

Investigation of A Reciprocatory Driven Heat Loop to High Heat Single Phase Liquid Cooling for Temperature Uniformity

O.T. Popoola

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Abstract

A bellows-type Reciprocating-Mechanism Driven Heat Loops (RMDHL) is a novel heat transfer device that could attain a high heat transfer rate through a reciprocating flow of the working fluid inside the heat transfer device. This paper investigates the possibility of applying the device for single phase liquid cooling for high performance computing. The objective of this paper is to apply the RMDHL to a liquid cooling system and compare its performance with a continuous cooling system. A Computational Fluid Dynamic (CFD) code that is validated experimentally was employed to numerically simulate both the Dynamic Pump Driven Heat Loop (DPDHL) and the reciprocating loop. To confirm the validity of the Numerical code to satisfactorily predict the reciprocating flow in the RMDHL, an experimental procedure was used to validate the Numerical Code. This work proposes an efficiency term based on the temperature uniformity and overall performance, and compare both systems based on the proposed efficiency term. It was discovered that for temperature uniformity, the RMDHL performed better than the DPDHL with an efficiency of more than 30

Index terms— heat loop, reciprocating flow, cooling, heat flux.

Introduction the most significant hindrances to the technological advances in power electronics, plasma-facing components, high load optical components, laser diode arrays, X-ray medical devices, power electronics for hybrid vehicles as well as for toys and appliances, high-power computers, power generation, optoelectronic equipment, leading edges/nose caps of supersonic/hypersonic cruise vehicles, advanced gas turbines, and new directed energy based weapon systems has always been the issue of effective thermal management. Microelectronic chips which power the system or subsystems of these devices dissipate heat fluxes as high as 10 W through a 5 mm x 5 mm side (400 W/cm²) and heat fluxes over 1,000 W/cm² have been projected [1], [2]. The attendant rise in temperature in these devices which as results from the waste heat dissipation of the chips is the cause of failure in these devices. Such that the failure rate of these systems themselves increases exponentially with temperature [3]. An effective thermal management system must find a solution to high heat flux as well as the non-uniform system temperature or heat flux distribution across the surfaces. Efforts are actively ongoing to develop better solutions to this problem.

Cao and Gao [4][5] and Cao et al. [6] conceived, designed and tested a novel solenoid and bellows-type Reciprocating-Mechanism Driven Heat Loops (RMDHL). The RMDHL shown in Fig 1 uses a reciprocating flow of the working fluid inside the heat transfer device for cooling of the cold plate/evaporator. In addition to the hollow loop, other components include a reciprocating driver, an evaporator section, a condenser section, and a liquid reservoir. The reciprocating driver is integrated with a liquid reservoir and facilitates a reciprocating flow of the working fluid within the heat loop. There is a partial vacuum within the loop and the working fluid hermetically sealed within the loop is under a substantially saturated condition. Experimental results for bellows based heat loop indicated that using a 5 W rated driver, the heat loop could handle a heat loads of more than 550 W in the evaporator section. Additional studies are required to extend the device to substantially increase the cooling load while simultaneously optimizing material and energy utilization.

Furthermore, in the selection of thermal management solution, there are quite a number possible options available and for each approach there is a large number of process variables. As a result, it is essential that

each cooling system be investigated on a case by case basis. Even when all the factors are investigated, it is also essential to create a schedule of preference of ideal combinations for proper selection. Computer simulation has become an invaluable tool for greatly improving thermal management for particular applications [7].

Developing a CFD model For the RMDHL is not a simple one as the model will involve generating the oscillating flow in the channel using fluid structure interaction, numerous fluid properties such as density, viscosity, thermal conductivity and specific heat, as well as the geometry and the flow conditions [8], [9]. The geometry for the bellows type RMDHL is a challenge as it involves a continuous interchange between the rectangular channels of the evaporator and the circular channels in the connecting piping.

Furthermore, a review of literature [9]- [19] showed that the study into heat transfer in oscillating pipe flow has been mostly experimental and analytical studies focused on pulsating pipe flow, Stirling engines and Vuilleumier heat pumps type systems, high Reynolds number open channel applications and gravity-wave induced boundary layer in biological systems like arteries and airways. For the RMDHL, the requirement for the numerical for the inlet and outlet boundary conditions is a challenge, as it involves specifying the inlet and outlet in the same geometric position. Depending on the flow direction, inlet and outlet interchange. The outlet and the inlet in the forward direction become the inlet and outlet in the reverse direction. Additionally, the fluid conditions at the outlet and inlet of the model are interdependent for both the forward and reverse flow; the outlet flow conditions determine the value of the inlet flow conditions. The numerical studies reviewed failed to provide details on how to resolve the inlet and outlet boundary condition of the oscillating flow or simply modelled the loop driver using a fluid structure interaction (FSI) model. FSI modelling for the RMDHL requires costly computational resources because the number of mesh node in the driver is more than double the number of nodes in the rest of the RMDHL loop.

This study aims to empirically compare the performance of RMDHL to that of an existing liquid cooling systems, a dynamic pumps driven heat loop (DPDHL). This experimental and numerical study looks into the heat transfer and fluid flow aspects of the (RMDHL). Using a commercial CFD software and a novel numerical code, this study proposes an open loop configuration of the reciprocating flow. The proposed open loop configuration is developed based on the laminar model of T. S. Zhao and Cheng [20] and it seeks to reduces the computational cost of the numerical study by eliminating the need for fluid structure interaction study. It is expected that for future studies, the open loop configuration will reduce computational cost at the same time provided the accuracy required. To establish the accuracy of the Numerical codes, the results of the simulation were validated with appropriate experimental data. The study will also present the results of the validation of the CFD model and then compare the performance of a RMDHL with the DPDHL in terms of temperature, uniformity and heat removal from the surface of the heat source. For the current study a 3D, turbulent flow setup of continuous and RMDHL cooling loops with liquid water as the cooling fluid is provided. The setup and its results will be the foundation for the turbulent two phase model for various cooling fluids. It is expected that the completed model will be used to effectively evaluate the general concepts of RMDHL for future development and optimization of a standard industrial product.

1 II. Conceptual Design of the Bellow-Type RMDHL

The construction of the RMDHL and the specification of the design parameters remain as specified by [6]. For the schematic of the RMDHL represented in Fig. 1b, the most important relation that describes the critical requirement for the operation of the heat loop is given as [6]:

$$2 \quad \text{????????????????} + 2\text{????????} + \text{????????}$$

(1)

The length and average interior cross-sectional area of the evaporator are denoted by L_e and A_e , respectively, the length and average interior crosssectional area of the connection tubing between the evaporator and the condenser are L_t and A_t , the length and interior cross-sectional area of each condenser section are L_c and A_c . The piston cross-sectional area and reciprocating stroke are A_p and S , respectively. From the geometry of the heat loop Fig 1b and consideration of all the components of the RMDHL designed in equation (1), the critical S was calculated as 7 cm. A value of 7.62 cm was used for the reciprocating driver.

3 III. Performance Evaluation of the

Model Bellow-Type RMDHL

The experimental setup for the bellows-type RMDHL demonstration model is similar to the setup shown in Fig. 2a. The setup includes electric heaters for supplying heat to the cold plate of the heat loop, a DC power supply to the reciprocating driver, a control circuit board to control the reciprocating frequency of the driver, a constant temperature circulator to maintain a constant coolant inlet temperature of 10oC to the condenser, which would also control the operating temperature level of the heat loop, a data acquisition system, and the fabricated heat loop. Eight Omega flexible heaters (four on each side of the cold plate) are clamped by two aluminum plates onto the cold plate with insulation layers sandwiched between the heaters and clamping plates. Each heater has a dimension of 2 cm by 12 cm and could provide a heat input up to 200 W [6]. Twelve thermocouples were placed at different locations of the heat loop. Nine of them (numbered as No. 1 through No. 9) are placed on

the top surface of the cold plate at different locations for the study of temperature uniformity on the cold plate. Figure 2b shows detailed locations of these thermocouples. One thermocouple is placed near the condenser and another two thermocouples are placed on two ends of the bellows pump to monitor the heat loop temperature distribution in addition to those on the cold plate. These three thermocouples are numbered, respectively, as T10, T11, and T12, as shown in Fig. 2b.

During the experimentation, the heat loss from the clamping plate to the ambient was amounted to be less than 1%. Therefore, the sources of the experimental uncertainty were primarily due to the instruments themselves. The scanning thermocouple thermometer has an accuracy of $\pm 0.1\%$ of reading $\pm 0.4^\circ\text{C}$. The power meter has an accuracy of $\pm (1\% \text{ reading} + 5 \text{ digits})$. So the maximum uncertainty for the temperature and heat power measurements would be 1.0% and 2%, respectively.

IV.

4 Numerical Analysis

It should be mentioned that the RMDHL can work either a single-phase cooling loop or two-phase cooling loop. In this study a single-phase application. A Computational Fluid Dynamic (CFD) code was employed to numerically simulate both the Dynamic Pump Driven Heal Loop (DPDHL) and the reciprocating loop. The first step of the model development was the generation of a 3D CAD model of the process by Solid Works. The condenser and evaporator loops are enclosed with solid wall. The two loops are separated from each other by the wall off the part body. The solid walls are aluminum and thermo physical properties for them are obtained from the fluent database. The working liquid in the both loops is water. The heat fluxes are applied on both side of the evaporator and the boundary conditions are presented in the Table 1.

The schematic for the RMDHL is presented in Figure 3. The configuration for the geometry for the numerical model of the RMDH loop and the mesh grid distribution for numerical simulations of the RMDH loop is shown in Fig. 3c. The displacement of the piston $x_p(t)$ with time is [21]:

The pressure gradient takes the form:

Reynolds number for the reciprocating flow in the main pipe is given by: $Re = \frac{\rho \cdot \dot{V}}{\mu \cdot D}$ (1)

(V.

5 Governing Equations

As stated earlier, an open loop configuration of the heat loop is modeled. A C++ numerical code was used to determine the interfacial conditions between the end of the condenser and the pump. In this case, only a constant average temperature is initiated for the computation process and the final working fluid temperature at the interface had been determined through the iteration of the computational procedure. Even if physically the loop is open, the function has actually closed the loop from the computational point of view. The open loop is used to reduce the computational cost of solving the whole domain and to avoid the simulation of the bellows part which requires an FSI modeling. The constant heat flux condition is applied at the outer surface of the cold plate while the rest of the exterior surface of the loop was insulated. A constant temperature is applied at the inlet of the condenser cooling water.

The geometry and thermal boundary conditions for the RMDHL is a bit more complex than the DPDHL. DPDHL will have permanent inflow and outflow regions, where one can easily define the inlet velocity and temperature boundary conditions. RMDHL flows require interchange between the inflow and outflow boundaries during a cycle. For most applications, it is difficult to determine the inflow/outflow boundary conditions, since fluid particles exiting the flow domain during a part of the cycle are fed back into the domain, later in the cycle. The DPDHL which represents the case of forced convection heat transfer in channels and tubes is well understood. Based on above assumptions, the governing equations for fluid and energy transport are: Fluid flow: (6) (7) Energy in fluid flow (8) Energy in heat sink solid part (9) The boundary conditions for these equations are specified in the previous table. Based on the operating conditions described above, the boundary conditions for the governing equations are given as: Inlet:

Outlet:

Fluid-solid interface:

At the top wall:

In Eq. (??), and are the fluid inlet pressure and temperature, respectively;

is the pressure at the outlet, n is the direction normal to the wall or the outlet plane, and is the heat flux applied at the top wall of the heat sink.

6 VI.

7 Results and Discussion

Details of the numerical solution scheme are presented in Table ???. The CFD numerical algorithm utilizes Pressure Implicit with Splitting of Operators (PISO) formulation for the solution of the Navier-Stokes and

heat transport equations. Gradient discretization was Green-Gauss Node based, pressure discretization was Second order while the momentum and energy discretization were Second order upwind. Transient formulation was second order Implicit. Appropriate under relaxations were used to improve the numerical stability for all governing equations. The solver conditions for the DPDHL are similar to those for conventional unidirectional flow. The criteria for convergence was set at 10^{-4} for the continuity and x, y and z momentum. While a convergence criterion of 10^{-8} was set for the DPDHL and 10^{-6} for the RMDHL.

The resulting computational mesh is presented in Fig. 3c. In order to establish computational accuracy, grid independence studies are always necessary and were equally performed in this work. The mesh independence studies were conducted for two more grids with coarse and fine meshes settings. The variation of the results between the coarsest and finest meshes was 5% (the largest variation). However, for the mesh used for the numerical simulation the results showed less than 1.5% variation for the last two grid size.

Fig ?? show the comparison of the results for the experimental data and the Numerical results for the RMDHL loop. This comparison shows that the values of the numerical model are significantly higher than those of the experimental data. However, statistical comparison using the best-fit regression, the Nash-Sutcliffe efficiency (NSE), the percentage bias (PBIAS) and RMSE-observations standard deviation ratio (RSR) table 3 show that the results of the computational study were compared with the experimental work and in general, good agreement with experimental data within acceptable limits. Details in Fig 4 ??nd Table 4. As is widely adopted, NSE determines the relative magnitude of the residual variance ("noise") compared to the measured data variance ("information"). NSE ranges accurate the prediction. PBIAS measures the average tendency of the simulated data to be larger or smaller than the experimental data, the lower the magnitude the more accurate the model simulation, and the optimal value would therefore be zero. RSR measures the error index and like the PBIAS, its optimal value is zero. Hence the numerical solution was used as the basis for the comparison. For the RMDHL, the temperature profile is more uniform than the temperature profile for the DPDHL. Table 4 and Table 5 show that not only is the mean temperature for the RMDHL lower than the mean temperature for the DPDHL, the standard deviation around the mean is about 1.5 o C for the RMDHL and about 5 o C for the DPDHL. It will be observed that there is an average of about 7% difference when the average value of the numerical model is compared to the data collected. This is because the actual numerical modeling of the reciprocating flow would require a Fluid structure interaction (FSI) of the pump. To reduce computational costs associated with the FSI, This study adopted a 'virtual loop' analysis, a numerical code in C. The virtual loop assumed complete perfect mixing of the fluid in the pump and assigns the mean parameter formulation to inlets and outlets as flow direction changes. The details of the Virtual loop has been presented in details in [22] . The maximum temperature occurs at the midpoint of the walls while the maximum temperature for the DPDHL is at the exit side of the cold plate. In terms of performance; thus, the RHMDL is more effective in cooling the plate than the DPDHL by up to 5 o C. As shown in Table 5, for a heat transfer rate of 550 W, 500 W, 450 W, 400 W, the DPDHL produced an average hot plate temperature of 331.71, 327.77, 323.18, and 318.19 o C, respectively; while the RMDHL produced an average of 328.09, 327.31, 324.37 and 313.19 o C, respectively. The basis for determining the average hot plate temperature is provided in Equation (??6). The reason for the better performance is that RMHDL is that rate of heat loss to the condenser is higher for the RMDHL than for the DPDHL. there are two temperature gradients. One gradient along the evaporator and another gradient across the evaporator. The gradient along the evaporator is common to both the DPDHL and the RMDHL and is as a result of pressure drop along the piping in the evaporator. The effect of this gradient will vary if a different piping configuration is adopted.0 V ?? ?? ? 2 V V p V ?? ?? ? ?? ? ?? ? 2 p c V T k T ?? ? ?? ? 2 0 s s k T ?? ? ? , in in out ave V V T T ?? ? , 0 out T PP n ? ? ? ? 0, . s s s T T V T T k k n n ? ? ? ? ? ? s w s T q k n ? ?? ? in V in T out p w q (13)

8 Global

The empirical variation of the temperature is investigated at 3 cross-sections. The cross sections are shown in Fig. 7, section A-A at one end, Section B-B at the center, and section C-C at the other end. Temperatures at the centerline was compared for both reciprocating and DPDHL flow at two heat transfer rate, 400 and 550 W and compared statistically. Figure ?? and table 4 presents the details of the analysis. The plate temperature is minimum at the inlet of the evaporator and gradually increases toward the outlet of the outlet for the DPDHL flow loop. Another statistic indicator that may be used to gage the temperature uniformity over the cold plate is the standard deviation, defined [6] as: 1. Although the maximum temperature differences may vary with the power input, they are generally around 6 o C for the RMDHL and 20 o C for the DPDHL loop. The standard deviation for the RMDHL is less than half of the value for the DPDHL (Table 5).? ? = ? 1 ??1 ? (? ? ? ? ?) 2 ? ?=1

The standards deviation of the RMDHL changes only slightly with increasing rate of heat transfer but for the DPDHL it increases significantly with increasing rate of heat transfer. It should be pointed out that all of the data presented herein are based on a low driver reciprocating frequency of 0.14/s for a maximum stroke. The figures show that not only is the mean temperature for the RMDHL lower than the mean temperature for the DPDHL, the standard deviation around the mean is about 1.5 °C for the RMDHL and about 4 °C for the DPDHL.

It should be pointed out that all of the data presented herein are based on a low driver reciprocating frequency of 0.14/s for a maximum stroke. The figures show that not only is the mean temperature for the RMDHL lower

than the average temperature for the DPDHL cooling loop, the standard deviation around the mean is about 1.5 o C for the RMDHL and about 4 o C for the DPDHL Fig. 9 reveals that although the variation in hot plat temperature is different for the RHMDL and the DPDHL, the variation in the range of the temperature is the same. The range is highest at the entrance; it begins to drop towards as the cooling proceeds towards the entrance. The range is flattening towards the middle with a slight inflection and continues to fall at the outlet of the fluid.

In a bid to determine the efficiency of both systems, this work also proposed a an expression for the Coefficient of Performance (COP) based on temperature. The requirement of adequate coefficient in predicting the system is that the coefficient must satisfies the second law of thermodynamics (Moran and Shapiro, 2004) and should be dependent on operating conditions, especially avarage plate temperature and relative temperature between sink and system. The coefficient is proposed in Equations 15 -17. The COP terms is similar to the term used for determination of the COP for carnot vapor refrigeration cycle. For the basis for selcting the cold reservoir and the hot reservoir is defined in Eq 18. The summary of the calculations is presented in Table 6. Table 6 shows the value of the COP and the resulting efficiency is similar irrespective of the changing heat flux, and the various temperature parameters ??Fig 9) used in computing the terms on the hot plate. The trend follows variations in similar terms in the literature (Moran and Shapiro 2004;Mcquiston et al. 2006). Ultimately the efficiencies show that the value of the efficiency of the RMDHL is about 30% higher than those attained by the DPDHL flow system (Fig 9b). Thp = average temperature of hot plate (ATHP); Tcp = average temperature of cold plate (ATCP) Thf = average temperature of hot fluid (ATHF); ??? = efficiency

9 Conclusion

A numerical model for the simulation of the RMDHL has been successfully built and validated by experimental data. The results indicate that the cooling efficiency of the RMDHL is meaningfully higher than that of the DPDHL with a reduced maximum temperature under the same heat input and cooling conditions. The results show that that the temperature increases with increase of heat flux on the walls or decrease of the flow rate. It was also shown that the temperature profiles are more uniform for an RMDHL loop compared to a DPDHL loop both in terms of temperature uniformity and efficiency.

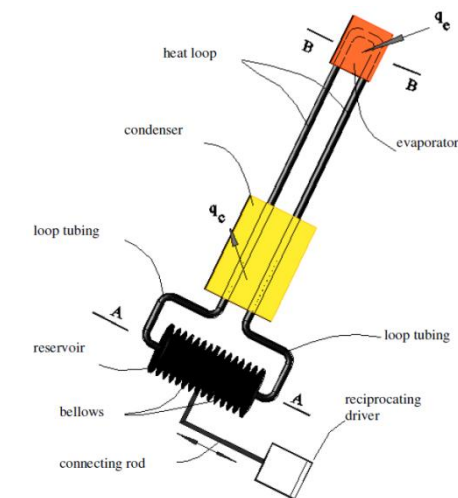
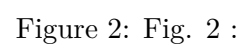
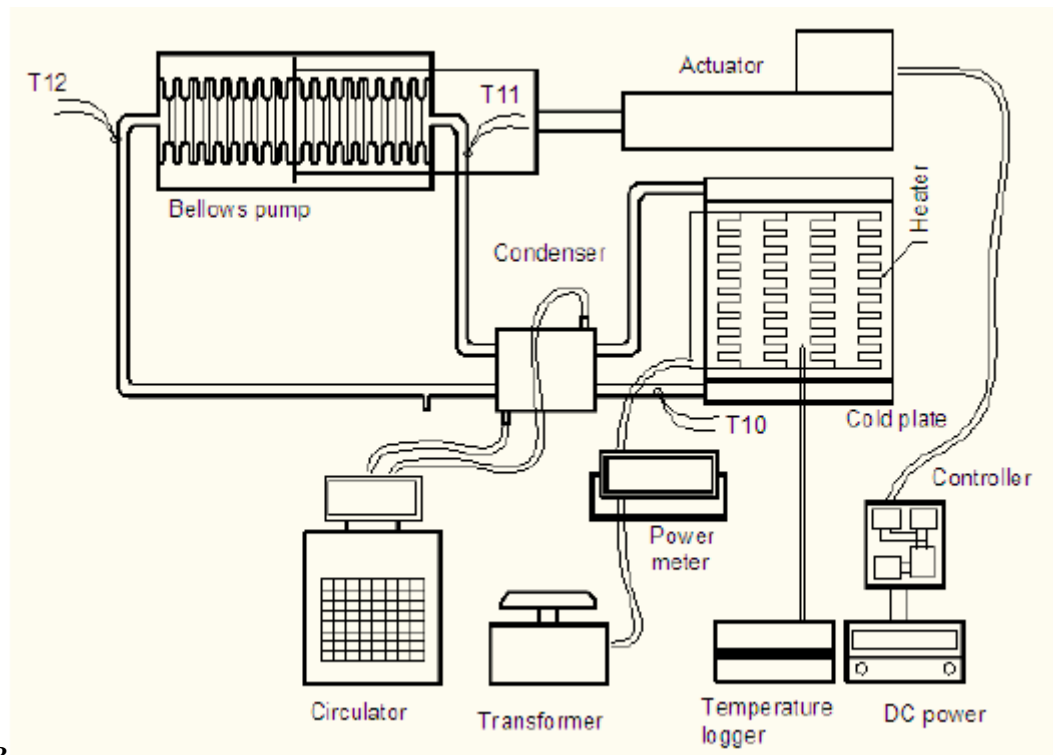


Figure 1: Fig 1 :





3

Figure 3: Fig. 3 :

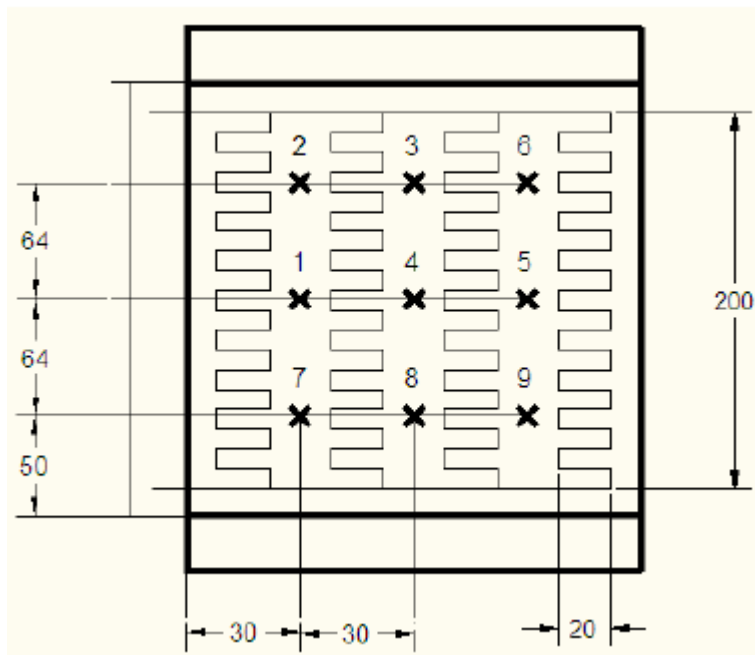


Figure 4:

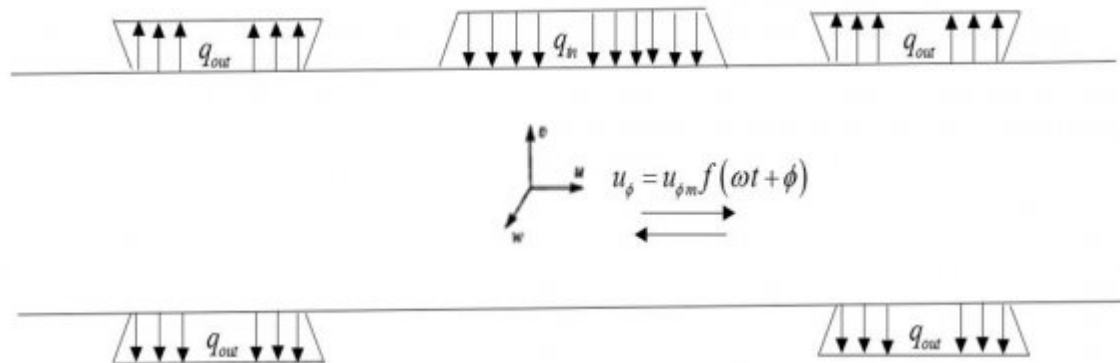
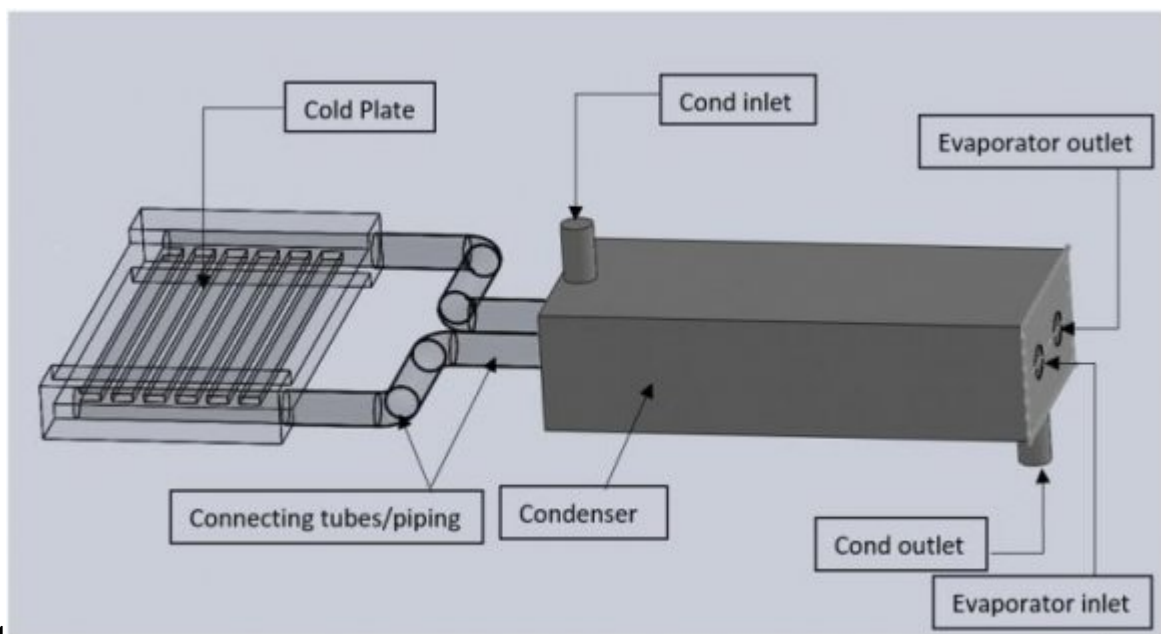


Figure 5:



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Figure 6: Table 2 :Fig. 4 :

56

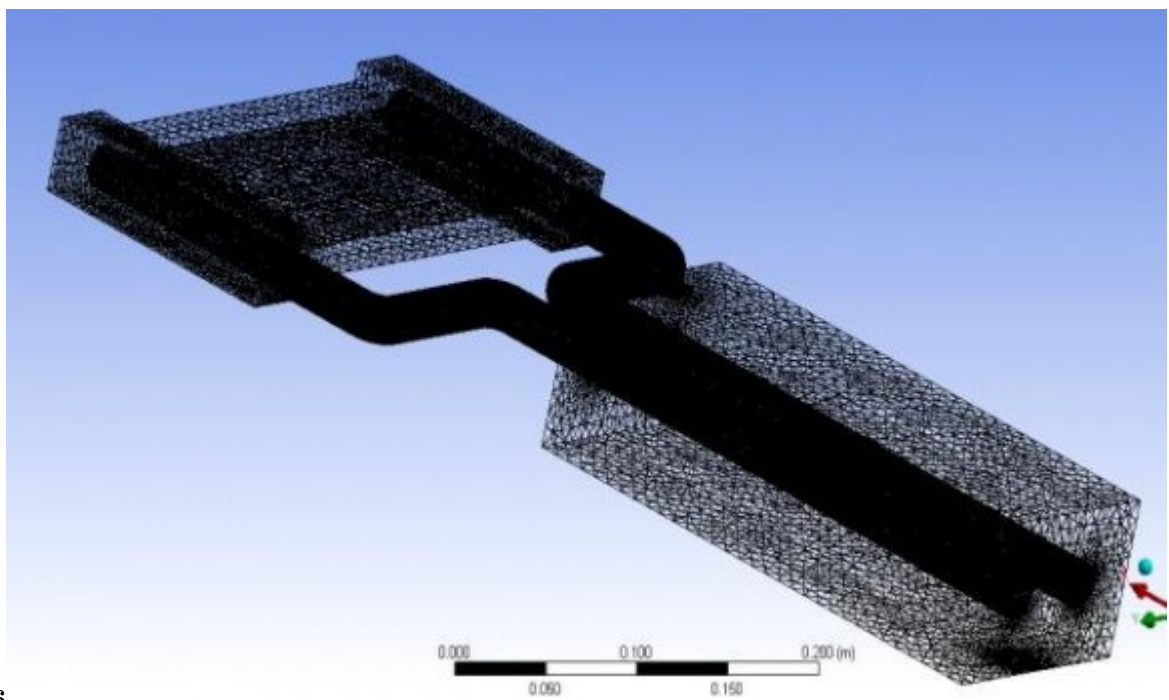


Figure 7: Fig. 5 :GlobalFig. 6 :A

7

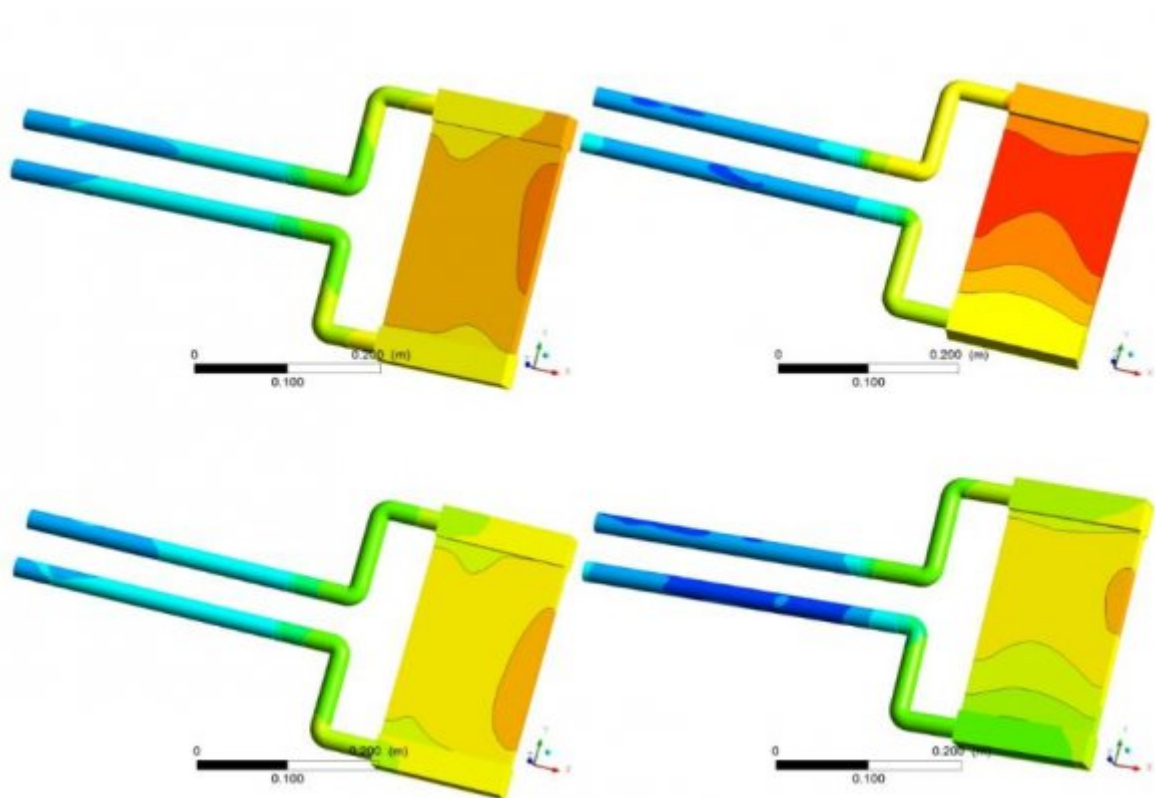
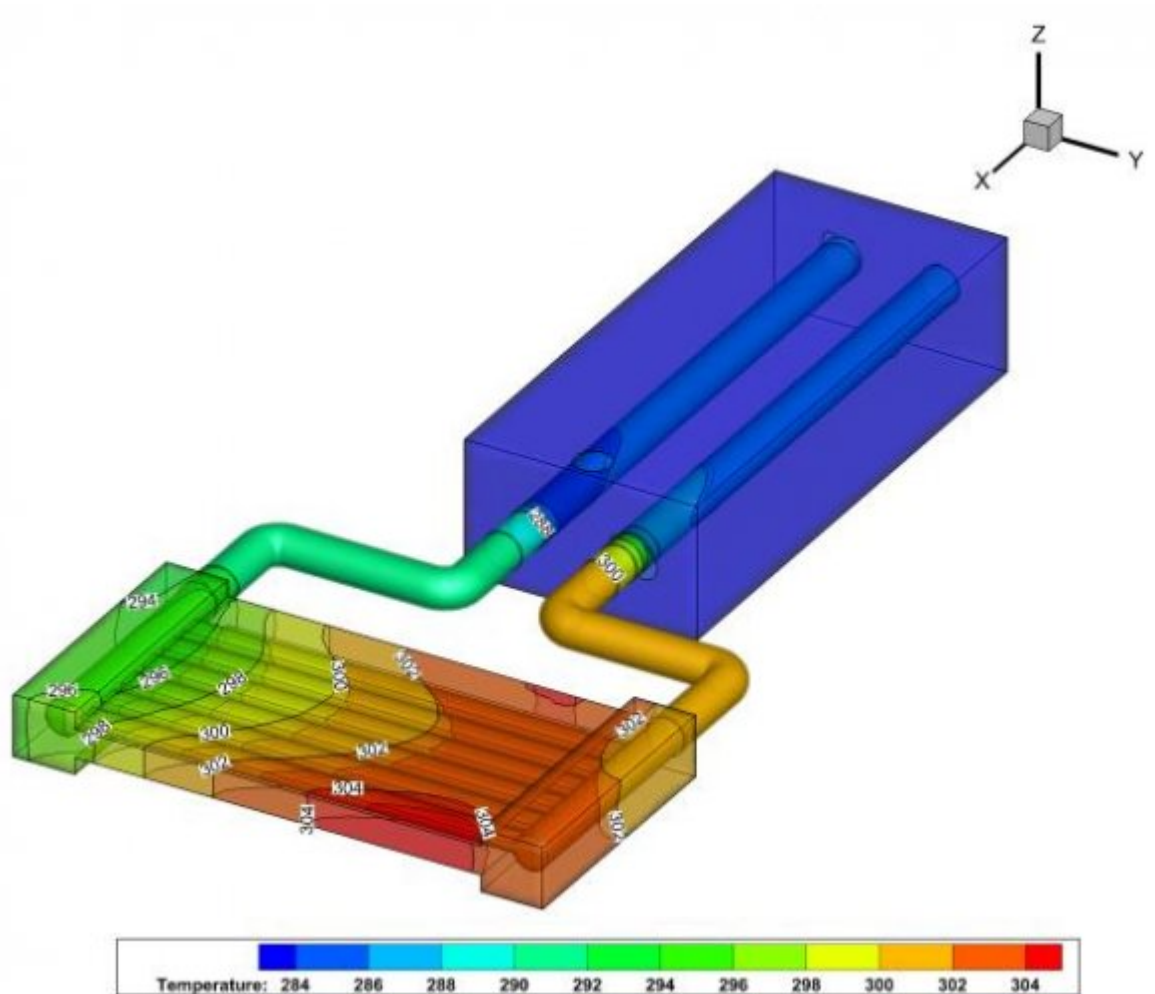


Figure 8: Fig. 7 :



148

Figure 9: (14)Fig. 8 :

9

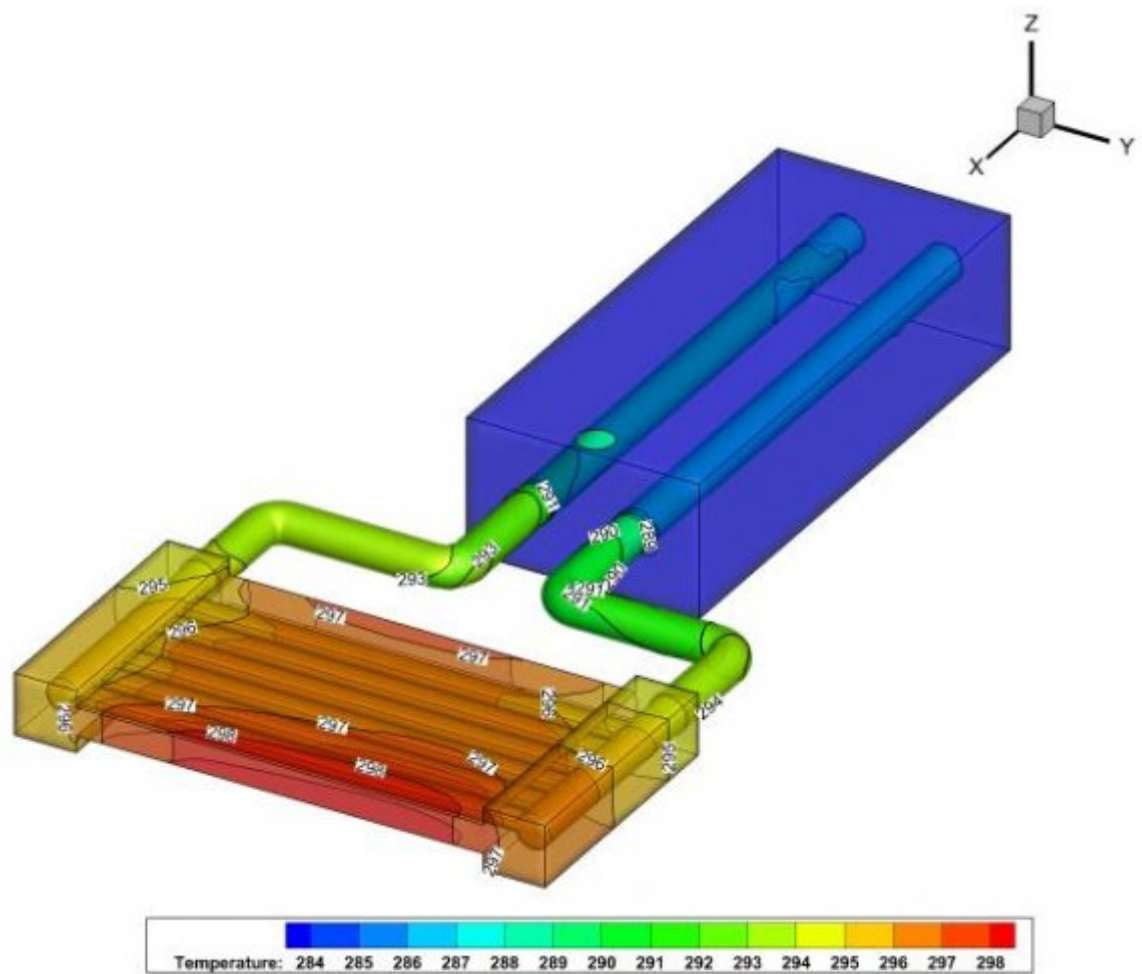


Figure 10: Fig. 9 :

1

Boundary conditions		Values and their ranges.
Inlet velocity of the evaporator	varying	7.62, 8.62, 9.62, 10.62
	stroke (cm)	
	frequency (n)	0.14, 0.28, 0.42, 1
Inlet velocity of the condenser		1.223 m/s
Inlet temperature of the condenser		283 K
Solid wall thickness		0.0001 m
	Heat (W)	Heat Flux (W/m ²)
	551	7983
Heat (Q)	500 455	7244 6592
	400	5795

Figure 11: Table 1 :

3

Year 2017		550W Experimental		Numerical		400W	
Thermocouple No		Temperature (K)					
A	1	305.9		312.1		301.8	307.8
	2	302.0		311.1		297.7	307.0
	3	304.4		312.7		299.9	308.0
	4	306.8		311.9		302.0	307.0
	5	306.9		311.9		303.0	308.2
Regression	6	306.1	308.2	310.9	313.3	302.1	302.9
	7						
	8	303.3		311.1		299.0	307.1
	9	307.2		312.2		303.1	308.1
Regression	R2	0.1		0.0		0.1	0.0
	Slope	0.3		311.86		0.3	311.9
	Intercept (K)	304.32		311.86		304.3	311.9
NSE				-7.87			-7.9
PBIAS				-2.04			-2.1
RSR				2.98			3.0

Figure 12: Table 3 :

4

Q(W)		DPDHL				RMDHL			
		400		550		400		550	
x (m)		Tmin		Tmax		Tmin		Tmax	
0.01	305.90	321.80	15.93	314.70	336.80	22.05	304.90	313.50	8.58
0.03	305.90	321.20	15.33	314.80	336.00	21.22	306.10	313.00	6.88
0.04	306.00	320.60	14.64	314.90	335.10	20.24	307.10	312.80	5.70
0.06	306.00	320.40	14.36	314.90	334.70	19.83	307.50	313.40	5.85
0.08	306.10	320							

Figure 13: Table 4 :

5

Temperature (K)	0.00	0.02	0.04	0.06	0.08	0.10	0.12	0.14
	25.00							
	20.00			$y = -513368x^4 + 129219x^3 - 10010x^2 + 227.05x + 20.494$				
	10.00			$y = -362484x^4 + 91519x^3 - 7112.6x^2 + 162.11x + 14.811$				
	15.00							
	5.00			$y = -9381.8x^3 + 2313x^2 - 178.84x$				
	-							
		0.01	0.03	0.04	0.06	0.08	0.10	0.12
					Increasing X(m)			
		400 W DPDHL	550 W DPDHL		400W WRMDHL	550W RMDHL		
			400W		550W	400W RMDHL	550W RMDHL	
		Section A-A	2.96		4.09	1.67	1.38	
		Section B-B	2.86		3.96	0.86	0.86	
		Section B-B	3.49		4.74	1.99	1.51	
For this purpose, the steady-state minimum temperature, maximum temperature, and the temperature difference, at different power input for water coolant inlet temperatures of 10								

[Note: o C is shown in Table]

Figure 14: Table 5 :

[illegible]

Figure 15: Table 6 :

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