space integrity in the occupant compartment. Thus structural performance of weld need special attention. Side impact crash tests consist of a stationary test vehicle struck on the driver's side by a crash cart fitted with an IIHS deformable barrier element. The 1,500 kg moving deformable barrier (MDB) has an impact velocity of 50 km/h (31.1 mi/h) and strikes the vehicle on the driver's side at a 90-degree angle [26]. The longitudinal impact point of the barrier on the side of the test vehicle is

dependent on the vehicle's wheelbase. The impact reference distance (IRD) is defined as the distance rearward from the test vehicle's front axle to the closest edge of the deformable barrier when it first contacts the vehicle (Figure 6). Middle plane of barrier is in-line with front row dummy seat reference plane



Fig.6: Moving deformable barrier alignment with test vehicle [26]

The MDB is accelerated by the propulsion system until it reaches the test speed (50 km/h) and then is released from the propulsion system 25 cm before the point of impact with the test vehicle. The impact point tolerance is \pm 2.5 cm of the target in the horizontal and vertical axes. The impact speed tolerance is 50 \pm 1 km/h. The MDB alignment calculation was configured to maximize loading to the occupant compartment.

One of the leading automotive OEM client was interested in B- pillar correlation with new weld methodology. B-pillar subsystem level test is best way to study of weld performance in Impact Analysis (Figure 7). The crash event between the MDB and the target vehicle is shortened by this approach. IIHS Side Impact barrier mounted on wagon fixture base for sled test. Barrier engages B-pillar only in component level resulting in single load path for energy management. Thus developing component testing to confirm performance prior to full-vehicle testing is best strategy. A laboratory experiment was designed at Wichita State University's National Institute for Aviation Research to test the B-Pillar spot weld welded structures [27]. Wichita State University's National Institute for Aviation Research utilizing state-of-the-art testing, measurement and data collection equipment along with advanced software and techniques to perform crash sled test analyses. This Crash dynamics lab performs various component level crash tests. NIAR research center wagon fixture base used for this subsystem level test. The test conditions are equivalent to full vehicle test as per IIHS test protocol, especially confirmation of impact point is same as used in full vehicle test setup. The results of B-Pillar Component test were used to improve the spot weld finite element model developed at Wichita State University, simulating the crash events at NIAR sled test facility with a higher degree of correlation.

An area of focus in this study is the deformation mode capture. This component level setup not captures door to occupant interaction. To understand the effects of the spot weld, two FE models have been developed. The first model is MAT 100 SW to provide a baseline test and understanding of side impact crash at a basic level. The second door model is a new spot weld in terms of spot weld parameters which is representative of weld failure. [Studies have been performed by modeling the components of the door including the trim, inner panel, outer panel, Hinge pillar and Rocker material. The CAE model is followed latest procedure per Side Safety regulation using 4 mm mesh. Two pieces for b pillar are layered & weldedafter the blanking process & before hot stamping, Spot weld modeled with new paramter applied for high strength steel parts as indicated in picture.





wagon fixture base for barrrier mouting

Fig.7: Test setup for B-Pillar spot weld welded structures [28]

The idea was to make the wagon accelerate like in the full-scale test by LINCAP, to validate the new spot weld model. These sled tests are referred to as *correlation tests*. The sled tests were done to evaluate how well the spot weld perform and what could be improved to meet the customer needs. Based on physical test findings, a procedure was developed for spot weld failure in order to correlate properly in Ls-Dyna simulations. In simulation model, B-pillar is impacted by a moving rigid impactor plate. The impacting mass is modeled using a mass element of 1500 kg and is attached to the impactor plate by a reference point located on RBE3. A SPC boundary condition is imposed at upper and lower end of B-pillar using *Boundary_SPC constrained to zero in all three direction.B-Pillar spot weld design had significant strength gradient at joint between upper and lower Bpillar components. B-pillar Lower material changed from HSS to EHSS steel grade characterized in earlier section. EHSS steel grade provides increased elongation for event. This side impact model was then used to investigate the effects of spot weld failure. Spot welds commonly fail under combined loads during impact scenario. Spot weld lines around B pillar are shown in figure 7.

BLUE: Baseline RED: New SW Model



Fig.8: Post-crash deformation of the B-Pillar spot weld welded structures

The load balance between underbody and upper body has changed in new spot weld Design and caused the lower body intrusion. The B-pillar side impact simulation shows the comparison of side sill deformation mode between baseline and new spot weld model(Figure 8).Baseline CAE model softer than the test predicting moredeformation than the test.



Fig. 9: (a)Comparison of Stress contour of the B-Pillar spot weld welded structures LH side view, (b) Test Deformation of the B-Pillar[27] RH side view, (c)B-pillar velocity comparison

Post deformation of test vs simulation compared in figure 9. Baseline FE model having MAT 100 spot weld material model displayed undesirable structural performance as per stress contour. This model had insufficient Strength/elongation combination. New Spot WeldB-pillar Modelimproved CAE correlation for deformation modes as shown in figure 9. It is observed that internal energy of B-pillar reinf parts is 6 % more for New Spot Weld Model compared to baseline. Also result were compared with side impact crash test data found in Lightweight BIW Structure project by the Auto/Steel Partnership (A/SP), 2009[29].

Component test correlates well with B pillar simulation when spot welds failure defined as per MAT_100_DAMAGE model. This focused on the need to define spot weld failure for side impact testing to evaluate the risk of injuries and then finding countermeasure to diminish it.

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Table 4. Result Summary for B-Philar IIRS Component resulting /Side impact statistics								
Load case	Measuring Points	Target	Baseline	New Spot Weld Model				
	B pillar velocity (at beltline) (m/sec)	10	10.2	10				
IIHS								

70

123

Table 4: Result Summary for B-Pillar IIHS Component Testing /Side Impact statistics

WSU sled tests are simplified cases which do not account forintrusion and occupant to door spacing. Hence above table compare simulation study for baseline and new spot weld model. New Spot Weld Model analysis catches well velocity & crush modes. Overall New Spot Weld Model show lower velocity. Not a big difference in B-pillar beltline velocity however B-pillar residual space cut down by 60 mm. The baseline simulation shows less survival space as compared to New spot weld model.Reducing B-pillar intrusion vis structural upgrading of the body side weld failure model. Failure in the weld diminish momentum exchange between door and dummy and thus it delay force by more energy absorption. This is compliant for occupant cushioning. Failure of weld at bottom concentrating the impact load on the occupant in the lower pelvis region. A more desirable crush pattern for the B-pillar/door is to remain upright during side impact for a more evenly distributed impact loading on the occupant.

B pillar residual intrusion (at beltline) (mm)

V. Conclusion

To establish modelling procedure for weld failure in this paper, simulation model was built and correlated with the Baseline test specification. A failure spot weld analysis performed in this work could he extremely relevant from the vehic1e design stand point. The weld model includes failure criteria based on a critical plastic failure strain, as well as on a force envelope. Depending on the materials, a greater number of different specimen tests will be needed to identify the parameters for the damage model. Two examples were provided to demonstrate the implementations of this procedure and to show the improvement of the results through the use of new spot weld model. In the first example, axial load was applied on a hat shape rail to observe crush deformation mode. In the second example, T section specimen impacted to see weld failure in joint region, the weld failure significantly improved. Both of the examples proved the proposed spot welding procedure was correct. Then, investigations based on the simple models were performed to identify the B-pillar velocity in side impact simulations. National Institute for Aviation Research did this project to show their capability to capture this correlations The system integrated FEM has proven to be a valuable and effective predictive tool that can account for spot weld interactions for Structural integrity of B-Pillar welded structures. Through computational simulations results, this study provide essential information to match performance of weld and to study the stiffness of the b-pillar sub-structure.

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Journals Research

The FARSE can go through standards of OARS. You can also play vital role if you have any suggestions so that proper amendment can take place to improve the same for the benefit of entire research community.

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MARSE accrediting is an honor. It authenticates your research activities. After becoming MARSE, you can add 'MARSE' title with your name as you use this recognition as additional suffix to your status. This will definitely enhance and add more value and repute to your name. You may use it on your professional Counseling Materials such as CV, Resume, Visiting Card and Name Plate etc.

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The MARSE member can apply for approval, grading and certification of standards of their educational and Institutional Degrees to Open Association of Research, Society U.S.A.





Once you are designated as MARSE, you may send us a scanned copy of all of your credentials. OARS will verify, grade and certify them. This will be based on your academic records, quality of research papers published by you, and some more criteria.

It is mandatory to read all terms and conditions carefully.

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Institutional Fellow of Open Association of Research Society (USA)-OARS (USA)

Global Journals Incorporation (USA) is accredited by Open Association of Research Society, U.S.A (OARS) and in turn, affiliates research institutions as "Institutional Fellow of Open Association of Research Society" (IFOARS).

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The IFOARS institution is entitled to form a Board comprised of one Chairperson and three to five board members preferably from different streams. The Board will be recognized as "Institutional Board of Open Association of Research Society"-(IBOARS).

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The IBOARS can initially review research papers of their institute and recommend them to publish with respective journal of Global Journals. It can also review the papers of other institutions after obtaining our consent. The second review will be done by peer reviewer of Global Journals Incorporation (USA) The Board is at liberty to appoint a peer reviewer with the approval of chairperson after consulting us.

The author fees of such paper may be waived off up to 40%.

The Global Journals Incorporation (USA) at its discretion can also refer double blind peer reviewed paper at their end to the board for the verification and to get recommendation for final stage of acceptance of publication.





The IBOARS can organize symposium/seminar/conference in their country on seminar of Global Journals Incorporation (USA)-OARS (USA). The terms and conditions can be discussed separately.

The Board can also play vital role by exploring and giving valuable suggestions regarding the Standards of "Open Association of Research Society, U.S.A (OARS)" so that proper amendment can take place for the benefit of entire research community. We shall provide details of particular standard only on receipt of request from the Board.





The board members can also join us as Individual Fellow with 40% discount on total fees applicable to Individual Fellow. They will be entitled to avail all the benefits as declared. Please visit Individual Fellow-sub menu of GlobalJournals.org to have more relevant details.

Journals Research relevant details.

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After nomination of your institution as "Institutional Fellow" and constantly functioning successfully for one year, we can consider giving recognition to your institute to function as Regional/Zonal office on our behalf.

The board can also take up the additional allied activities for betterment after our consultation.

The following entitlements are applicable to individual Fellows:

Open Association of Research Society, U.S.A (OARS) By-laws states that an individual Fellow may use the designations as applicable, or the corresponding initials. The Credentials of individual Fellow and Associate designations signify that the individual has gained knowledge of the fundamental concepts. One is magnanimous and proficient in an expertise course covering the professional code of conduct, and follows recognized standards of practice.





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- Fellow can also join as paid peer reviewer and earn 15% remuneration of author charges and can also get an opportunity to join as member of the Editorial Board of Global Journals Incorporation (USA)
- This individual has learned the basic methods of applying those concepts and techniques to common challenging situations. This individual has further demonstrated an in-depth understanding of the application of suitable techniques to a particular area of research practice.

Note :

- In future, if the board feels the necessity to change any board member, the same can be done with the consent of the chairperson along with anyone board member without our approval.
- In case, the chairperson needs to be replaced then consent of 2/3rd board members are required and they are also required to jointly pass the resolution copy of which should be sent to us. In such case, it will be compulsory to obtain our approval before replacement.
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The paper should be in proper format. The format can be downloaded from first page of 'Author Guideline' Menu. The Author is expected to follow the general rules as mentioned in this menu. The paper should be written in MS-Word Format (*.DOC,*.DOCX).

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Page Size: 8.27" X 11'"

- Left Margin: 0.65
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- Font type of all text should be Swis 721 Lt BT.
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- Author Name in Font Size of 11 with one column as of Title.
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- Two Column with Equal Column with of 3.38 and Gaping of .2
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You can use your own standard format also. Author Guidelines:

1. General,

- 2. Ethical Guidelines,
- 3. Submission of Manuscripts,
- 4. Manuscript's Category,
- 5. Structure and Format of Manuscript,
- 6. After Acceptance.

1. GENERAL

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Scope

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The Global Journals Inc. (US) follows the definition of authorship set up by the Global Academy of Research and Development. According to the Global Academy of R&D authorship, criteria must be based on:

1) Substantial contributions to conception and acquisition of data, analysis and interpretation of the findings.

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3) Final approval of the version of the paper to be published.

All authors should have been credited according to their appropriate contribution in research activity and preparing paper. Contributors who do not match the criteria as authors may be mentioned under Acknowledgement.

Acknowledgements: Contributors to the research other than authors credited should be mentioned under acknowledgement. The specifications of the source of funding for the research if appropriate can be included. Suppliers of resources may be mentioned along with address.

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Manuscript submission is a systematic procedure and little preparation is required beyond having all parts of your manuscript in a given format and a computer with an Internet connection and a Web browser. Full help and instructions are provided on-screen. As an author, you will be prompted for login and manuscript details as Field of Paper and then to upload your manuscript file(s) according to the instructions.



To avoid postal delays, all transaction is preferred by e-mail. A finished manuscript submission is confirmed by e-mail immediately and your paper enters the editorial process with no postal delays. When a conclusion is made about the publication of your paper by our Editorial Board, revisions can be submitted online with the same procedure, with an occasion to view and respond to all comments.

Complete support for both authors and co-author is provided.

4. MANUSCRIPT'S CATEGORY

Based on potential and nature, the manuscript can be categorized under the following heads:

Original research paper: Such papers are reports of high-level significant original research work.

Review papers: These are concise, significant but helpful and decisive topics for young researchers.

Research articles: These are handled with small investigation and applications

Research letters: The letters are small and concise comments on previously published matters.

5.STRUCTURE AND FORMAT OF MANUSCRIPT

The recommended size of original research paper is less than seven thousand words, review papers fewer than seven thousands words also. Preparation of research paper or how to write research paper, are major hurdle, while writing manuscript. The research articles and research letters should be fewer than three thousand words, the structure original research paper; sometime review paper should be as follows:

Papers: These are reports of significant research (typically less than 7000 words equivalent, including tables, figures, references), and comprise:

(a)Title should be relevant and commensurate with the theme of the paper.

(b) A brief Summary, "Abstract" (less than 150 words) containing the major results and conclusions.

(c) Up to ten keywords, that precisely identifies the paper's subject, purpose, and focus.

(d) An Introduction, giving necessary background excluding subheadings; objectives must be clearly declared.

(e) Resources and techniques with sufficient complete experimental details (wherever possible by reference) to permit repetition; sources of information must be given and numerical methods must be specified by reference, unless non-standard.

(f) Results should be presented concisely, by well-designed tables and/or figures; the same data may not be used in both; suitable statistical data should be given. All data must be obtained with attention to numerical detail in the planning stage. As reproduced design has been recognized to be important to experiments for a considerable time, the Editor has decided that any paper that appears not to have adequate numerical treatments of the data will be returned un-refereed;

(g) Discussion should cover the implications and consequences, not just recapitulating the results; conclusions should be summarizing.

(h) Brief Acknowledgements.

(i) References in the proper form.

Authors should very cautiously consider the preparation of papers to ensure that they communicate efficiently. Papers are much more likely to be accepted, if they are cautiously designed and laid out, contain few or no errors, are summarizing, and be conventional to the approach and instructions. They will in addition, be published with much less delays than those that require much technical and editorial correction.

The Editorial Board reserves the right to make literary corrections and to make suggestions to improve briefness.

It is vital, that authors take care in submitting a manuscript that is written in simple language and adheres to published guidelines.

Format

Language: The language of publication is UK English. Authors, for whom English is a second language, must have their manuscript efficiently edited by an English-speaking person before submission to make sure that, the English is of high excellence. It is preferable, that manuscripts should be professionally edited.

Standard Usage, Abbreviations, and Units: Spelling and hyphenation should be conventional to The Concise Oxford English Dictionary. Statistics and measurements should at all times be given in figures, e.g. 16 min, except for when the number begins a sentence. When the number does not refer to a unit of measurement it should be spelt in full unless, it is 160 or greater.

Abbreviations supposed to be used carefully. The abbreviated name or expression is supposed to be cited in full at first usage, followed by the conventional abbreviation in parentheses.

Metric SI units are supposed to generally be used excluding where they conflict with current practice or are confusing. For illustration, 1.4 I rather than $1.4 \times 10-3$ m3, or 4 mm somewhat than $4 \times 10-3$ m. Chemical formula and solutions must identify the form used, e.g. anhydrous or hydrated, and the concentration must be in clearly defined units. Common species names should be followed by underlines at the first mention. For following use the generic name should be constricted to a single letter, if it is clear.

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Abstract, used in Original Papers and Reviews:

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Many researchers searching for information online will use search engines such as Google, Yahoo or similar. By optimizing your paper for search engines, you will amplify the chance of someone finding it. This in turn will make it more likely to be viewed and/or cited in a further work. Global Journals Inc. (US) have compiled these guidelines to facilitate you to maximize the web-friendliness of the most public part of your paper.

Key Words

A major linchpin in research work for the writing research paper is the keyword search, which one will employ to find both library and Internet resources.

One must be persistent and creative in using keywords. An effective keyword search requires a strategy and planning a list of possible keywords and phrases to try.

Search engines for most searches, use Boolean searching, which is somewhat different from Internet searches. The Boolean search uses "operators," words (and, or, not, and near) that enable you to expand or narrow your affords. Tips for research paper while preparing research paper are very helpful guideline of research paper.

Choice of key words is first tool of tips to write research paper. Research paper writing is an art.A few tips for deciding as strategically as possible about keyword search:



- One should start brainstorming lists of possible keywords before even begin searching. Think about the most important concepts related to research work. Ask, "What words would a source have to include to be truly valuable in research paper?" Then consider synonyms for the important words.
- It may take the discovery of only one relevant paper to let steer in the right keyword direction because in most databases, the keywords under which a research paper is abstracted are listed with the paper.
- One should avoid outdated words.

Keywords are the key that opens a door to research work sources. Keyword searching is an art in which researcher's skills are bound to improve with experience and time.

Numerical Methods: Numerical methods used should be clear and, where appropriate, supported by references.

Acknowledgements: Please make these as concise as possible.

References

References follow the Harvard scheme of referencing. References in the text should cite the authors' names followed by the time of their publication, unless there are three or more authors when simply the first author's name is quoted followed by et al. unpublished work has to only be cited where necessary, and only in the text. Copies of references in press in other journals have to be supplied with submitted typescripts. It is necessary that all citations and references be carefully checked before submission, as mistakes or omissions will cause delays.

References to information on the World Wide Web can be given, but only if the information is available without charge to readers on an official site. Wikipedia and Similar websites are not allowed where anyone can change the information. Authors will be asked to make available electronic copies of the cited information for inclusion on the Global Journals Inc. (US) homepage at the judgment of the Editorial Board.

The Editorial Board and Global Journals Inc. (US) recommend that, citation of online-published papers and other material should be done via a DOI (digital object identifier). If an author cites anything, which does not have a DOI, they run the risk of the cited material not being noticeable.

The Editorial Board and Global Journals Inc. (US) recommend the use of a tool such as Reference Manager for reference management and formatting.

Tables, Figures and Figure Legends

Tables: Tables should be few in number, cautiously designed, uncrowned, and include only essential data. Each must have an Arabic number, e.g. Table 4, a self-explanatory caption and be on a separate sheet. Vertical lines should not be used.

Figures: Figures are supposed to be submitted as separate files. Always take in a citation in the text for each figure using Arabic numbers, e.g. Fig. 4. Artwork must be submitted online in electronic form by e-mailing them.

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Even though low quality images are sufficient for review purposes, print publication requires high quality images to prevent the final product being blurred or fuzzy. Submit (or e-mail) EPS (line art) or TIFF (halftone/photographs) files only. MS PowerPoint and Word Graphics are unsuitable for printed pictures. Do not use pixel-oriented software. Scans (TIFF only) should have a resolution of at least 350 dpi (halftone) or 700 to 1100 dpi (line drawings) in relation to the imitation size. Please give the data for figures in black and white or submit a Color Work Agreement Form. EPS files must be saved with fonts embedded (and with a TIFF preview, if possible).

For scanned images, the scanning resolution (at final image size) ought to be as follows to ensure good reproduction: line art: >650 dpi; halftones (including gel photographs) : >350 dpi; figures containing both halftone and line images: >650 dpi.

Figure Legends: Self-explanatory legends of all figures should be incorporated separately under the heading 'Legends to Figures'. In the full-text online edition of the journal, figure legends may possibly be truncated in abbreviated links to the full screen version. Therefore, the first 100 characters of any legend should notify the reader, about the key aspects of the figure.

6. AFTER ACCEPTANCE

Upon approval of a paper for publication, the manuscript will be forwarded to the dean, who is responsible for the publication of the Global Journals Inc. (US).

6.1 Proof Corrections

The corresponding author will receive an e-mail alert containing a link to a website or will be attached. A working e-mail address must therefore be provided for the related author.

Acrobat Reader will be required in order to read this file. This software can be downloaded

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www.adobe.com/products/acrobat/readstep2.html. This will facilitate the file to be opened, read on screen, and printed out in order for any corrections to be added. Further instructions will be sent with the proof.

Proofs must be returned to the dean at <u>dean@globaljournals.org</u> within three days of receipt.

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You must strictly follow above Author Guidelines before submitting your paper or else we will not at all be responsible for any corrections in future in any of the way.

Before start writing a good quality Computer Science Research Paper, let us first understand what is Computer Science Research Paper? So, Computer Science Research Paper is the paper which is written by professionals or scientists who are associated to Computer Science and Information Technology, or doing research study in these areas. If you are novel to this field then you can consult about this field from your supervisor or guide.

TECHNIQUES FOR WRITING A GOOD QUALITY RESEARCH PAPER:

1. Choosing the topic: In most cases, the topic is searched by the interest of author but it can be also suggested by the guides. You can have several topics and then you can judge that in which topic or subject you are finding yourself most comfortable. This can be done by asking several questions to yourself, like Will I be able to carry our search in this area? Will I find all necessary recourses to accomplish the search? Will I be able to find all information in this field area? If the answer of these types of questions will be "Yes" then you can choose that topic. In most of the cases, you may have to conduct the surveys and have to visit several places because this field is related to Computer Science and Information Technology. Also, you may have to do a lot of work to find all rise and falls regarding the various data of that subject. Sometimes, detailed information plays a vital role, instead of short information.

2. Evaluators are human: First thing to remember that evaluators are also human being. They are not only meant for rejecting a paper. They are here to evaluate your paper. So, present your Best.

3. Think Like Evaluators: If you are in a confusion or getting demotivated that your paper will be accepted by evaluators or not, then think and try to evaluate your paper like an Evaluator. Try to understand that what an evaluator wants in your research paper and automatically you will have your answer.

4. Make blueprints of paper: The outline is the plan or framework that will help you to arrange your thoughts. It will make your paper logical. But remember that all points of your outline must be related to the topic you have chosen.

5. Ask your Guides: If you are having any difficulty in your research, then do not hesitate to share your difficulty to your guide (if you have any). They will surely help you out and resolve your doubts. If you can't clarify what exactly you require for your work then ask the supervisor to help you with the alternative. He might also provide you the list of essential readings.

6. Use of computer is recommended: As you are doing research in the field of Computer Science, then this point is quite obvious.

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10. Bookmarks are useful: When you read any book or magazine, you generally use bookmarks, right! It is a good habit, which helps to not to lose your continuity. You should always use bookmarks while searching on Internet also, which will make your search easier.

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19. Know what you know: Always try to know, what you know by making objectives. Else, you will be confused and cannot achieve your target.

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21. Arrangement of information: Each section of the main body should start with an opening sentence and there should be a changeover at the end of the section. Give only valid and powerful arguments to your topic. You may also maintain your arguments with records.

22. Never start in last minute: Always start at right time and give enough time to research work. Leaving everything to the last minute will degrade your paper and spoil your work.

23. Multitasking in research is not good: Doing several things at the same time proves bad habit in case of research activity. Research is an area, where everything has a particular time slot. Divide your research work in parts and do particular part in particular time slot.

24. Never copy others' work: Never copy others' work and give it your name because if evaluator has seen it anywhere you will be in trouble.

25. Take proper rest and food: No matter how many hours you spend for your research activity, if you are not taking care of your health then all your efforts will be in vain. For a quality research, study is must, and this can be done by taking proper rest and food.

26. Go for seminars: Attend seminars if the topic is relevant to your research area. Utilize all your resources.

27. Refresh your mind after intervals: Try to give rest to your mind by listening to soft music or by sleeping in intervals. This will also improve your memory.

28. Make colleagues: Always try to make colleagues. No matter how sharper or intelligent you are, if you make colleagues you can have several ideas, which will be helpful for your research.

29. Think technically: Always think technically. If anything happens, then search its reasons, its benefits, and demerits.

30. Think and then print: When you will go to print your paper, notice that tables are not be split, headings are not detached from their descriptions, and page sequence is maintained.

31. Adding unnecessary information: Do not add unnecessary information, like, I have used MS Excel to draw graph. Do not add irrelevant and inappropriate material. These all will create superfluous. Foreign terminology and phrases are not apropos. One should NEVER take a broad view. Analogy in script is like feathers on a snake. Not at all use a large word when a very small one would be sufficient. Use words properly, regardless of how others use them. Remove quotations. Puns are for kids, not grunt readers. Amplification is a billion times of inferior quality than sarcasm.

32. Never oversimplify everything: To add material in your research paper, never go for oversimplification. This will definitely irritate the evaluator. Be more or less specific. Also too, by no means, ever use rhythmic redundancies. Contractions aren't essential and shouldn't be there used. Comparisons are as terrible as clichés. Give up ampersands and abbreviations, and so on. Remove commas, that are, not necessary. Parenthetical words however should be together with this in commas. Understatement is all the time the complete best way to put onward earth-shaking thoughts. Give a detailed literary review.

33. Report concluded results: Use concluded results. From raw data, filter the results and then conclude your studies based on measurements and observations taken. Significant figures and appropriate number of decimal places should be used. Parenthetical remarks are prohibitive. Proofread carefully at final stage. In the end give outline to your arguments. Spot out perspectives of further study of this subject. Justify your conclusion by at the bottom of them with sufficient justifications and examples.

34. After conclusion: Once you have concluded your research, the next most important step is to present your findings. Presentation is extremely important as it is the definite medium though which your research is going to be in print to the rest of the crowd. Care should be taken to categorize your thoughts well and present them in a logical and neat manner. A good quality research paper format is essential because it serves to highlight your research paper and bring to light all necessary aspects in your research.

INFORMAL GUIDELINES OF RESEARCH PAPER WRITING

Key points to remember:

- Submit all work in its final form.
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- Please note the criterion for grading the final paper by peer-reviewers.

Final Points:

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The introduction will be compiled from reference matter and will reflect the design processes or outline of basis that direct you to make study. As you will carry out the process of study, the method and process section will be constructed as like that. The result segment will show related statistics in nearly sequential order and will direct the reviewers next to the similar intellectual paths throughout the data that you took to carry out your study. The discussion section will provide understanding of the data and projections as to the implication of the results. The use of good quality references all through the paper will give the effort trustworthiness by representing an alertness of prior workings.

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- \cdot Align the primary line of each section
- · Present your points in sound order
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- \cdot Use past tense to describe specific results
- · Shun familiar wording, don't address the reviewer directly, and don't use slang, slang language, or superlatives

· Shun use of extra pictures - include only those figures essential to presenting results

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The summary should be two hundred words or less. It should briefly and clearly explain the key findings reported in the manuscript-must have precise statistics. It should not have abnormal acronyms or abbreviations. It should be logical in itself. Shun citing references at this point.

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- Reason of the study theory, overall issue, purpose
- Fundamental goal
- To the point depiction of the research
- Consequences, including <u>definite statistics</u> if the consequences are quantitative in nature, account quantitative data; results of any numerical analysis should be reported
- Significant conclusions or questions that track from the research(es)

Approach:

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- Present a justification. Status your particular theory (es) or aim(s), and describe the logic that led you to choose them.
- Very for a short time explain the tentative propose and how it skilled the declared objectives.

Approach:

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- If use of a definite type of tools.
- Materials may be reported in a part section or else they may be recognized along with your measures.

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- Simplify details how procedures were completed not how they were exclusively performed on a particular day.
- If well known procedures were used, account the procedure by name, possibly with reference, and that's all.

Approach:

- It is embarrassed or not possible to use vigorous voice when documenting methods with no using first person, which would focus the reviewer's interest on the researcher rather than the job. As a result when script up the methods most authors use third person passive voice.
- Use standard style in this and in every other part of the paper avoid familiar lists, and use full sentences.

What to keep away from

- Resources and methods are not a set of information.
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The page length of this segment is set by the sum and types of data to be reported. Carry on to be to the point, by means of statistics and tables, if suitable, to present consequences most efficiently. You must obviously differentiate material that would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matter should not be submitted at all except requested by the instructor.



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- Sum up your conclusion in text and demonstrate them, if suitable, with figures and tables.
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- Present a background, such as by describing the question that was addressed by creation an exacting study.
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Approach

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- Give details all of your remarks as much as possible, focus on mechanisms.
- Make a decision if the tentative design sufficiently addressed the theory, and whether or not it was correctly restricted.
- Try to present substitute explanations if sensible alternatives be present.
- One research will not counter an overall question, so maintain the large picture in mind, where do you go next? The best studies unlock new avenues of study. What questions remain?
- Recommendations for detailed papers will offer supplementary suggestions.

Approach:

- When you refer to information, differentiate data generated by your own studies from available information
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Introduction	Containing all background details with clear goal and appropriate details, flow specification, no grammar and spelling mistake, well organized sentence and paragraph, reference cited	Unclear and confusing data, appropriate format, grammar and spelling errors with unorganized matter	Out of place depth and content, hazy format
Methods and Procedures	Clear and to the point with well arranged paragraph, precision and accuracy of facts and figures, well organized subheads	Difficult to comprehend with embarrassed text, too much explanation but completed	Incorrect and unorganized structure with hazy meaning
Result	Well organized, Clear and specific, Correct units with precision, correct data, well structuring of paragraph, no grammar and spelling mistake	Complete and embarrassed text, difficult to comprehend	Irregular format with wrong facts and figures
Discussion	Well organized, meaningful specification, sound conclusion, logical and concise explanation, highly structured paragraph reference cited	Wordy, unclear conclusion, spurious	Conclusion is not cited, unorganized, difficult to comprehend
References	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring

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