

GLOBAL JOURNAL

OF RESEARCHES IN ENGINEERING: A

Mechanical & Mechanics Engineering

Design for Rooftop of Metro

Parametric Control for Machining

Highlights

Review of Modelling Techniques

Evaluation of Machinability Index

Discovering Thoughts, Inventing Future

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CONTENTS OF THE ISSUE

- i. Copyright Notice
 - ii. Editorial Board Members
 - iii. Chief Author and Dean
 - iv. Contents of the Issue
-
1. Fixture Design for Rooftop of Metro. *1-15*
 2. Evaluation of Parametric Control for Machining with WEDM and Machinability Index. *17-21*
 3. A Review of Modelling Techniques for Loading Problems in Flexible Manufacturing System. *23-36*
-
- v. Fellows and Auxiliary Memberships
 - vi. Process of Submission of Research Paper
 - vii. Preferred Author Guidelines
 - viii. Index



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Fixture Design for Rooftop of Metro

By Prof. S. N. Shinde, Siddharthkshirsagar, Aniruddhapatil, Tejasparge
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Abstract- Researching the possibilities for fixture design aided by computers has been in the sphere of interest of a number of authors worldwide for a longer period. Research results have led to the precise and systematised knowledge on the possibilities offered by computer application in fixture design process. The paper emphasises the importance of fixture design automation. It presents a general structure of the automated design system with a special highlight on the fixture design systems and their main characteristics. It also shows a structure and a part of output results of the automated modular fixture design system. Finally, the reached conclusions are presented with the expected directions of future researches. In industrial ergonomics a manipulator is a lift assist device used to help workers lift, maneuver and place articles in process that are too heavy, too hot, large or otherwise too difficult for a single worker to manually handle.

Keywords: *welding, fixture, manipulators, solidworks, plc.*

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Fixture Design for Rooftop of Metro

Prof. S. N.Shinde ^α, Siddharthkshirsagar ^σ, Aniruddhapatil ^ρ, Tejasparge ^ω & Riteshlomte [¥]

Abstract- Researching the possibilities for fixture design aided by computers has been in the sphere of interest of a number of authors worldwide for a longer period. Research results have led to the precise and systematised knowledge on the possibilities offered by computer application in fixture design process. The paper emphasises the importance of fixture design automation. It presents a general structure of the automated design system with a special highlight on the fixture design systems and their main characteristics. It also shows a structure and a part of output results of the automated modular fixture design system. Finally, the reached conclusions are presented with the expected directions of future researches. In industrial ergonomics a manipulator is a lift assist device used to help workers lift, maneuver and place articles in process that are too heavy, too hot, large or otherwise too difficult for a single worker to manually handle.

Keywords: welding, fixture, manipulators, solidworks, plc.

1. INTRODUCTION

Fixture design is typically a setup cost function, making it very valuable in flow time and indirect cost calculations. Due to the rapid response required in many applications, the fixture design principles must be integrated and properly detailed so as to facilitate the fast design development of a fixture. Frequent checking, positioning, individual marking and non-uniform quality in manufacturing process are

eliminated by fixture. This increase productivity and reduce operation time. Welding fixtures are normally designed to hold and support the various components (workpieces) to be welded. Fixture is a device for locating, holding and supporting a work piece during a manufacturing industry [2]. It is necessary to support them in a proper location which is capable of preventing distortions in workpieces during welding. For this the locating elements need to be placed carefully, clamping has to be light but firm, placement of clamping elements has to be clear of the welding area and the fixture has to be quite stable and rigid to withstand the welding stresses. With the aid of manipulator the welding fixture on which the rooftop will be placed is rotated for welding purpose. After necessary welding operations being performed, the fixture is rotated back to its original position. Then the rooftop is unclamped and unscrewed from its fixture in order to get lifted by the crane to be placed on the train top. For carrying out these operations appropriate design and functioning of this mechanism is of prime concern. As a result of complex alignment and positioning equipment are important as they are required in nearly all research and manufacturing processes[1].



Figure 1 : Rooftop of railway

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Current production systems in manufacturing industry are characterized by product range extension, high frequency in changing production programs, demands for constant product quality improvement, shortenings in production time, constant need for increasing technological level of products and decreasing their manufacturing costs. In industries it is however, with the availability of 64 digit computers and refined FE tools, welding engineers around the world are

more biased towards the computer simulations of complex welding phenomenon instead of the conventional trial and error approach on the shop floor is the most common practice nowadays [5]. With such market demands, and intensive development of science, technique and information technologies, the level and the trend of further development of technological machining processes in metal manufacturing industry depend on all the composing factors, those being the following: type of blank, machining process, order of operations, machinery, operation and sequence concentration, tools, fixtures, measurements, etc

II. MATERIALS AND COMPONENTS

Out of many types of steel used for manufacturing we have chosen plain carbon steel while designing and manufacturing as it is robust, cheaper than other steels and easily available.

- i. The fabrication System mounted on the base is made up of mild steel.
- ii. For hard parts which are prone to inducing friction is made up of alloy steel grade EN-19 having high tensile strength, good ductility and shock resisting properties.
- iii. Pins are made up of 20MnCr5 which are toughened and case hardened for smooth operation.

Jigs and Fixtures are made of variety of materials, some of which can be hardened to resist wear. Materials generally used: -

- High speed Steel: Cutting tools like drills, reamers and milling cutters.
- Carbon steels: Used for standard cutting tools.
- Non shrinking tool steels: High carbon or high chromium.
 - Very little distortion during heat treatment.
 - Used widely for fine, intricate press tools.
- Nickel chrome steels: Used for gears.
- High tensile steels: Used for fasteners like high tensile screws
- Mild steel: Used in most part of Jigs and Fixtures Cheapest material contains less than 0.3% carbon
- Cast Iron: Used for odd shapes to some machining and laborious fabrication
 - CI usage requires a pattern for casting.
 - Contains more than 2% carbon.
 - Has self-lubricating properties.

Our finalized design is a product of the several different ideas and components originally created in the design phase.

a) *Manipulator*:- In industrial ergonomics a manipulator is a lift assist device used to help workers lift, maneuver and place articles in process that are too

heavy, too hot, too large or otherwise too difficult for a single worker to manually handle. As opposed to simply vertical lift assists (cranes, hoists, etc.) manipulators have the ability to reach in to tight spaces and remove workpieces.



Figure 2 : Manipulator

- b) *Gears*:- Gears used are spur gears or straight-cut gears are the simplest type of gear. They consist of a cylinder or disk with the teeth projecting radially, and although they are not straight-sided in form (they are usually of special form to achieve constant drive ratio, mainly involute), the edge of each tooth is straight and aligned parallel to the axis of rotation. These gears can be meshed together correctly only if they are fitted to parallel shafts.



Figure 3 : Spur Gear

- c) *Brake Motor*:- A Motor is a device that creates motion. It usually refers to an engine of some kind. It may also specifically refer to Electric motor, a machine that converts electricity into a mechanical motion. Brake motor consists of an induction motor coupled to a disk brake, forming an integrated compact and robust unit. The brake used is sturdy with few moving parts and minimum of maintenance. This type of motor is mainly used in applications requiring quick stop and positive action and stand still like conveyors, gear reducers, machine tools etc. The motor used in our project is

1.5 HP with a rotational speed of 0.5 rpm as per our application.

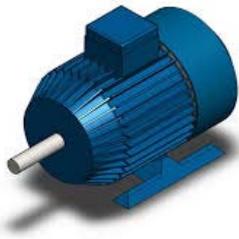


Figure 4 : Brake Motor

d) **Gear Box**:-The gear box used in our project work is a BOX type 5 inch worm and worm wheel gear box. It comprises of series of worm gear units made with die cast aluminium housing from size 25 upto 90 and cast iron for the size 110, 130, & 150. Two taper roller bearings are mounted on the worm shaft improving the mechanical resistance to the axial thrust generated by the worm wheel. The housing has been designed using parametric 3-D CAD software supported by symmetric analysis of the thermal dissipation capacity and structural resistance to deformation under the effect of working loads. The housing has been optimized to maximize the draining of water or liquid in the event of gear box being subjected to splashing or washing, thanks to the adoption of auto lubricated bearings on the output gear.

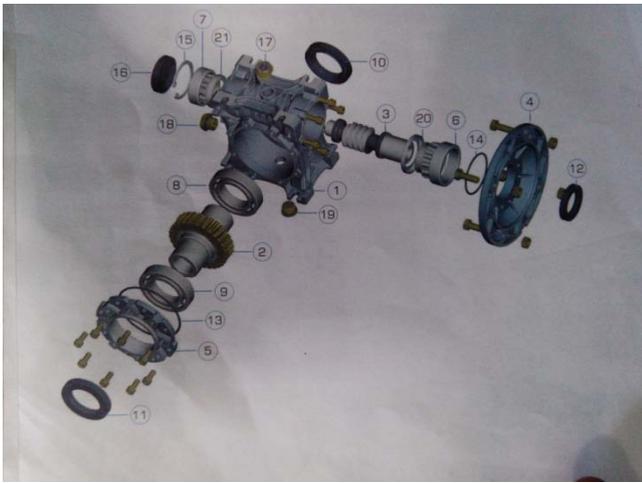


Figure 5 : Exploded view of Gear Box

e) **Bearing** :- Bearing is a machine element that constraints relative motion and reduces friction between moving parts to only the design motion. The design of bearing provides free linear of the moving part or free rotation around the fixed axis. Bearing used in our project is single deep groove bearing no. 6206 having a basic static capacity of 1000 Kgf and basic dynamic capacity of 1.30 Kgf. The maximum rotational speed for the bearing is 13000 rpm.

f) **PLC** :- The main concept of this research is implementation of a control system, by using an intelligent device, which controls the fixture so that manipulation of job becomes easy. A Programmable Logic Controller, PLC, is an electronic device used for Automation of industrial processes, control of machines and automation of factory assembly lines implying that PLC is an industrial computer which has multi-purpose use in order to handle complex parts and processes safely [3].

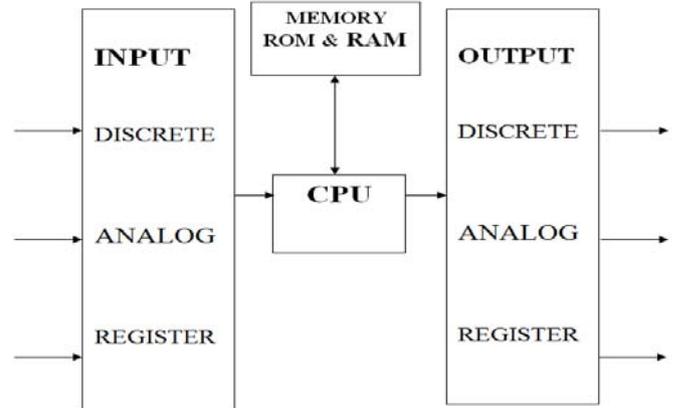


Figure 6: PLC

g) **Drive unit**:- The entire unit including the gear box, brake motor, shaft and the bearing mounting with the shaft is called drive unit. This entire unit is used to rotate the shaft with the help of gear mechanism according to our requirements. In order to improve the efficiency of the drive it needs to be regularly maintained.

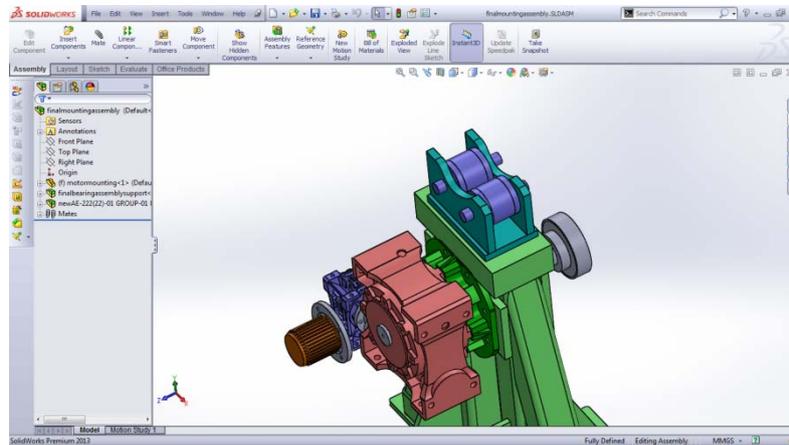


Figure 7 : Drive Unit

f) *Motor mounting:* - The entire drive unit is placed on this mounting. Its unique design plays a crucial role in reducing the weight of the entire assembly. The roller

support is mounted on the mounting assembly and the drive unit is attached to its side.

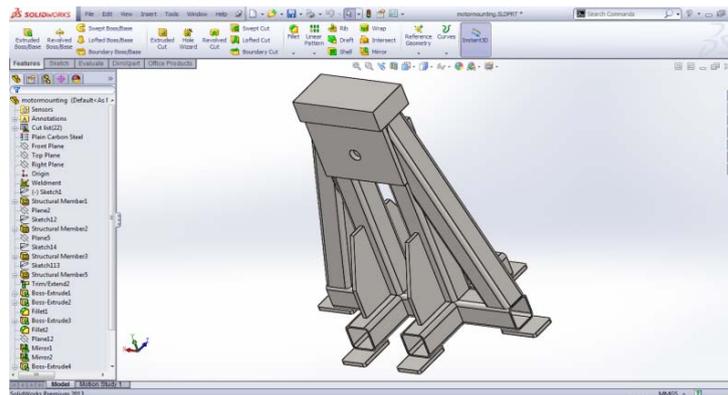


Figure 8 : CAD Model of Motor mounting



Figure 9 : Motor mounting

g) *Shaft support:* - For frictionless shaft rotation there is a specially designed shaft support. It mainly consists of the use of bearings. This results in point contact between the shaft and the bearings, thus

maintaining a firm support for the shaft movement. Mostly, temporary support is not adopted, while in others it becomes essential to protect the crew and equipment from any side fall.

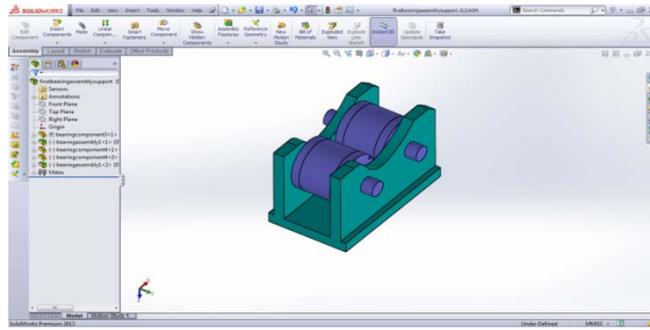


Figure 10 : Shaft Support

h) *Duct*: - In order to carry the electrical wires and other appliances for purposes of lighting specially designed pair of duct is used as a protective

covering. The duct size is 300x200x6 mm which is assembled four in a number.

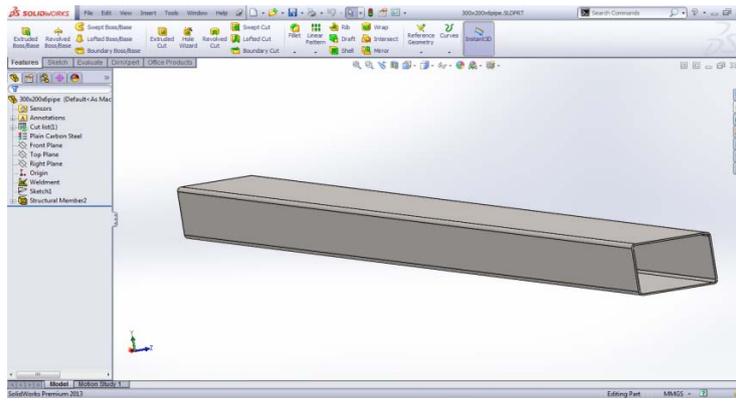


Figure 11 : Duct

i) *Supporting Components*: - These components are not considered as the main parts of the design but still they play a very important role in avoiding the falling of the main component that is the rooftop.

When the entire assembly is turned by the manipulator, the rooftop is supported by these components so that welding operation can be carried out easily and safely.

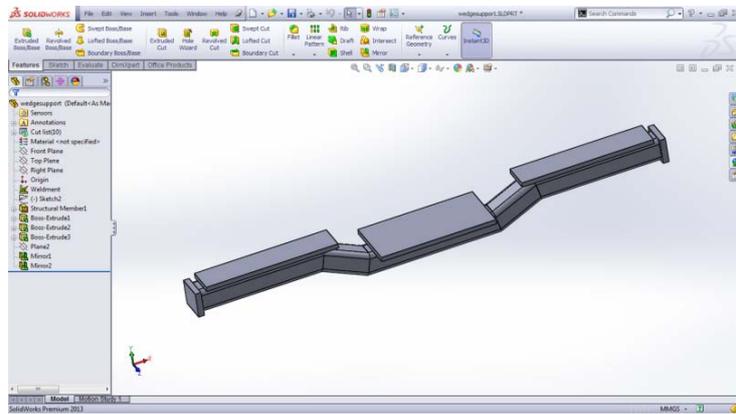


Figure 12 : Duct Supporting Component

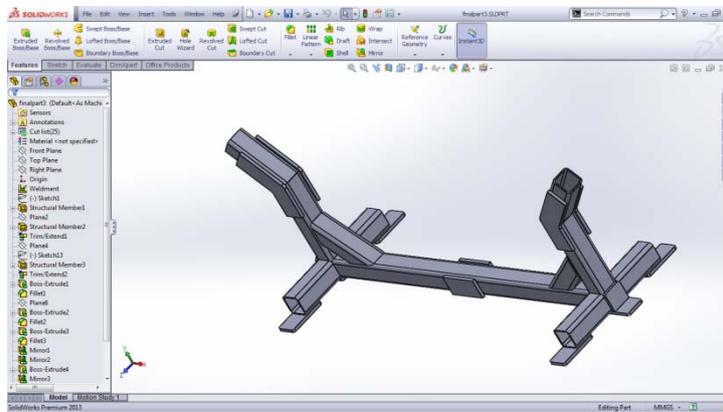


Figure 13 : Duct Supporting Assembly

j) *Actual rooftop:* - It basically consists of four components each having a specific dimension which is altogether assembled as one part of the entire rooftop assembly. Another pair of the rooftop

is similar but having different dimensions. Though the design is complicated, error while manufacturing will not be tolerated.

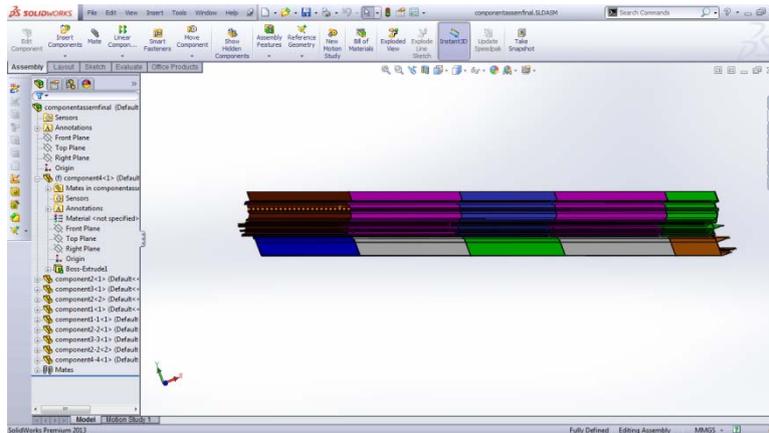


Figure 14 : CAD Model of a Rooftop

k) *Final Assembly:* - Based on the above design of the components, various components are assembled together in order to design the entire assembly which is further used for manufacturing.

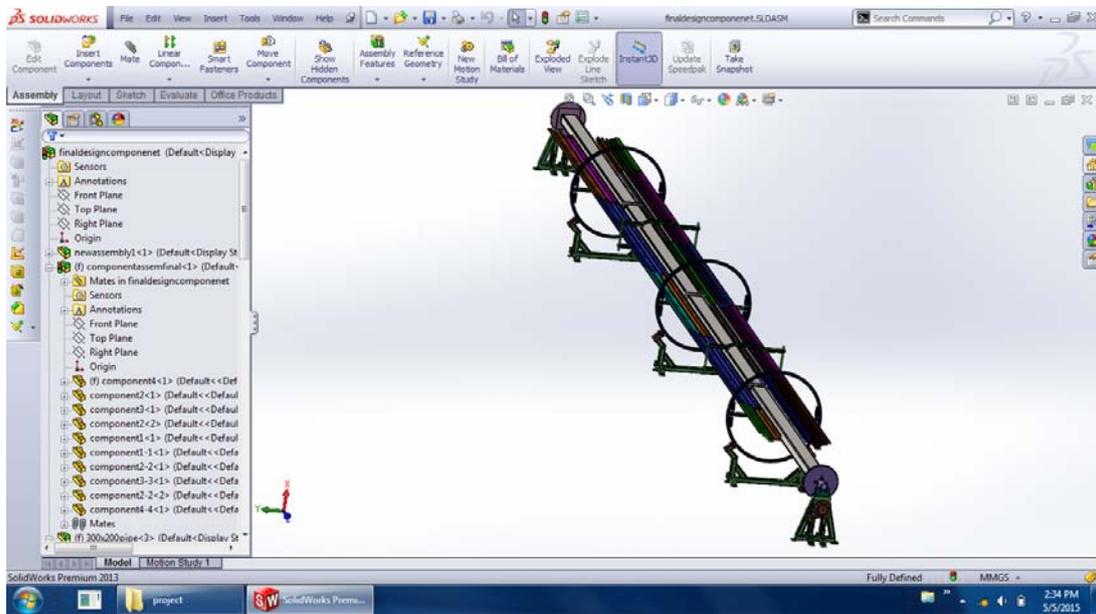


Figure 15 : CAD Model of assembly

III. DESIGN PROCEDURE

Before starting with the designing of the component there are rules which we followed which are:-

1. Compare the cost of production of work with present tools with the expected cost of production, using the tool to be made and see that the cost of buildings is not in excess of expected gain.
2. Decide upon locating points and outline clamping arrangement Make all clamping and binding devices as quick acting as possible
3. Make the jig fool proof Make some locating points adjustable Avoid complicated clamping arrangements
4. Round all corners
5. Provide handles wherever these will make handling easy
6. Provide abundant clearance
7. Provide holes on escapes for chips Locate clamps so that they will be in best position to resist the pressure of the cutting tool when at work
8. Place all clamps as nearly as possible opposite some bearing point of the work to avoid springing action Before using in the shop, test all jigs as soon as made

The complete planning, design and documentation process for a fixture can be carried out systematically in 3 phases based on application which are design pre planning, fixture design, and design approval[4].

The steps considered during designing are as follows:-

- Analytical design for fixture.

- 3 - D Modeling in SOLIDWORKS Wildfire 5.0
- Fixture assembly.

a) Analytical design for fixture

It includes the design of base plate, base vblock, threaded block, supporting v-block, clamp, hexagonal bolt with washer, supporting pin.

b) 3D Modelling in SOLIDWORDS

It includes generation of 3D models of all part details of the fixture like base plate, blade, shim, spacer, bolts, riser, etc.

c) Fixture assembly

It includes assembly of all the parts of the fixture step by step.

IV. DESIGN CALCULATIONS

a) Theoretical design calculation of duct

To calculate deflection of duct having rectangular cross section when subjected to full loading condition :

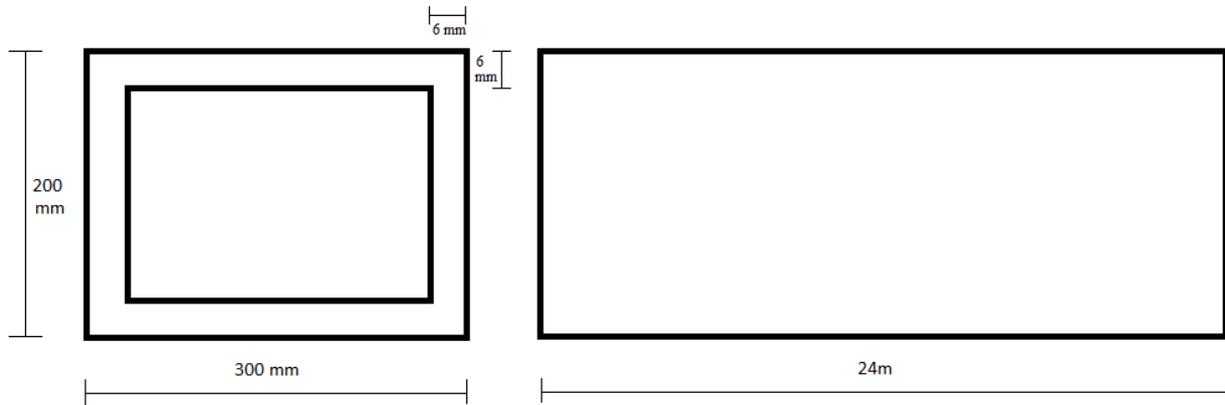


Figure 16 : Rectangular Cross Section of duct

For Figure 24, Moment of Inertia can be determined by,

$$I_{yy} = (b_1 h_1^3 - b_2 h_2^3) / 12$$

From Figure 24,

$$b_1 = 200 \text{ mm} \quad ; \quad h_1 = 300 \text{ mm}$$

$$b_2 = (200 - 12) = 188 \text{ mm} \quad ; \quad h_2 = (300 - 12) = 288 \text{ mm}$$

Substituting above values in moment of inertia formula,

$$\begin{aligned} I_{yy} &= [b_1 h_1^3 - b_2 h_2^3] / 12 \\ &= [(200 * 300^3) - (188 * 288^3)] / 12 \\ &= 75756672 \text{ mm}^4 \\ &= 7.57 * 10^5 \text{ m}^4 \end{aligned}$$

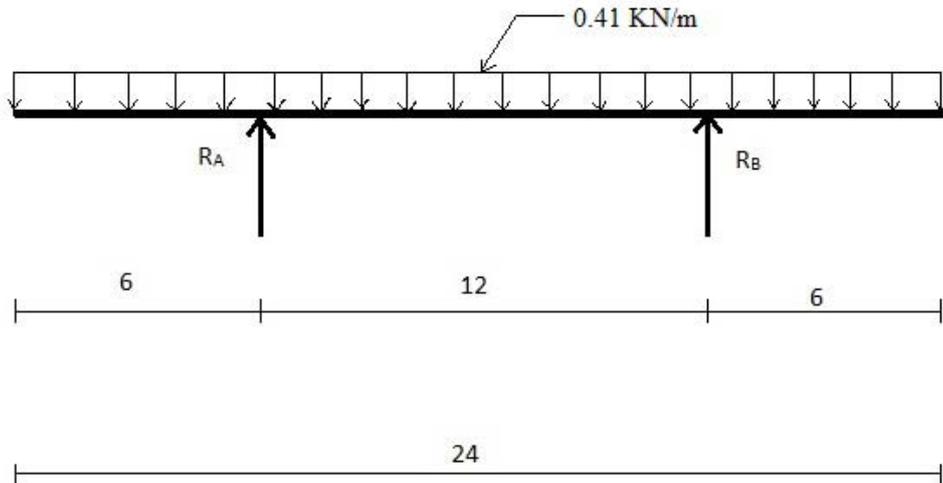


Figure 17 : FBD of Duct of 24 m

Total weight on the duct = 1000 kg = 1000 * 9.81 = 9810 N

Considering it as UDL over the span of 24 m length = 9810 / 24 = 0.41 kN/m

From Figure 25,

Considering Forces in x and y directions, we get,

$$R_A = R_B = 9.81/2 = 4.9 \text{ kN}$$

By Macaulay's method,

$$M = EI D^2y/Dx^2$$

$$\Rightarrow EI D^2y/Dx^2 = 4.9 (x) - 0.41 (x) (x/2)$$

Integrating and solving the equation, we get,

$$EI y = 4.9 (x^3/6) - 0.41 (x^4/24) + C_1x + C_2$$

Boundary Conditions,

$$\text{At } x = 0 \quad ; \quad y = 0$$

$$x = 12 \quad ; \quad y = 0$$

Now Substituting the following boundary conditions in the above equation and solving it, we get,

$$C_1 = -88.08 \quad ; \quad C_2 = 0$$

So, the final equation becomes,

$$EI y = 0.8166 x^3 - 0.017 x^4 - 88.08 x$$

Where, E = $210 * 10^9 \text{ N/m}^2$
 I = $7.57 * 10^{-5} \text{ m}^4$

calculated is finalized or changed based on the difference between two values. Two conditions are considered based on which analysis is done which are:-

Therefore,

Deflection, $y = 23.5 \text{ mm}$ (downward)

b) *Verification of calculation in Ansys*

In order to verify the calculations, analysis of duct is carried out in Ansys so that the deflection

i. *Undeformed condition*

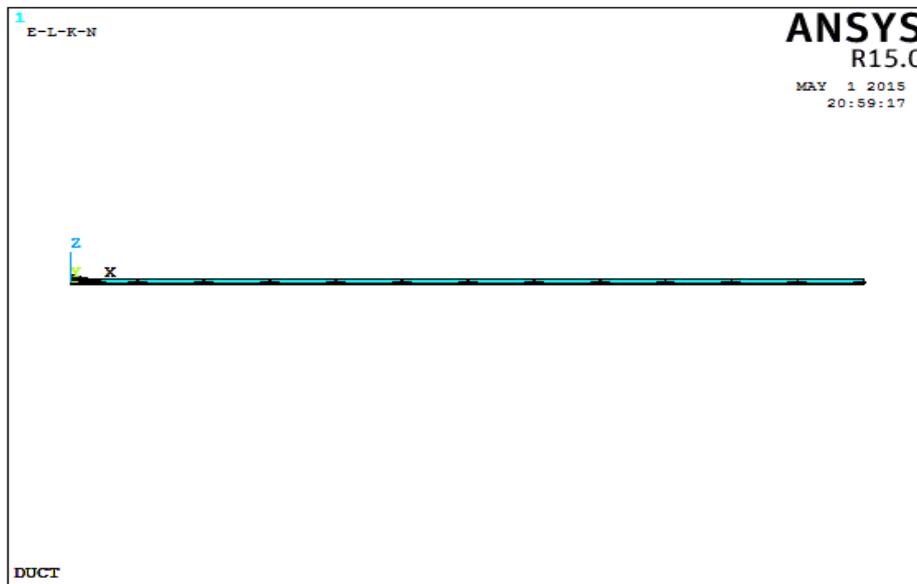


Figure 18 : Undeformed Duct without forces

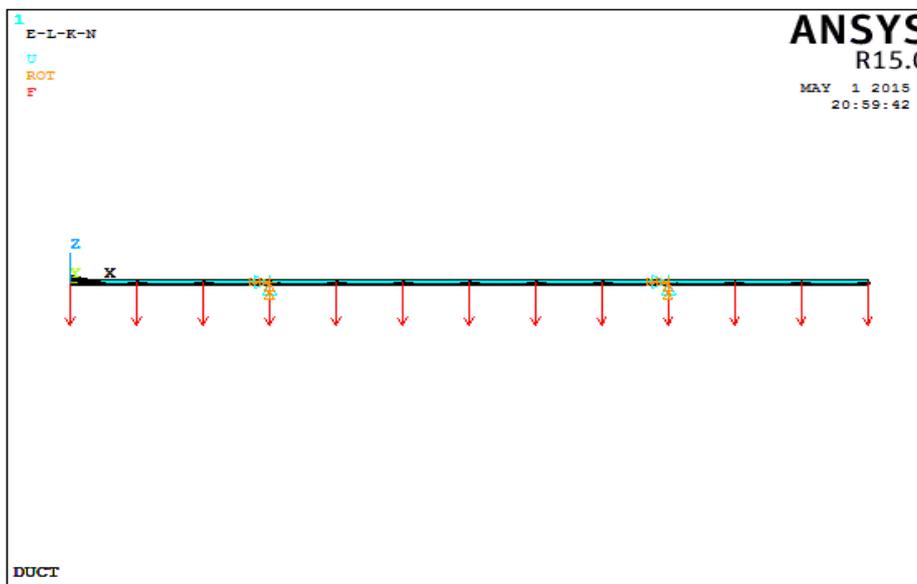


Figure 19 : Undeformed Duct with forces

ii. Deformed Condition

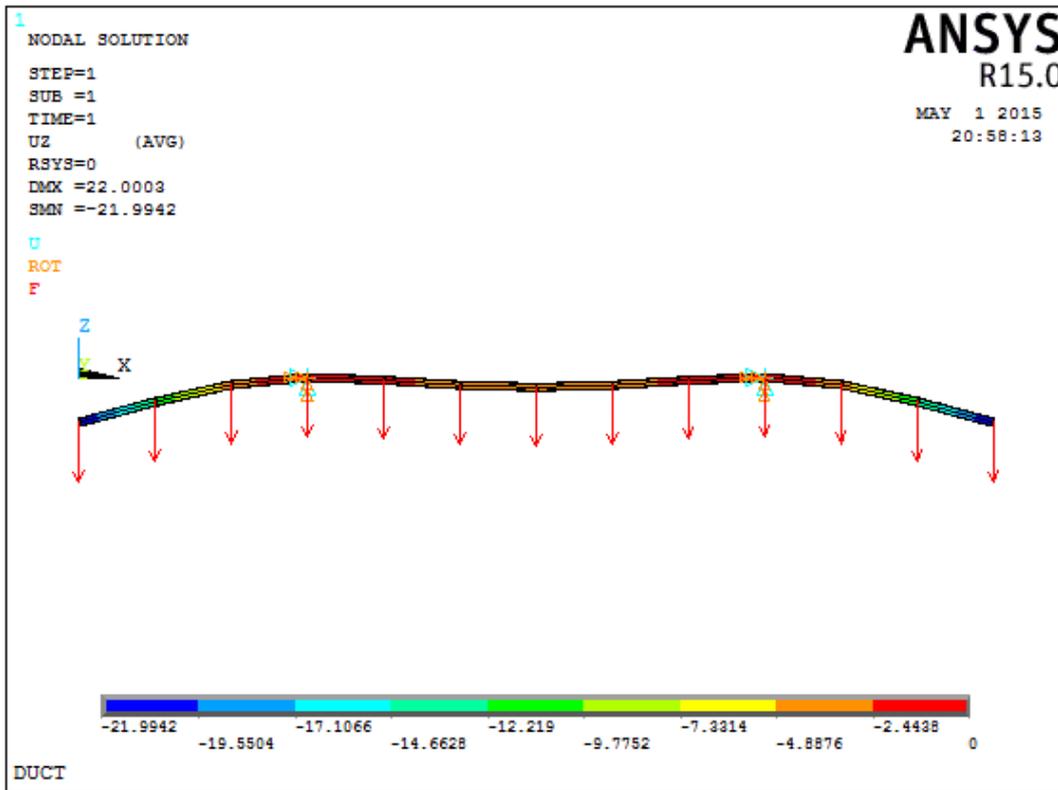


Figure 20 : Deformed Duct

Maximum deflection of duct = 21.9942 (Downward)

c) Calculations of Spur gear

For the given pair of spur gear,
Pitch Circle Diameter (P.C.D.) of pinion, $d_p = 150\text{mm}$
Pitch Circle Diameter (P.C.D.) of gear, $d_g = 700\text{mm}$

Based on standard selections, Standard Module, $m = 6\text{mm}$ for gear pair
From the above information we can calculate the following parameters :-

- 1) Width (b) = 10m = $10 * 6 = 60\text{mm}$
- 2) Teeth of pinion (Z_p) = $d_p / m = 150/6 = 25$
- 3) Teeth of gear (Z_g) = $d_g / m = 700/6 = 117$
- 4) Center distance (C.D) = $(d_p + d_g) / 2 = (700 + 150) / 2 = 425\text{mm}$
- 5) Addendum (h_a) = 1m = $1 * 6 = 6\text{mm}$
- 6) Dedendum (h_i) = 1.25m = $1.25 * 6 = 7.5\text{mm}$

Now, Check whether Pinion or Gear is weaker
Ultimate tensile strength for Pinion, $(S_{ut})_p = 600\text{ MPa}$
for Gear, $(S_{ut})_g = 300\text{ MPa}$

Deformation Factor (c) = 11000 N/mm^2 ;
Power P = 7.5 KW;
Factor of safety, FOS = 2.5;
Sum of errors between meshing teeth (e) = 7.3 microns;
Velocity factor = $6 / (6 + V)$; Lewis factor = $0.484 - 2.87 / z$;
Thus,
 $(\sigma_b)_p = (S_{ut})_p / 3 = 600 / 3 = 200\text{ MPa}$

$$(\sigma_b)_g = (S_{ut})_g / 3 = 300 / 3 = 100 \text{ MPa}$$

Lewis form factor is

$$Y_p = 0.484 - 2.87 / 25 = 0.3692$$

$$Y_g = 0.484 - 2.87 / 117 = 0.46$$

Now,

$$(\sigma_b)_p * Y_p = 200 * 0.3692 = 73.84 \text{ MPa}$$

$$(\sigma_b)_g * Y_g = 100 * 0.46 = 46 \text{ MPa}$$

As $(\sigma_b)_p * Y_p < (\sigma_b)_g * Y_g$, gear is weaker than pinion in bending. So, the design is required based on gear.

$$\text{Beam Strength of gear, } F_b = (\sigma_b)_g * Y_g * b * m = 46 * 60 * 6 = 16560 \text{ N}$$

$$\text{Effective load on gear pair, } F_{\text{eff}} = (K_a * K_m * F_t) / K_v$$

$$\text{As } V = \pi d_p N_p / 60 = (\pi * m * Z_p * N_p) / 60$$

$$= (3.14 * 6 * 25 * 1440) / (60 * 10^3)$$

$$= 11.304 \text{ m/sec}$$

$$\text{Tensile Force, } F_t = P / V = 7500 / 11.304 = 663.48 \text{ N}$$

$$K_v = 6 / (6 + V) = 6 / (6 + 11.304) = 0.3467$$

$$K_a = 1.56 \text{ and } K_m = 1 \text{ (assume)}$$

Therefore,

$$F_{\text{eff}} = (K_a * K_m * F_t) / K_v = (1.56 * 1 * 663.48) / 0.3467 = 2985.373 \text{ N}$$

Dynamic Load by Buckingham's Equation :-

$$F_d = [21V(\text{Ceb} + F_t)] / [21V + (\text{Ceb} + F_t)^{(1/2)}]$$

$$\Rightarrow F_d = [21 * 11.304(11000 * 7.3 * 10^{-3} * 60 + 663.48)] / [21 * 11.304 + (11000 * 7.3 * 10^{-3} * 60 + 663.48)^{(1/2)}]$$

$$\Rightarrow F_d = 3631.97 \text{ N}$$

Design safety :-

$$F_{\text{eff}} = (F_t)_{\text{max}} + F_d = K_a * K_m * F_t + F_d$$

$$\Rightarrow F_{\text{eff}} = 1.56 * 1 * 663.48 + 3631.97$$

$$\Rightarrow F_{\text{eff}} = 4667 \text{ N}$$

$$\text{Therefore, FOS} = F_b / F_{\text{eff}} = 16560 / 4667 = 3.5483$$

As available FOS of gear pair is higher than the required FOS; Design of gear pair is safe.

$$\text{Surface Hardness, } F_w = d_p * b * Q * K$$

$$\text{But, } d_p = 150 \text{ mm ; } b = 60 \text{ mm}$$

$$Q = 2Zg / (Z_g + Z_p) = (2 * 117) / (25 + 117) = 1.648$$

$$\text{Assume, } K = 0.16 * (\text{BHN} / 100)^2$$

$$F_w = 150 * 60 * 1.648 * 0.16 * (\text{BHN} / 100)^2$$

$$\text{But, } F_w = \text{FOS} * F_{\text{eff}}$$

$$\text{Hence, } 2373.12 * (\text{BHN} / 100)^2 = 2.5 * 4667$$

$$\text{BHN} = 221.7322$$

V. VARIOUS PROCESSES AND MACHINES USED FOR OUR COMPONENT

- **Gas cutting:** - Oxy-fuel cutting is a process that uses fuel gases and oxygen to weld and cut metals, respectively. Pure oxygen, instead of air, is used to increase the flame temperature to allow localized melting of the workpiece material (e.g. steel) in a room environment. A common propane/air flame burns at about 2,000 °C (3,630 °F), a propane/oxygen flame burns at about 2,500 °C (4,530 °F), and an acetylene/oxygen flame burns at about 3,500 °C (6,330 °F).

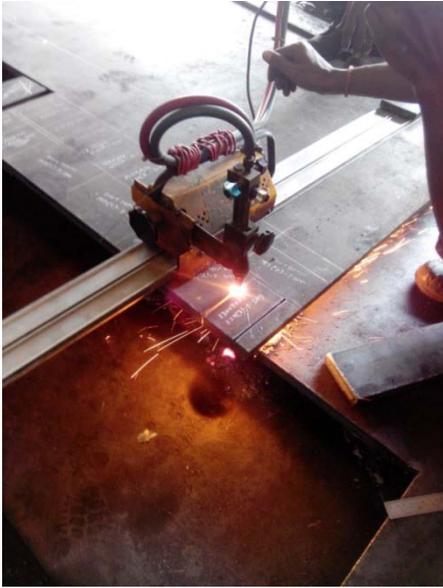


Figure 21 : Gas Cutting Process

- **Arc welding:** -Arc welding is a type of welding that uses a welding power supply to create an electric arc between an electrode and the base material to melt the metals at the welding point. They can use either direct (DC) or alternating (AC) current, and consumable or non-consumable electrodes. Each weld on any component is welded using a specific welding process with the aid of highly focused electrode shielding gas, largedegree of control the welder has over the heat intensity leads to production of very strong and consistent welds [6].
- **Special purpose machine:** -Special purpose machines are designed to perform some specific applications which cannot be carried out using conventional machines. In our company the SPM is of the company SCHARMANN is used mainly for job setting and machining the components using operations like sizing, drilling, rimming, boring, finishing etc.



Figure 22 : Special Purpose Machine

- **Vertical machining center:** - VMC used in our company is of the Hartford Company. It is very costly but serves its purpose to the fullest. Being economical it is widely used for large scale production of components. It is basically constituted of three components- the monitor where program is fed, keypad for feeding the program and the control panel for controlling the feed rate, RPM, start and stop of machine. For the machining purpose following are the codes which are written:-

a) Drilling



Figure 23 : G-code for Drilling

b) Interpolation

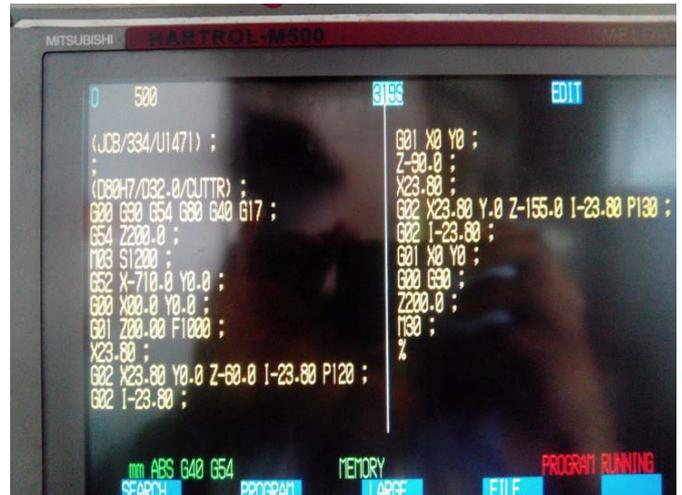


Figure 24 : G-code for Interpolation

c) Milling



Figure 25 : G-code for Milling

VI. MANUFACTURING PROCEDURE

The actual manufacturing phase which plays a very important role is mainly classified into three categories:-

- **Fabrication:** Metal fabrication is the building of metal structures by cutting, bending, and assembling processes. This stage plays a very simple but a crucial role. Fabrication shops and machine shops have overlapping capabilities, but fabrication shops generally concentrate on metal preparation and assembly as described above. By comparison, machine shops also cut metal, but they are more concerned with the machining of parts on machine tools.
- **Machining:** Machining is any of various processes in which a piece of raw material is cut into a desired final shape and size by a controlled material-removal process. The three principal machining processes are classified as turning, drilling and milling. Other operations falling into miscellaneous categories include shaping, planing, boring, broaching and sawing
- **Assembly:** Component or end item comprising of a number of parts or subassemblies put together to perform a specific function, and capable of disassembly without destruction. It is the last stage of manufacturing but very difficult requiring high precision and accuracy. Successful fixture designs begin with a logical and systematic plan. With a complete analysis of the fixture's functional requirements, very few design problems occur. When they do, chances are some design requirements were forgotten or underestimated. The workpiece, processing, tooling and available machine tools may affect the extent of planning

needed. Preliminary analysis may take from a few hours up to several days for more complicated fixture designs. Fixture design is a five step problem-solving process.

The manufacturing process which we selected must be an economical balance of materials, manpower, product design, tooling and manpower, plant space, and many other equipment factors influencing cost and practicality.

a) *Our Basic Aim for Manufacturing the Assigned Fixture was*

1. Using Materials More Economically
2. Eliminating Operations
3. Selection of Proper Tooling
4. Minimum Cost Analysis

In minimum cost studies, it is found that when changes occur in a common variable (In this case it is operational speed), the change may modify other cost aspects of the problem in such a way that the combined problem effect produces a minimum value.



Figure 26 : Milling Machine

b) *Component Fabrication*

Precision cutting and forming of sheet metal is utilised for manufacture of superstructures including drivers cab engine hoods, and compartments for housing electrical equipment. All activities connected with pipes like pickling, bending, cutting, forming and threading of pipes of various sizes are undertaken in another well-equipped work area.

All electrical equipment is assembled in the fabricated control compartments and driver's control stands are done in another work area.

c) *Under frame Fabrication*

Under frames are fabricated with due care to ensure designed weld strength. Requisite camber to the under frame is provided during fabrication itself. Critical welds are tested radio-graphically. Welder training and their technical competence are periodically reviewed.

High Horse Power (HHP) under frame is fabricated using heavy fixtures, positioners to ensure down hand welding.

VII. RESULTS

From the above design calculations the type of gear which we have chosen is spur gear because it has proportional Brinell hardness number, high power transmission efficiency, highly reliable and unlike belt drives have no slip condition.

From the above bending condition the design of duct is not suitable, so it is required to take a plain rectangular duct with square cross section in order to reduce the bending below 10mm. By changing the

cross section the inertia will change leading to decrease in the deflection. Thus it is advisable to design a duct 100*100mm with 8mm thickness and 6mm chamfer.

Bearing selection also plays a very important role and based on our application it is highly recommended to select single row deep groove ball bearing as they can sustain some axial load in either direction as well as radial loads, and the two raceway cross-sections are simple circular arcs which can be very precisely finished so that the bearings have low friction and very little noise or vibration. Several different cage designs are available with different characteristics and the choice depends upon the individual application.

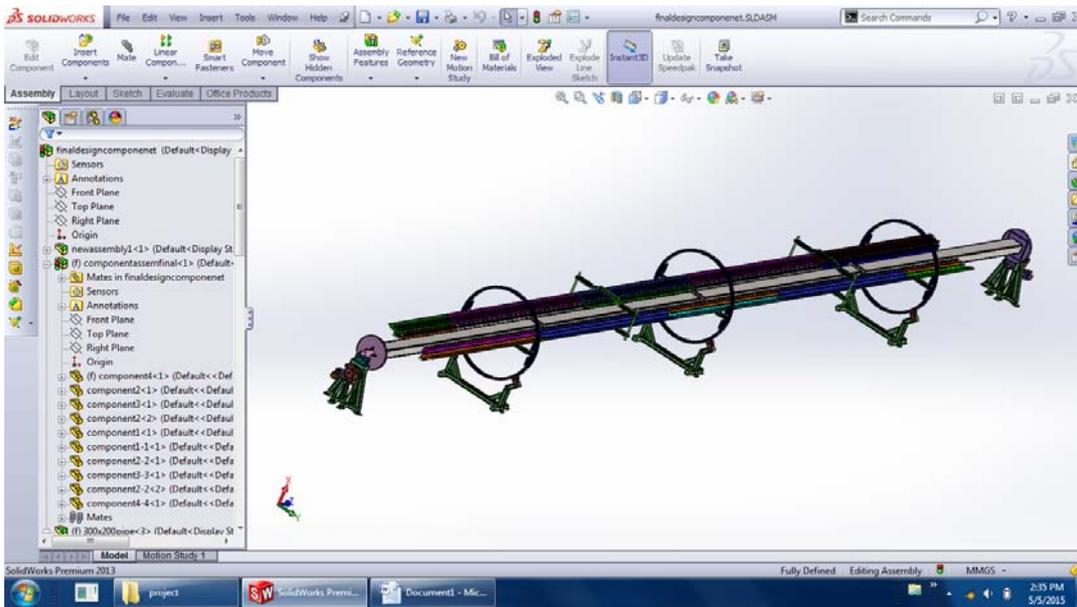


Figure 27 : Final assembly of fixture

VIII. ACKNOWLEDGEMENT

Inspiration and guidance are invaluable in every aspects of life, especially in the fields of academics, which we have received from our company. We would like to thank them as they are responsible for the complete presentation of our project and also for the endless contribution of time, effort valuable guidance and encouragement given by professor S.N.Shindeto project work.

IX. CONCLUSION

Conclusion is drawn on the basis of the information collected on each aspect of our project. It leads to a belief that if applied will create an even better machine than we have designed. The process of conducting operations related to welding fixtures and positioners helps in gaining a deeper understanding as well as effective project process. From finding a resource for research material to design updates of the

part causes the task of accurately prototyping the real design difficult. It is important that the design satisfies all of the functional requirements and design parameters which were outlined at the start of the project. In order to meet the requirements of the fixture customization is done by making the clamping system very practical for various sizes and geometries. By also knowing the material selection a cost benefit analysis could be conducted to determine how cost effective the product is.

Design data handbooks detail mechanical component design analysis with sufficient information provided regarding material specification, properties, requirements for design, etc. This facilitates designers to apply their exact requirements and choose from available resources. Also, verification with the design data books allows one to confirm that correct procedures are being followed. Similarly, the idea behind the preparation of a guide for fixturing as undertaken in this project is to develop a guide that

could be used as a ready reference while designing jigs and fixtures. This project represents the first phase of designing a comprehensive roadmap for fixture design, to assist Tinker Engineers, designers and shop supervisors alike, as well as sub-contractors.

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Evaluation of Parametric Control for Machining with WEDM and Machinability Index

By Perla Sreenivasa Rao & Dr. K. Ravindra

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Abstract- The present research work is intended to optimize the machining parameters for achieving high dimensional accuracy in wire electric discharge machining (WEDM). Experiments were designed and carried out to evaluate the best parametric setting which gives parameters like power, spark gap and corner radius using Inconel X-750 as workpiece material. These parameters are determined for a wide range of job thickness and mathematical correlations were developed for the parameters such as power and spark gap. Analysis of variance (ANOVA) is also performed to study the fitness. This procedure eliminates the need for repeated experiments which saves time and material unlike conventional machining process. The primary objective of the study is to find out the important and combination of one or more factors that influence the machining process in order to achieve the best power setting in turn machining current. Also, Machinability index of various materials which can be machined by WEDM is evaluated by referring to the present research work and literature review.

Keywords: *wire electrical discharge machining, ferrous and non-ferrous materials, aviation materials, parameters, machinability index.*

GJRE-A Classification : FOR Code: 290501



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Evaluation of Parametric Control for Machining with WEDM and Machinability Index

Perla Sreenivasa Rao ^α & Dr. K. Ravindra ^σ

Abstract- The present research work is intended to optimize the machining parameters for achieving high dimensional accuracy in wire electric discharge machining (WEDM). Experiments were designed and carried out to evaluate the best parametric setting which gives parameters like power, spark gap and corner radius using Inconel X-750 as workpiece material. These parameters are determined for a wide range of job thickness and mathematical correlations were developed for the parameters such as power and spark gap. Analysis of variance (ANOVA) is also performed to study the fitness. This procedure eliminates the need for repeated experiments which saves time and material unlike conventional machining process. The primary objective of the study is to find out the important and combination of one or more factors that influence the machining process in order to achieve the best power setting in turn machining current. Also, Machinability index of various materials which can be machined by WEDM is evaluated by referring to the present research work and literature review. The index may be useful to the fraternities like industry and academia in determining the best cutting parameters that are to be set on the machine. The best parameters evaluated out of this study, will be useful while setting up the machine which avoids trial and error method and also aids in process planning.

Keywords: wire electrical discharge machining, ferrous and non-ferrous materials, aviation materials, parameters, machinability index.

I. INTRODUCTION

Worldwide industry acceptance has brought revolutionary changes in bringing the Wire electrical discharge machines (WEDM) into the shop floors which is an unconventional production process thus manufacturing the components with a complex geometry.

The material is removed from a workpiece by creating a series of rapidly recurring electric current

discharge (thousands of sparks) between the cutting tool and workpiece, immersed in a non-conductive fluid called dielectric.

The wire used for machining is also called as a tool/electrode and is made of copper, brass, tungsten or brass coated of diameter varying from 0.03 to 0.30mm.

A constantly moving wire fed from a spool is subjected to a high tension with the help of an advanced tension servo control mechanism shall results in producing precision components of extremely complex shape and desired profile.

The WEDM can be deployed to machine the materials that are hard to machine such as high strength and temperature resistive materials (HSTR). Also, the components manufactured out of Wire EDM would be free from the geometrical changes as there won't be any mechanical stresses developed during the machining. The dimensional accuracy can be achieved even in the case of machining the heat treated materials regardless of the hardness. Hard or difficult to machine materials are also can be machined using the WEDM.

The mechanical stresses that are developed during the machining process would be eliminated as there would not be any direct contact between workpiece and the tool. It may be observed that the material is eroded ahead of the wire travel.

The first commercially NC machine was built and introduced to the manufacturing industry in the late 1960s. The WEDM process was developed as a result of quest of a technique to replace the machined EDM electrode. D.H. Dulebohn has automated the WEDM process and controlled the shape of the machined components with the help of optical-line follower technique in 1974. The process has become very popular by the year 1975 and by then the industry has good understanding and knowledge about various capabilities of WEDM. Later, it was observed that there was rapid growth in deploying the WEDM machines in the manufacturing segment.

The first CNC EDM was fabricated in late 1970s which has brought a major evaluation of the machining processes.

As a result, the wide range of capabilities of the WEDM process were significantly implemented for any

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through hole machining owing to the wire, which has to pass through the component to be machined. The WEDM applications includes Prototype production, die making, closed loop manufacturing, metal disintegration machining, Extrusion Dies, Fixtures and Gauges, Form tools and inserts, Bio-Medical applications, Aerospace, defense and electronic parts. Limited varieties of composites and ceramics also can be machined using WEDM. Fig.1. shows the schematic view of the process.

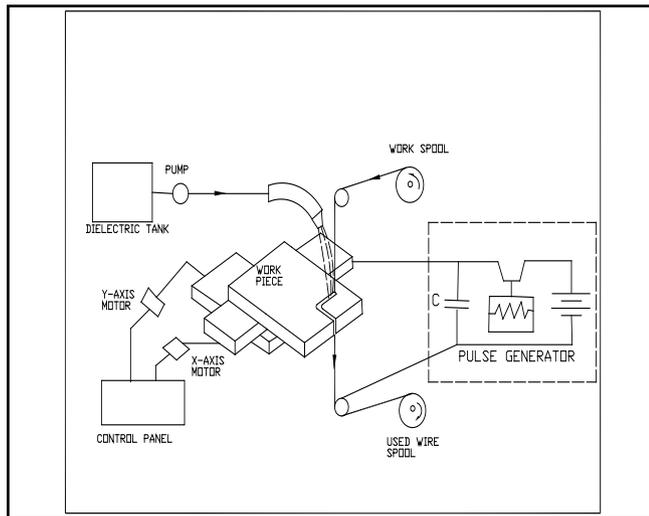


Figure1 : Wire electrical discharge machining Process

WEDM removes material with the help of a storage capacitor by releasing a series of discrete electrical discharges (transient sparks over a shorter duration). The erosion takes place when the capacitor starts discharging an electrical current through an accurately positioned and constantly moving wire (tool/electrode) and the workpiece (anode). A narrow gap is maintained between the tool and cathode through an insulated medium (dielectric fluid). A microprocessor embedded with the WEDM machine maintains a constant narrow gap varying from 25 to 50 microns between the electrode and workpiece.

When the wire approaches close to the workpiece, the controlled electrical discharges creates a concentrated spark that helps melting down the required portion of material into vaporized tiny particles during the erosion process.

The workpiece is totally submerged in dielectric fluid which would help in maintaining constant temperature and also flushes away the debris after erosion. Flushing mechanism plays a vital role when there is a change in thickness of the workpiece.

The flushing mechanism even aids in cooling down the workpiece after erosion and surrounding environment handling huge temperature range of 10000°C. The volume of the material removed per spark may be 10-6 mm³ approximately.

WEDM does not require customized form or a shaped electrode as there is only a wire used as a tool

which saves investment of resources like cost, time and money. Unlike traditional machining, the WEDM process eliminates use of different electrodes for rough and finish operations. Sometimes, the finish operation may demand multiple passes along the profile/shape to be created.

WEDM can achieve exceptionally high dimensional accuracy as it uses a thin and continuous wire feeding through the workpiece and enables the production of parts particularly a complex shape.

Surface finish quality depends on the amount of electrical discharge energy and also relates to the intensity and duration of the spark plasma. Decrease in both pulse duration and discharge current may influence Surface finish, cutting speed and MRR.

Machining Parameters influencing the WEDM process Discharge Current, Gap Voltage, Pulse parameters like pulse frequency and duration, Conductivity, flow rate and flushing pressure of dielectric fluid, dielectric flushing pressure, wire size, material, speed and tension, thickness, melting point, material of workpiece etc.,

a) Experimental Set-Up

The experimental studies were performed on a Wire EDM machine of make ULTRACUT 334.

A brass wire of 250 microns diameter is used as a tool-electrode with a wire tension of 70N at a velocity of 3.4 m/min. Inconel X-750 is used as a workpiece material for conducting the experimentation. As per DIN 160 standards, the preferred mechanical strength of the brass alloy wire opted for the experimentation is of 900 N/mm² with a composition of CuZn36.

Deionized water with a dielectric conductivity of a value of 38 mhos is used as a Dielectric medium for the present study. A range of 30 to 90 Volts has been set as a gap voltage. The optimum values were obtained at 80 Volts.

Experimental investigation was done to find out the influence of the current with respect to the parameters like varying workpiece thickness, spark gap and the geometry. Workpiece thickness of Inconel X-750 material used was varying from 5 to 80mm material.

As shown in Fig.2, an "L" shaped cut was performed to measure the corner radius with respect to the current value and also another slot of 30mm length has been cut to measure the slot width. Series of experiments were carried out varying the workpiece thickness starting from 5 to 80 mm with an increment of 2.5mm or 5mm as convenient. A total of 20 experiments were conducted in the present research work.

Necessary care was taken to achieve high cutting speed with respect to varying current with a least wire breakage.



Figure 2 : Shape of the slots machined

The instrument, Nikon OPTOMECH-Rapid-optical microscope with a 100X magnification is used for measuring the workpiece after cutting. Necessary parameters related to corner geometry were recorded and tabulated for quick reference.

The spark gap can be derived using the equation $W = d + 2 * Sg$ Where W = Slot width, d = Wire diameter and Sg = Spark gap

The variation of power, spark gap and corner radius with respect to change in thickness of workpiece is discussed in this article to derive the best fit curve. Origin 8.0 software tool is being used for the study. The mathematical equations are derived and statistical analysis ANOVA is also performed to calculate the coefficient of variance, R^2 and standard deviation in order to determine the fitness of the curve.

b) Results and Discussions

Fig.3. describes the effect of variation in thickness with respect to the power. The increase in workpiece thickness causes variation in power. It is also observed that the increase in workpiece thickness causes increase in machining current for a specific set of machining conditions.

This phenomenon reveals that the high amount of energy required to machine higher workpiece thickness, the machining can be performed only when the current is increased which involves high amount of power. However, the rate of power change is found decreasing with increasing thickness. This may be due to the limitation of current carrying capacity of the wire electrode.

The plot is useful to determine suitable values like the minimum power required for machining the INCONEL X- 750 workpiece at given thickness with in working range of the select machine.

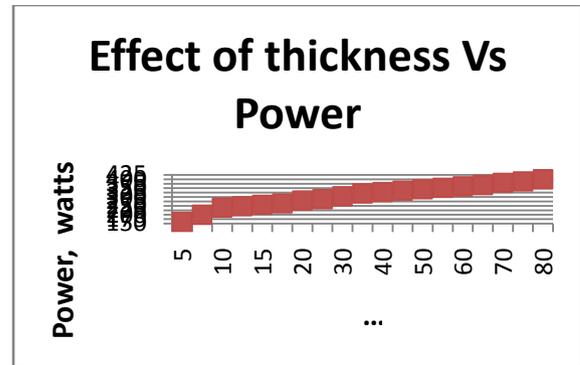


Figure 3 : Effect of Thickness on Power

The power required in turn the machining current can be selected from the plot for a given thickness of the job.

By regression and correlation of the available data, the mathematical expression for the best fit curve is derived as given below.

$$\text{Power (P)} = 400.16 - [80 \times 5107.31 / (1 + \text{exponential of } \{(T+223.8) / 26.3 \})] \quad \text{Eqn. (1)}$$

Fig.4 depicts the trend of variation in spark gap with the increase in workpiece thickness. The plot shows that the spark gap increases with increment in workpiece thickness. The increase in gap may be due to the spark jumping longer because of high energy generated at high current values, is required to machine the job of higher thickness, though the rate of change is proportionate with respect to the job thickness. The best fit curve is plotted and is carried out the statistical analysis (ANOVA).

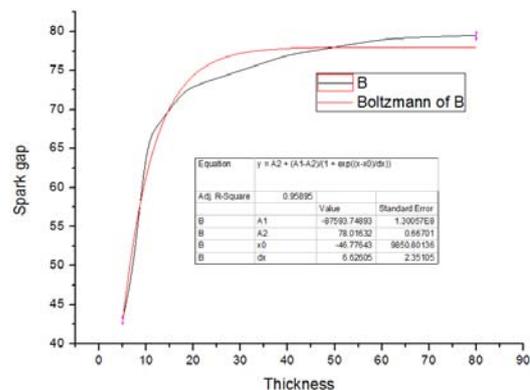


Figure 4 : Effect of Thickness Vs Spark gap

The mathematical relation can be expressed as Spark gap (Sg) = $78.016 - [87671.75 / \{ 1 + \text{exponential of } \{ (T+46.77) / 6.63 \} \}]$ Eqn. (2)

Where Sg in micrometers.

The outcome of statistical analysis gives the value of R-Squared and standard deviation as 0.9657 and 0.2557 respectively. This is useful in finding the spark gap i.e., the cutting width to compute the MRR

and determine the wire offset used while generating a CNC part program and hence high accuracy can be achieved.

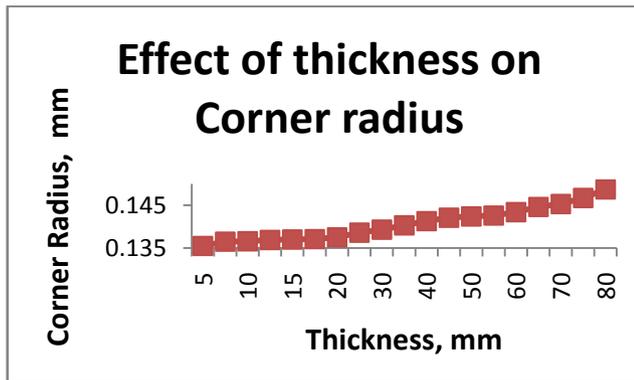


Figure 5 : Effect of workpiece thickness on corner radius

Fig.5. shows the variation in corner radius with the increase in thickness of workpiece. The curve shows an increasing trend in corner radius with increase in thickness of the workpiece. The plot shows that the spark gap increases with increment in workpiece

thickness. The increase in gap may be due to the spark jumping longer because of high energy generated at high current values, is required to machine the job of higher thickness causing deeper cutting, though the rate of change is proportionate with respect to the job thickness. The profile geometry/contour of the corner radius generated can be similar to that of cross-section of the wire used for machining. From the plot, corner radius that can be achieved can be predicted while machining a particular workpiece thickness at optimum cutting parameters. The parameters can be set even for the required corner radius on a given job thickness from the database built while optimizing the parameters.

c) Machinability Index

The data for machining 5mm thick workpieces of Mild steel, HSS, HC-HCr steel, En24 steel, Stainless steel, Copper, Brass, Graphite, Tungsten-carbide and Titanium are adopted from the literature[4, 5, 10-12], and Inconel X-750 are considered from the present research work. The machinability index is calculated for all these materials and tabulated as below.

Table 1: Machinability Index

S.No.	Material, (5mm thickness)	Cutting speed, (mm/min)	Machinability Index
1	Mild steel	3.10	1.000
2	HSS	3.44	1.207
3	HC-HCr steel	2.20	0.752
4	EN24 steel	2.67	0.827
5	Stainless steel	3.00	0.985
6	Copper	2.80	1.253
7	Brass	7.80	2.560
8	Graphite	1.60	0.616
9	Tungsten carbide	1.40	0.474
10	Titanium	4.11	1.412
11	Inconel X-750	3.84	1.324

II. CONCLUSION

The influence of machining parameters like Current and Workpiece thickness with respect to the accuracy criterion such as cutting speed and spark gap are determined. A better control on machining accuracy can be achieved in comparison with earlier researchers by controlling the primary parameter "current" in turn Power. The results are useful in setting up the parameters required for accurate cuts on Inconel X-750 workpieces of any size ranging between 5 and 80mm. The appropriate machining parameters can be chosen depends on the availability of wire-electrodes. The mathematical relation developed and the plots are much more beneficial in estimating the spark gap and also to achieve high cutting accuracy for any given workpiece thickness within the working range of the select machine. The modern industrial applications like tool

and die manufacturing units may make use of these results in order to optimize the use of Wire EDM resources in more efficient manner than the past.

Student fraternity, Researchers, Manufacturing industry can refer the machinability index developed out of this research to have an overall understanding about various challenges like the degree of difficulty or ease while dealing with the machining of different materials.

The findings of the present work will open up new insights into the fundamental and applied researchers in the WEDM area for better understanding of the technology, and also useful to the manufacturing industry and tool rooms for taking up a quantum leap from the present day needs of machining of the conductive materials irrespective of their metallurgical properties.

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A Review of Modelling Techniques for Loading Problems in Flexible Manufacturing System

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Abstract- Though flexible manufacturing systems have promised wide range of benefits but the implementation of FMS has fraught with difficulty as a result of which the implementation rate of FMS is much lower than has been expected. To bridge the gap efforts at global level are carried out widely in today's global and informative world. In the progress, modelling plays a vital role in the design, planning, implementation and operation of FMSs. Models are used widely to provide insight into how the FMS system and its components interact. With time new optimization problems arises in FMS, thus new modelling methods and techniques and updation of the existing needs to be developed time to time. Since the publication of the first articles on the planning problems of FMS's (Stecke Kathryn E. and Solberg James J., 1981)(Stecke, 1983b), much research has been devoted to the solution of these types of problems. The aim of this paper is to review the approaches to model FMS and the solution approaches. A review paper provides basis and direction for future research directions.

Keywords: flexible manufacturing system (fms), loading in fms, modelling of fms, mathematical modelling of fms, artificial intelligence in FMS.

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A Review of Modelling Techniques for Loading Problems in Flexible Manufacturing System

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Abstract- Though flexible manufacturing systems have promised wide range of benefits but the implementation of FMS has fraught with difficulty as a result of which the implementation rate of FMS is much lower than has been expected. To bridge the gap efforts at global level are carried out widely in today's global and informative world. In the progress, modelling plays a vital role in the design, planning, implementation and operation of FMSs. Models are used widely to provide insight into how the FMS system and its components interact. With time new optimization problems arises in FMS, thus new modelling methods and techniques and updation of the existing needs to be developed time to time. Since the publication of the first articles on the planning problems of FMS's (Stecke Kathryn E. and Solberg James J., 1981)(Stecke, 1983b), much research has been devoted to the solution of these types of problems. The aim of this paper is to review the approaches to model FMS and the solution approaches. A review paper provides basis and direction for future research directions. The modelling approaches and techniques in the paper are classified into three categories; hierarchical approach, mathematical modelling and artificial approaches. The solution approaches used are discussed with the modelling approaches respectively. A majority of research paper modelled FMS's, production planning problems, loading problem of FMS as mathematical model. This paper provides insight of different modelling approaches proposed in the literature to tackle the FMS problems during the last few decades.

Keywords: flexible manufacturing system (fms), loading in fms, modelling of fms, mathematical modelling of fms, artificial intelligence in FMS.

I. INTRODUCTION

To satisfy rapidly changing global market and requirements of customer demand, systems needs to be designed to increase flexibility. Flexible manufacturing is the answer to the problem. FMS are as flexible as job shop and as efficient as production lines. Thus FMS are complex and combinational problem, where arises a wide range of problems with its exploration. Prior to start of manufacturing, production planning problems is one among them. FMS planning problems is to decide which cutting tools are to be placed in which tool magazine, to decide when and

which part to be produced and in what quantity, how pooling of the machines and tools has to be done, number and types of fixtures and pallets required and available, number and type of cutting tools available and required, type of operations that can be performed etc. These decisions are to be made before the start of manufacturing. The scheduling problem needs next to be addressed. The five production planning problems mentioned by Kathryn E. Stecke (Stecke, 1983a, 1983b) needs to be solved before solving scheduling problem. Solution of production planning problem is the pre-requisite to solve the scheduling problem. Scheduling is the time table for the machines set up for prescribed production target. Production planning problem needs to be solved to reach the shop floor and scheduling need to be done for actual production to begun.

Depending on the type of the manufacturing problem objectives are defined for problem formulation and optimal solution. The type and number of objective function depends on the type and nature of a particular manufacturing system. One or more objective may be desirable at one or more stage of FMS life cycle, i.e. from FMS conception, design, to scheduling. For handling large number of objectives the weightage factor for each objective needs to be defined to solve the problem. Various modelling techniques for different objectives have been identified and different solution techniques were targeted in the literature.

II. LITERATURE REVIEW OF MODELLING FOR FMS LOADING PROBLEM

A model is a representation of the construction and working of some system of interest. A model is similar to but simpler than the system it represents. A model enables the analyst to predict the effect of changes to the system. A model should be a close approximation to the real system and should incorporate most of its salient features and, it should not be so complex to understand and experiment with. A good model is a judicious trade-off between realism and simplicity. Simulation practitioners recommends for increasing the complexity of a model iteratively. An important issue in modelling is model validity. According to Maria model validation techniques include simulating the model under known input conditions and comparing model output with system output (Maria, 1997). Mathematical programming models, Heuristic

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approaches, Queuing network models, Simulation models etc. have been utilized for modelling various types of complex problems of FMS's. Different modelling methods and approaches used for modelling FMS's, particularly the loading problem of FMS's have been identified and classified pearly reviewed as under.

a) Artificial Intelligence (AI)

AI covers techniques like fuzzy logic, neural networks, and immune algorithms. AI is potentially suitable for complex and ill-defined problem (Kempf, 1985)(Lu, 1986). Loading problems in FMS has been modelled with fuzzy logic by Vidyarthi and Tiwari in 2001 (Vidyarthi & Tiwari, 2001), Chan and Swarnkar in 2006 (Chan & Swarnkar, 2006), Petrovic and Akoz in 2008 (Petrovic & Akoz, 2008) and Rai et al. in 2012 (Rai, Kameshwaran, & Tiwari, 2002), with neural and a fuzzy Petri net by Kumar et al. in 2004 (R. R. Kumar, Singh, & Tiwari, 2004), with artificial immune algorithm by Prakash et al. in 2008 (Prakash, Khilwani, Tiwari, & Cohen, 2008) and with artificial neural network by Kant and Vaishya in 2013 (Kant & Vaishya, 2013).

The FMS problems modelled with AI techniques have been solved with application of fuzzy-logic by Vidyarthi and Tiwari in 2001 (Vidyarthi & Tiwari, 2001), Kumar et al. in 2004 (R. R. Kumar et al., 2004) and Petrovic and Akoz in 2008 (Petrovic & Akoz, 2008), with application of GA by Rai et al. in 2002 (Rai et al., 2002), with application of Ant Colony Optimization (ACO) by Chan and Swarnkar in 2006 (Chan & Swarnkar, 2006), with application of Artificial Immune Algorithm by Prakash et al. in 2008 (Prakash et al., 2008) and with application of Artificial Neural Network (ANN) by Kant and Vaishya in 2013 (Kant & Vaishya, 2013).

b) Branch and Backtrack Approach

Branch and backtrack and Heuristic procedure for modelling the loading problem has been used by Shankar and Srinivasulu in 1989 (Shankar & Srinivasulu, 1989).

c) Branch and Bound Approach

The method was first described by Land and Doig in 1960 (Land & Doig, 1960). Branch and bound algorithm works by enumerating possible combinations of the variables in a branch and bound tree. A few integer variables are fixed to have zero or one value and others are allowed to have any value in the range between zero and one. The root of the tree is the original problem. A leaf node is selected from the tree and the algorithm is solved. In each iteration the descendents of feasible solutions are selected for further branching, and descendents of infeasible solutions are ignored.

Branch and bound approach for formulation of loading problem of FMS has been discussed by Kim and Yano in 1987 and 1989 (Y.-D. Kim & Yano, 1987)(Y.-D. Kim & Yano, 1989). The loading problem formulated by branch and bond methods has been solved with

application of *branch and bound approach* by Kim and Yano in 1987 and 1989 (Y.-D. Kim & Yano, 1987)(Y.-D. Kim & Yano, 1989).

d) Heuristic Approaches

Heuristics was the name of a certain branch of study, not very clearly circumscribed, belonging to logic, or to philosophy or to psychology often outlined, seldom presented in detail.

The aim of heuristic is to study the methods and rules of discovery and invention. A few traces of such study may be found in the commentators of Euclid; a passage of Pappus is particularly interesting in this respect. The most famous attempts to build up a system of heuristic are due to Descartes and to Leibnitz, both great mathematicians and philosophers. Bernard Bolzano presented a notable detailed account of heuristic. The present booklet is an attempt to revive heuristic in a modern and modest form. Heuristic reasoning is reasoning not regarded as final and strict but as provisional and plausible only, whose purpose is to discover the solution of the present problem. We shall attain complete certainty when we shall have obtained the complete solution, but before obtaining certainty we must often be satisfied with a more or less plausible guess. We may need the provisional before we attain the final. We need heuristic reasoning when we construct a strict proof as we need scaffolding when we erect a building.

Heuristic reasoning is often based on induction, or on analogy. Provisional, merely plausible heuristic reasoning is important in discovering the solution, but you should not take it for a proof; you must guess, but also examine your guess (Polya, 1945).

Heuristic is a program, rule, piece of knowledge, etc., which one is not entirely confident to be useful in providing a practical solution, but has reason to believe to be useful, and which is added to a problem-solving system in expectation that an average the performance will improve (Romanycia & Pelletier, 1985).

Heuristics are defined as the set of rules that provides optimal or non-optimal solution to the problem with less computational work (Greene & Sadowski, 1986). For different manufacturing enterprises a wide range of heuristics procedures have been developed. Heuristics for FMS in 1987 (Werra, 1987), and Petri net modelling combined with heuristic for FMS in 1994 (D. Y. Lee & DiCesare, 1994) has been developed. Heuristic model for the FMS capacity planning problem was presented in 1989 (Mazzola, 1989).

The loading problems of FMS has been modelled with simple heuristics by Stecke and Talbot in 1983(Stecke & Talbot, 1983), Stecke and Talbot (Stecke & Talbot, 1985), Ammons et al. (Ammons, Lofgren, & McGinnis, 1985) and, Shankar and Tzen (Shankar & Tzen, 1985) in 1985, Rajagopalan in 1986(Rajagopalan,

1986), *Kim and Yano in 1987* (Kim Yeong-Dae and Yano Candace A., 1987), *Tang and Denardo in 1988* (Tang & Denardo, 1988), *Shankar and Srinivasulu in 1989* (Shankar & Srinivasulu, 1989), *Kim and Yano in 1991* (Y. D. Kim & Yano, 1991), *Mukhopadhyay et al. in 1992* (Mukhopadhyay, Midha, & Murlikrishna, 1992), *Oba and Hashimot in 1993* (Kato, Oba, & Hashimot, 1993), *Roh and Kim* (Roh H.-K. and Kim Yeon-D., 1997) and, *Hsu and De-Matta* (Hsu & De-Matta, 1997) in 1997, *Farkas et al. in 1999* (Farkas, Koltai, & Stecke, 1999), *Rahimifard and Newman* (Rahimifard & Newman, 2000) and, *Tiwari and Vidyarthi* (M. K. Tiwari & Vidyarthi, 2000) in 2000, *Tiwari et al. in 2007* (M K Tiwari, Saha, & Mukhopadhyay, 2007) and, *Biswas and Mahapatra in 2009* (Biswas & Mahapatra, 2009); sequential *heuristic* by Shankar and Tzen in 1985 (Shankar & Tzen, 1985); and branch and backtrack with *heuristics* by Shankar and Srinivasulu in 1989 (Shankar & Srinivasulu, 1989).

The solution to the heuristics modelled loading problems were discussed with application of heuristics by Stecke and Talbot in 1983 (Stecke & Talbot, 1983), *Kim and Yano in 1987* (Y.-D. Kim & Yano, 1987), *Shankar and Srinivasulu in 1989* (Shankar & Srinivasulu, 1989), *Mukhopadhyay et al. in 1992* (Mukhopadhyay et al., 1992), *Hsu and De-Matta* (Hsu & De-Matta, 1997) and, *Roh and Kim* (Roh H.-K. and Kim Yeon-D., 1997) in 1997, *Farkas et al. in 1999* (Farkas et al., 1999) and, *Rahimifard and Newman in 2000* (Rahimifard & Newman, 2000); with application of *branch & bound, and branch & backtrack method* by Kato et al. in 1993 (Kato et al., 1993); with application of *GA* by *Tiwari and Vidyarthi in 2000* (M. K. Tiwari & Vidyarthi, 2000) and *Tiwari in 2007* (M K Tiwari et al., 2007); with application of *meta hybrid PSO* by Biswas & Mahapatra in 2009 (Biswas & Mahapatra, 2009); and *software simulation* by Shankar & Tzen in 1985 (Shankar & Tzen, 1985).

e) Hierarchical Model

Hierarchy modelling method is amongst the oldest modelling methods, dating from 1960's. This method processes data efficiently at faster rate but it is less flexible for optimization. The system is classified according to its hierarchy and its network tree is formulated. All links from one to many networks, from parent to child are specified. The system at higher level is parent to its lower level hierarchy.

Modelling of FMS by Buzacott and Shanthikumar in 1980 (Buzacott & Shanthikumar, 1980), modelling of automated manufacturing system by Simpson et al. in 1982 (Simpson, Hocken, & Albus, 1982) and modelling of loading and some other FMS problems by Bell and Bilalis in 1982 (Bell & Bilalis, 1982), Eversheim and Fromm in 1983 (Eversheim & Fromm, 1983), Stecke in 1983a (Stecke, 1983a) and 1983b (Stecke, 1983b), CAM-I in 1984 (CAM-I, 1984), O'Grady et al. in 1987 (O'Grady, Bao, & Lee, 1987) and O'Grady in 1987 (O'Grady, 1987) has been carried out

using hierarchical approach. A hierarchical model for integration of FMS production planning into a closed-loop material requirements planning (MRP) environment was proposed by Mazzola in 1989 (Mazzola, 1989).

f) Markov Chains

A Markov chain is a model consisting of a group of states and specified transitions between the states. A Markov chain can have a finite or infinite number of states. In a discrete time Markov chain (DTMC) each state change takes place at a fixed decision point and the time between changes is constant. In a continuous time Markov chain (CTMC), changes can happen at any instant. Transitions in a Markov chain depend on only the current state, and not on any history of previous states.

Markov chains have been used to model FMS by Vishwanadham et al. in 1992 (Vishwanadham, Narahari, & Johnson, 1992) and loading problems of FMS by Aldaihani and Savsar in 2005 (Aldaihani & Savsar, 2005).

g) Mathematical Modelling

Mathematics has been the language of science. Mathematics is used to solve many real-world problems of industry, physical sciences, economics, social and human sciences, engineering and technology (Stecke, 2005a). A mathematical model can be deterministic (input and output variables are fixed values) or stochastic (at least one of the input or output variables is probabilistic); static (time is not taken into account) or dynamic (time-varying interactions among variables are taken into account). In a mathematical model usually, some of the decision variables are restricted to integer values and some are continuous. Usually the optimization problems are formulated with zero-ones to encode choices from a small set of available options to a decision, usually in binary form of zero and one. Use of mathematics and simple mathematical models to solve problems in industry were discussed in detail by Stecke in 2005 (Stecke, 2005b). Mathematical programming models have been applied widely to solve the production planning problems. Mathematical programming requires high degree of accuracy and the solution approach requires efficient computational help. Integer programming (IP), mixed integer programming (MIP) and linear integer programming (LIP) has been widely utilized for mathematical modelling.

Stecke applied 0-1 nonlinear MIP for formulation of mathematical model of grouping and loading problems during 1981-83 (Stecke, 1981)(Stecke, 1982)(Stecke, 1983b) and mathematical program for FMS in 1983 (Stecke, 1983b). 0-1 nonlinear MIP formulation of the manufacturing systems was utilized in 1984 by Chatterjee et al. (Chatterjee, Cohen, Maxwell, & Miller, 1984). MIP formulation of the routing mix problem was carried out by Chatterjee et al. in 1984 (Chatterjee

et al., 1984). Ammons et al. formulated IP model of loading problems in assembly lines in 1985 (Ammons et al., 1985) and Hwang developed IP model of FMS problems in 1986 (Hwang, 1986). Equivalent IP formulation for the process planning problem of FMS was carried out by Kusiak and Finke in 1988 (Kusiak & Finke, 1988).

Kimemia in 1982 (Kimemia, 1982) and Kimemia and Gershwin in 1983 (Kimemia & Gershwin, 1983) used dynamic programming; Kimemia in 1982 (Kimemia, 1982), Kusiak in 1983 (Kusiak, 1983), Lee et al. in 1997 (D.-H. Lee, Lira, Lee, Jun, & Kim, 1997) and Kim et al. in 2012 (H. Kim et al., 2012) utilized LIP formulation; Stecke in 1983 and 1986 (Stecke, 1983b)(Stecke, 1986) discussed non-linear IP formulation; Wilson in 1992 (Wilson J. M., 1992), Lee and Kim in 1998 (D.-H. Lee & Kim, 1998), Sawik in 2000 (Sawik, 2000) and Dobson and Nambimadom in 2001 (Dobson & Nambimadom, 2001) adopted IP formulation; Taboun & Ulger in 1992 (Taboun & Ulger, 1992), Swarnkar & Tiwari in 2004 (Swarnkar & Tiwari, 2004) and Sujono & Lashkari in 2007 (Sujono & Lashkari, 2007) utilized 0–1 IP formulation; and Jahromi & Tavakkoli-Moghaddam in 2012 (Jahromi & Tavakkoli-Moghaddam, 2012) discussed 0-1 LIP formulation for modelling the loading problems of FMS.

Sarin and Chen in 1987 (Sarin & Chen, 1987), Rajamani and Adil in 1996 (Rajamani & Adil, 1996), Ozdamarl and Barbarosoglu in 1999 (Ozdamarl & Barbarosoglu, 1999), Chen and Ho in 2005 (Chen & Ho, 2005), Nagarjuna et al. in 2006 (Nagarjuna, Mahesh, & Rajagopal, 2006), Goswami and Tiwari in 2006 (Goswami & Tiwari, 2006), Kumar et al. in 2006 (A. Kumar, Prakash, Tiwari, Shankar, & Baveja, 2006), Biswas and Mahapatra in 2007 (Biswas & Mahapatra, 2007) and 2008 (Biswas & Mahapatra, 2008), Ponnambalam and Kiat in 2008 (Ponnambalam & Kiat, 2008), Yogeswaran et al. in 2009 (Yogeswaran, Ponnambalam, & Tiwari, 2009), Yusof et al. in 2011 (Yusof, Budiarto, & Deris, 2011), Mgwatu in 2011 (Mgwatu, 2011), Yusof et al. in 2011 (Yusof, Budiarto, & Venkat, 2011), Kumar et al. 2012 (V. M. Kumar, Murthy, & Chandrashekar, 2012), Yaqoub and Abdulghafour in 2012 (Yaqoub & Abdulghafour, 2012), Yusof et al. in 2012 (Yusof, Budiarto, & Deris, 2012) and Mahmudy et al. in 2012 (Mahmudy, Marian, & Luong, 2012) utilized mathematical modelling for loading problems of FMS.

Mathematical programming for loading problems of FMS is discussed by Kiran and Tansel in 1985 (A. S. Kiran & Tansel, 1985), Kiran in 1986 (S. Kiran, 1986), Nayak and Acharya in 1998 (Nayak & Acharya, 1998), Turkcan et al. in 2007 (Turkcan, Akturk, & Storer, 2007), Ozpeynirci and Azizoglu in 2010 (Ozpeynirci & Azizoglu, 2010), Mandal et al. in 2010 (Mandal, Pandey, & Tiwari, 2010) and Kosucuoglu and Bilge in 2012 (Kosucuoglu & Bilge, 2012).

Abazari et al. in 2012 (Abazari, Solimanpur, & Sattari, 2012) discussed linear mathematical programming for the loading problems.

MIP is utilized by Greene and Sadowski in 1986 (Greene & Sadowski, 1986), Liang and Dutt in 1990 (Liang & Dutt, 1990), Henery et al. in 1990 (Henery C. Co, Biermann, & Chen, 1990), Guerrero in 1999 (Guerrero, 1999), Lee and Kim in 2000 (D.-H. Lee & Kim, 2000) Kumar and Shanker in 2000 (N. Kumar & Shanker, 2000), Kumar and Shanker in 2001 (N. Kumar & Shanker, 2001), Yang and Wu in 2002 (Yang & Wu, 2002), Tadeusz in 2004 (Tadeusz, 2004), Bilgin and Azizoglu in 2006 (Bilgin & Azizoglu, 2006), Murat and Erol in 2012 (Murat & Erol, 2012) and Yusof et al. in 2012 (Yusof et al., 2012) for loading problems of FMS.

0-1 Linear MIP is utilized by Chakravarty and Shtub in 1984 (Chakravarty & Shtub, 1984), Co in 1984 (H. C. Co, 1984), Ammons et al. in 1985 (Ammons et al., 1985), Shankar and Tzen 1985 (Shankar & Tzen, 1985), Greene and Sadowski in 1986 (Greene & Sadowski, 1986) and Sarin and Chen in 1987 (Sarin & Chen, 1987); nonlinear MIP by Berrada and Stecke in 1986 (Berrada & Stecke, 1986) and Stecke and Brian in 1995 (Stecke & Brian, 1995); linear MIP by Ventura et al. in 1988 (Ventura, Frank, & Leonard, 1988); and 0–1 MIP by Gamila and Motavalli in 2003 (Gamila & Motavalli, 2003) and Chan et al. in 2004 (Chan, Swamkar, & Tiwari, 2004) for loading problems of FMS.

Nonlinear and integer constraint was utilized by Kouvelis & Lee in 1991 (Kouvelis & Lee, 1991), non linear goal programming model by Kumar et. al. in 1991 (P. Kumar, Singh, & Tewari, 1991) and goal programming model by Atmaca & Erol in 2000 (Atmaca & Erol, 2000) for modelling loading problem of FMS were observed in the literature.

The mathematical formulated problems have been solved with application of *branch and bound algorithm* by Berrada and Stecke in 1986 (Berrada & Stecke, 1986); with application of *linearization methods by Stecke in 1981* (Stecke, 1981) and 1983 (Stecke, 1983b), and Jahromi and Tavakkoli in 2012 (Jahromi & Tavakkoli-Moghaddam, 2012); with application of *lagrangian approach* by Kinemia and Gershwin in 1985 (Kinemia & Gershwin, 1985), Sarin and Chen in 1987 (Sarin & Chen, 1987), Bilgin and Azizoglu in 2006 (Bilgin & Azizoglu, 2006) and Ozpeynirci and Azizoglu in 2010 (Ozpeynirci & Azizoglu, 2010); with application of *min-max approach* by Kumar et al. in 1987 (Kumar P., Singh N., & Tewari N. K., 1987); with application of *heuristics* by Ventura et al. in 1988 (Ventura et al., 1988), Stecke and Brian in 1995 (Stecke & Brian, 1995), Nayak and Acharya in 1998 (Nayak & Acharya, 1998), Lee and Kim in 2000 (D.-H. Lee & Kim, 2000), Dobson and Nambimadom in 2001 (Dobson & Nambimadom, 2001), Nagarjuna et al. and, (Nagarjuna et al., 2006) Goswami

and Tiwari (Goswami & Tiwari, 2006) in 2006, and Kim et al. in 2012 (H. Kim et al., 2012).

The loading problem has been solved with application of *genetic algorithm (GA)* by Ozdamarl and Barbarosoglu in 1999 (Ozdamarl & Barbarosoglu, 1999), Kumar and Shanker (N. Kumar & Shanker, 2000) and Sawik (Sawik, 2000) in 2000, Yang and Wu in 2002 (Yang & Wu, 2002), Kumar et al. in 2006 (A. Kumar et al., 2006), Mandal et al. in 2010 (Mandal et al., 2010), and Yusof et al. (Yusof et al., 2012), Kosucuoglu and Bilge (Kosucuoglu & Bilge, 2012), and Abazari et al. (Abazari et al., 2012) in 2012; with application of *simulated annealing (SA)* by Ozdamarl and Barbarosoglu in 1999 (Ozdamarl & Barbarosoglu, 1999), Chan et al. (Chan et al., 2004) and Tadeusz (Tadeusz, 2004) in 2004, and Mandal et al. in 2010 (Mandal et al., 2010); with application of *particle swarm optimization (PSO)* by Biswas and Mahapatra in 2007 (Biswas & Mahapatra, 2007) and 2008 (Biswas & Mahapatra, 2008) and, Ponnambalam and Kiat in 2008 (Ponnambalam & Kiat, 2008); with application of *Harmony Search algorithm (HS)* by Yusof in 2011 (Yusof, Budiarto, & Deris, 2011); with application of *box complex method* by Kumar et al. in 1991 (P. Kumar et al., 1991); with application of *approximation technique* by Wilson in 1992 (Wilson J. M., 1992); and with application of *iterative algorithms* by Lee et al. in 1997 (D.-H. Lee et al., 1997) and Lee and Kim in 1998 (D.-H. Lee & Kim, 1998).

The loading problem of FMS has also been solved by techniques like *TS-SA hybrid algorithm* by Swarnkar and Tiwari in 2004 (Swarnkar & Tiwari, 2004), *GA-SA Hybrid algorithm* by Yogeswaran et al. in 2009 (Yogeswaran et al., 2009), *GA-HS hybrid algorithm* by Yusof et al. in 2011 (Yusof, Budiarto, & Venkat, 2011), *GA-PSO hybrid heuristic algorithm* by Kumar et al. in 2012 (V. M. Kumar et al., 2012), *TS-SA hybrid algorithm* by Murat & Erol in 2012 (Murat & Erol, 2012), *constraint method* by Sujono and Lashkari in 2007 (Sujono & Lashkari, 2007), *Sequential and simultaneous approaches* by Turkcan et al. in 2007 (Turkcan et al., 2007) and *artificial immune system (AIS)* by Mandal et al. in 2010 (Mandal et al., 2010).

h) Multi-Criterion Programming

The loading problem of FMS has been formulated with *multi-criterion programming* model by Kumar et al. in 1987 (Kumar P. et al., 1987).

i) Network Modelling

Network modelling has a wide range of applications. The manufacturing processes have also been modelled as queueing networks, both as open or close networks. QN models are built in an aggregate way thus the models work well at the higher and more aggregate levels of a hierarchy of planning (Buzacott & Shanthikumar, 1980). Because of dynamic operations at lower levels, QN models are quite impractical at lower

level of hierarchy. Also the specific distributions may not accurately reflect the true operating characteristics of the particular FMS. The queueing network modelling can be closed (CQN) and open (OQN) type. The difference between CQN and OQN is that CQN contains fixed number of parts with no external arrivals or departures. For analysis of the queueing network model Buzen's algorithm and mean value analysis were widely used.

FMS has been modelled with CQN by Solberg in 1977 (Solberg, 1977), 1979 (Solberg, 1979) and 1980 (Solberg, 1980) and Vinod and Sabbagh in 1986 (Vinod & Sabbagh, 1986), with OQN by Shanthikumar & Stecke in 1984 (Shanthikumar & Stecke, 1984), with CANQ by Stecke and Solberg (Stecke & Solberg, 1985) and Stecke and Morin (Stecke & Morin, 1985) in 1985 and Afentakis in 1989 (Afentakis, 1989).

FMS has also been modelled with advanced CQN by Seidmann et al. in 1987 (Seidmann, Schweitzer, & Shalev-oren, 1987), with *discrete generalized network* by Ram et al. in 1990 (Ram, Sarin, & Chen, 1990) and with *queueing networks* by Narahari et al. in 1990 (Narahari, Viswanadham, Meenakshisundaram, & Rao, 1990) and Vishwanadham et al. in 1992 (Vishwanadham et al., 1992). *Queueing model* has been developed for the performance prediction of FMS's by Jain et al. in 2008 (Jain, Maheshwari, & Baghel, 2008). Modelling of the loading problems of FMS with single server CQN model by Stecke and Morin in 1984 (Stecke & Morin, 1984), CQN model by Stecke and Kim in 1987 (Stecke & Kim, 1987) and *constrained network model* by Bretthauer and Venkataramanan in 1990 (Bretthauer & Venkataramanan, 1990) were developed.

Solution of the network modelled FMS problems has been achieved by *surrogate and Lagrangian relaxation* by Bretthauer and Venkataramanan in 1990 (Bretthauer & Venkataramanan, 1990). Mean value analysis (MVA) has a wide suitability for solving the network models. MVA is an iterative technique that avoids numerical instabilities, developed by Reiser and Lavenberg in 1978-80 as an efficient solution technique for queueing network models, to overcome the numerical problems raised with the convolution algorithms (Reiser & Lavenberg, 1978)(Reiser & Lavenberg, 1980). MVA is based on applications of Little's theorem (Little, 1961). The application of Mean-value analysis of queues (MVAQ) for FMS modelling has been discussed by Suri and Hildebrant in 1984 (Suri & Hildebrant, 1984).

j) Perturbation Approach

Perturbation for modelling the loading problems of FMS has been used by Mukhopadhyay et al. in 1998 (Mukhopadhyay, Singh, & Srivastava, 1998).

Perturbation modelled FMS loading problem has been solved with application of SA in by Mukhopadhyay et al. 1998 (Mukhopadhyay et al., 1998).

k) *Petri Nets*

A Petri net has its origin from the dissertation of Carl Adam Petri, submitted in 1962 (Petri, 1962), to the faculty of Mathematics and Physics at the Technical University of Darmstadt, West Germany. The English translation of the report is also available in 1966 (Petri, 1966).

Petri nets are graphical and mathematical modelling tool used to model physical systems. Because of its graphic nature Petri nets are used as visual communication tool similar to flow charts, networks and block diagrams. It is possible to set up state equations, algebraic equations and other governing equations because of its mathematical nature.

FMS has been modelled with *timed Petri nets* by Cohen et al. in 1983 (Cohen et al., 1983), with *Petri nets* by Narahari and Viswanadham in 1985 (Narahari & Viswanadham, 1985), with generalized *stochastic Petri nets* (GSPN) by Narahari et al. in 1990 (Narahari et al., 1990), with *stochastic Petri nets* by Vishwanadham et al. in 1992 (Vishwanadham et al., 1992), with *Petri net* combined with heuristic by Lee and DiCesare in 1994 (D. Y. Lee & DiCesare, 1994), with *fuzzy coloured Petri nets* (CPNs) by Yeung et al. in 1996 (Yeung, Liu, Shiu, & Fung, 1996), with *colored Petri net* (CPN) based hierarchical model by Al-Titinchi and Al-Aubidy in 2004 (Al-Titinchi & Al-Aubidy, 2004). *Petri net* modelling has been used for loading problems of FMS by Tiwari et al. in 1997 (Tiwari M. K., Hazarika B., Vidyarthi N.K., 1997). Solution of the loading problem modelled using Petri nets has been done using *heuristics* by Tiwari et al. in 1997 (Tiwari M. K., Hazarika B., Vidyarthi N.K., 1997).

l) *Sequential Approach*

The loading problem of FMS has been modelled with two-stage *sequential approach* by Liang in 1994 (Liang, 1993) and Ming in 1994 (Ming, 1994), and *sequential approach* by Liang and Dutta in 2009 (Liang & Dutta, 2009).

The sequential modelled FMS problems have been solved with application of *Lagrangian relaxation* approach by Liang and Dutta in 2009 (Liang & Dutta, 2009).

m) *Simulation Models*

Simulation is a descriptive modelling technique through computer based programmes for analysis of the problems and solutions. FMS problems are very complex in nature, so simulation models are widely used to solve FMS problems because of its descriptive nature. Cost and computational time increases with increase in complexity of the problems.

A virtual manufacturing system mode has been developed for flexible manufacturing cells using object-oriented paradigm, and implemented with QUEST/IGRIP software by Kim and Choi in 2000 (S. Kim & Choi, 2000). Computer simulation package Simfactory II.5 has been used for modelling loading problem of FMS by Gupta in 1999 (Gupta, 1999).

n) *Unit Operation Approach*

Unit operation has been used to model Block Angular Structures of loading problems by Kouvelis and Lee in 1991(Kouvelis & Lee, 1991).

Table 1: Distribution density of FMS modelling methods

	1977	1978	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013				
1																									√	√		√		√								√			
2														√																											
3													√	√																											
4								√		√	√	√	√	√		√	√	√	√			√		√	√							√		√							
5							√	√	√				√	√																											
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7							√	√	√	√	√	√	√		√	√	√			√	√	√	√	√	√	√	√	√	√	√	√	√	√	√	√	√	√	√	√		
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Notations used in table 1

- | | | | |
|----|-------------------------------|-----|-----------------------------|
| 1. | Artificial Intelligence | 6. | Markov Chains |
| 2. | Branch and Backtrack Approach | 7. | Mathematical Modelling |
| 3. | Branch and Bound Approach | 8. | Multi-Criterion Programming |
| 4. | Heuristic Approaches | 9. | Network Modelling |
| 5. | Hierarchical Model | 10. | Perturbation Approach |

11. Petri Nets
12. Sequential Approach
13. Simulation Models
14. Unit Operation Approach

Figure 1: Modelling methods for the loading problems of FMS (1981-2013)

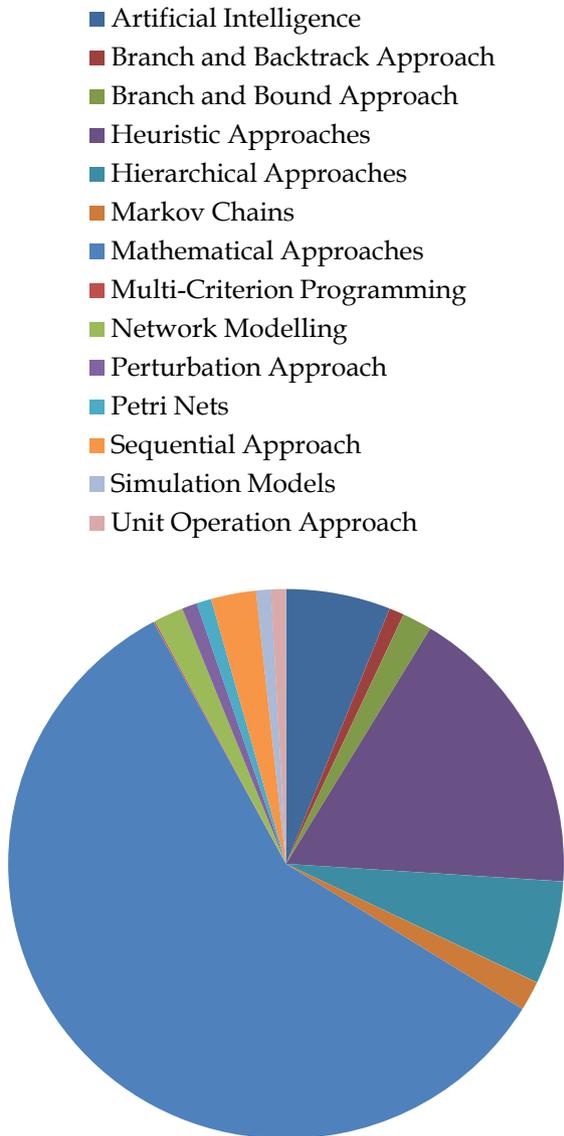
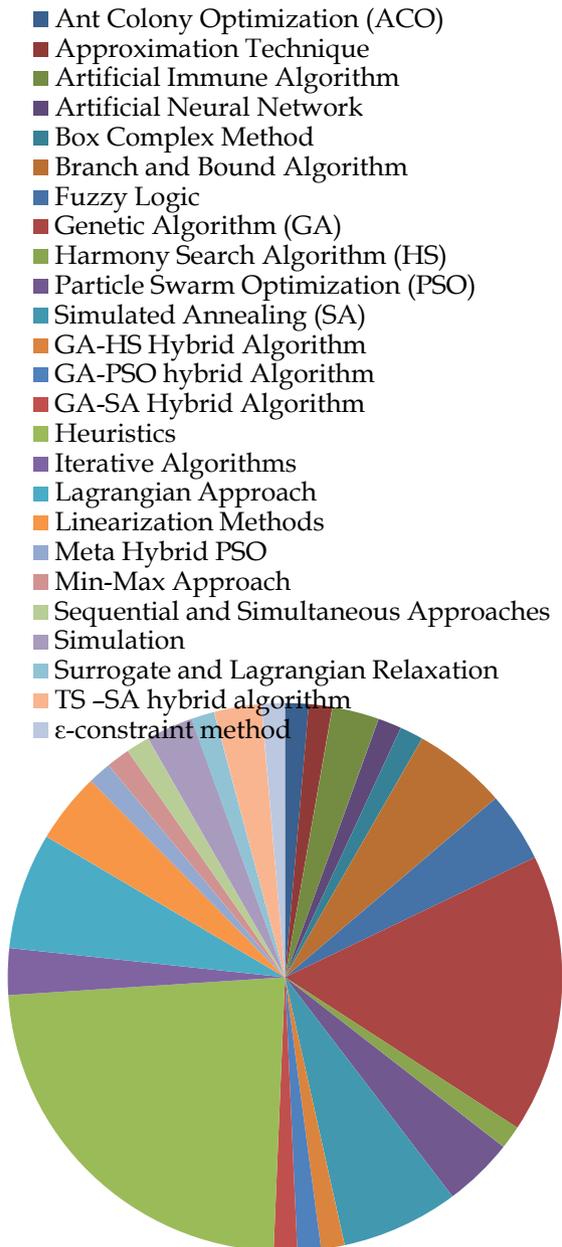
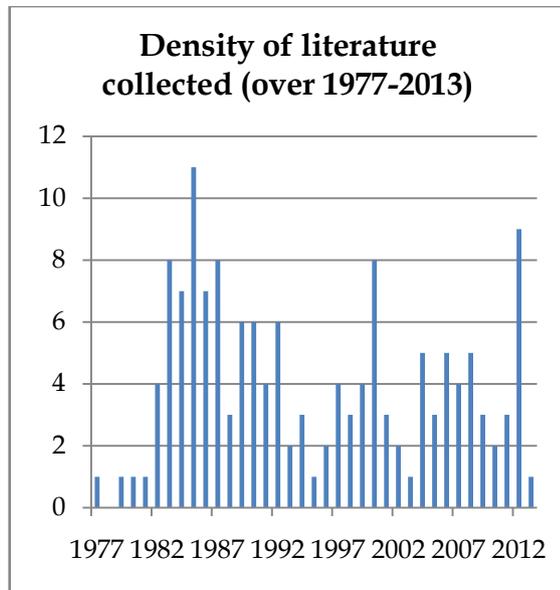


Figure 2 : Solution methodologies for loading problems of FMS





Accuracy, results acceptability and adaptability, computational time and cost are the major factors for selection of the type of modelling for a particular application, particularly loading problems of FMS.

III. CONCLUSION

Hierarchical modelling, mathematical modelling, heuristic approaches, network modelling, simulation techniques, artificial intelligence (fuzzy logic, artificial immune algorithms and artificial neural network), Petri nets, Markov chains, branch and bound approach, multi-criterion programming model, branch and backtrack approach, sequential approach, unit operation approach and perturbation approach have been discussed in the literature for modelling loading problems of FMS's. Mathematical, heuristics, hierarchical approaches and network modelling are the widely used and accepted ones. Moreover the global optimization techniques have been widely used for solving the formulated problems.

Solution of the mathematical models have been approached by branch and backtrack method, branch and bound algorithm, ant colony optimization (ACO), genetic algorithm (GA), harmony search algorithm (HS), simulated annealing (SA), particle swarm optimization (PSO), approximation technique, artificial immune algorithm, artificial neural network (ANN), box complex method, computer simulation package simfactory II.5, fuzzy-based solution methodology, GA-HS hybrid algorithm, GA-PSO hybrid heuristic technique, GA-SA hybrid algorithm, heuristic algorithms, meta hybrid PSO, min-max approach, sequential and simultaneous approaches, simulation, surrogate and lagrangian approaches, TS-SA hybrid algorithm and ϵ -constraint method.

Heuristics solutions do not assure optimal solution (Manoj Kumar Tiwari, Kumar, Kumar, Prakash,

& Shankar, 2006), GA-based heuristics for the loading problem lead to constraint violations and large number of generations (A. Kumar et al., 2006) and PSO avoids premature convergence (Biswas & Mahapatra, 2007). Because of less computational requirements, easy and fast convergence, better ease of apply, less time requirements are some of the factors attracting the researchers to use global optimization techniques for solving the mathematical or other model of the loading problems and other problems and FMS's. The authors after spending a lot of time on analysing and studying the research papers, books, Ph.D. thesis and other relevant materials suggests integer programming for modelling the loading problems and PSO for solution of the model.

To analyse the system performance and to provide insight of how the system behaves, and how system component behaves, and to identify the key factors and parameters affecting the system, modelling and simulation of the physical system is the only best solution. Various types of results, graphs, plots etc can be generated for useful analysis of the system. The key to be remembered is that the validity and accuracy of the result will depend on the model developed, and the information induced in the model (value of parameters and key variables). It is the human who developed the model and it is him only to validate and validate the results. The software or model will give the results in the type the user wants. Validation, accuracy and acceptance of the results depend on the user. The modelling simulation and analysis can be expensive and time consuming to develop and run for desired accurate and acceptable results and outputs. An ideal model should be least expensive which should require least computational time. A research work is required to compare the various modelling techniques on basis of certain parameters, which will help the industry and academicians in selection of the type of modelling techniques under certain parameters and constraints. The authors are working on this research.

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2. Ethical Guidelines,
3. Submission of Manuscripts,
4. Manuscript's Category,
5. Structure and Format of Manuscript,
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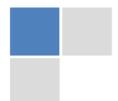
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- Shape the theory/purpose specifically - do not take a broad view.
- As always, give awareness to spelling, simplicity and correctness of sentences and phrases.

Procedures (Methods and Materials):

This part is supposed to be the easiest to carve if you have good skills. A sound written Procedures segment allows a capable scientist to replacement your results. Present precise information about your supplies. The suppliers and clarity of reagents can be helpful bits of information. Present methods in sequential order but linked methodologies can be grouped as a segment. Be concise when relating the protocols. Attempt for the least amount of information that would permit another capable scientist to spare your outcome but be cautious that vital information is integrated. The use of subheadings is suggested and ought to be synchronized with the results section. When a technique is used that has been well described in another object, mention the specific item describing a way but draw the basic principle while stating the situation. The purpose is to text all particular resources and broad procedures, so that another person may use some or all of the methods in one more study or referee the scientific value of your work. It is not to be a step by step report of the whole thing you did, nor is a methods section a set of orders.

Materials:

- Explain materials individually only if the study is so complex that it saves liberty this way.
- Embrace particular materials, and any tools or provisions that are not frequently found in laboratories.
- Do not take in frequently found.
- If use of a definite type of tools.
- Materials may be reported in a part section or else they may be recognized along with your measures.

Methods:

- Report the method (not particulars of each process that engaged the same methodology)
- Describe the method entirely
- To be succinct, present methods under headings dedicated to specific dealings or groups of measures
- Simplify - details how procedures were completed not how they were exclusively performed on a particular day.
- If well known procedures were used, account the procedure by name, possibly with reference, and that's all.

Approach:

- It is embarrassed or not possible to use vigorous voice when documenting methods with no using first person, which would focus the reviewer's interest on the researcher rather than the job. As a result when script up the methods most authors use third person passive voice.
- Use standard style in this and in every other part of the paper - avoid familiar lists, and use full sentences.

What to keep away from

- Resources and methods are not a set of information.
- Skip all descriptive information and surroundings - save it for the argument.
- Leave out information that is immaterial to a third party.

Results:

The principle of a results segment is to present and demonstrate your conclusion. Create this part a entirely objective details of the outcome, and save all understanding for the discussion.

The page length of this segment is set by the sum and types of data to be reported. Carry on to be to the point, by means of statistics and tables, if suitable, to present consequences most efficiently. You must obviously differentiate material that would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matter should not be submitted at all except requested by the instructor.



Content

- Sum up your conclusion in text and demonstrate them, if suitable, with figures and tables.
- In manuscript, explain each of your consequences, point the reader to remarks that are most appropriate.
- Present a background, such as by describing the question that was addressed by creation an exacting study.
- Explain results of control experiments and comprise remarks that are not accessible in a prescribed figure or table, if appropriate.
- Examine your data, then prepare the analyzed (transformed) data in the form of a figure (graph), table, or in manuscript form.

What to stay away from

- Do not discuss or infer your outcome, report surroundings information, or try to explain anything.
- Not at all, take in raw data or intermediate calculations in a research manuscript.
- Do not present the similar data more than once.
- Manuscript should complement any figures or tables, not duplicate the identical information.
- Never confuse figures with tables - there is a difference.

Approach

- As forever, use past tense when you submit to your results, and put the whole thing in a reasonable order.
- Put figures and tables, appropriately numbered, in order at the end of the report
- If you desire, you may place your figures and tables properly within the text of your results part.

Figures and tables

- If you put figures and tables at the end of the details, make certain that they are visibly distinguished from any attach appendix materials, such as raw facts
- Despite of position, each figure must be numbered one after the other and complete with subtitle
- In spite of position, each table must be titled, numbered one after the other and complete with heading
- All figure and table must be adequately complete that it could situate on its own, divide from text

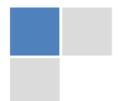
Discussion:

The Discussion is expected the trickiest segment to write and describe. A lot of papers submitted for journal are discarded based on problems with the Discussion. There is no head of state for how long a argument should be. Position your understanding of the outcome visibly to lead the reviewer through your conclusions, and then finish the paper with a summing up of the implication of the study. The purpose here is to offer an understanding of your results and hold up for all of your conclusions, using facts from your research and generally accepted information, if suitable. The implication of result should be visibly described. Infer your data in the conversation in suitable depth. This means that when you clarify an observable fact you must explain mechanisms that may account for the observation. If your results vary from your prospect, make clear why that may have happened. If your results agree, then explain the theory that the proof supported. It is never suitable to just state that the data approved with prospect, and let it drop at that.

- Make a decision if each premise is supported, discarded, or if you cannot make a conclusion with assurance. Do not just dismiss a study or part of a study as "uncertain."
- Research papers are not acknowledged if the work is imperfect. Draw what conclusions you can based upon the results that you have, and take care of the study as a finished work
- You may propose future guidelines, such as how the experiment might be personalized to accomplish a new idea.
- Give details all of your remarks as much as possible, focus on mechanisms.
- Make a decision if the tentative design sufficiently addressed the theory, and whether or not it was correctly restricted.
- Try to present substitute explanations if sensible alternatives be present.
- One research will not counter an overall question, so maintain the large picture in mind, where do you go next? The best studies unlock new avenues of study. What questions remain?
- Recommendations for detailed papers will offer supplementary suggestions.

Approach:

- When you refer to information, differentiate data generated by your own studies from available information
- Submit to work done by specific persons (including you) in past tense.
- Submit to generally acknowledged facts and main beliefs in present tense.



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<i>References</i>	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring



INDEX

B

Bilge · 51, 53, 64

D

Dissipation · 5
Ductility · 3

F

Fraternity · 39
Fraught · 45

I

Intricate · 3

M

Maneuver · 1, 3

P

Perturbation · 59
Pinion · 19, 21
Plausible · 47

Q

Queuing · 47

S

Symposium · 61



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