

Modelling and Simulation of Microcode based Built-In Self Test Technology for Multiported Memory

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Abstract

Now a day's embedded memory area and memory density is increasing. Due to this problem of fault is growing exponentially. It is necessary to detect and repair those faults. There are different methods to detect the faults present in memory. Asynchronous P-MBIST method is used to detect the faults. Simulation result includes asynchronous P-MBIST which detect mismatch of data occurred and it is shown by high fault pulse. To correct the detected fault redundancy circuit is used. This system is implemented using FPGA platform.

Index terms— built-in-self test (MBIST), built-in-self repair (BISR), asynchronous P-MBIST, microcode MBIST multiported memory, redundancy logic array, field progr

1 I. Introduction

According to the ITRS 2015, Now a days the memory area is increasing than logic area in SOCs. Fig. ?? [1] shows that shrinking the technologies give rise to defect and new fault models. Thus, the new trends in Multiported memory testing will be driven by the following items. BIST: The new fault and new defects eliminate using BIST. The only solution that allows at-speed testing for embedded memories, it has generate fault detection and coverage, the higher repair efficiency only detecting the faults is no longer sufficient for SOCs so memory repair is also necessary for this purpose both diagnosis and repair algorithm are required. BISR: Combining BIST with efficient and low cost repair schemes in order to improve the yield and system reliability as well.

Fig. ?? : Embedded Memories in Future SOCs [1] Auhtor ? ? : Department of Electronics and telecommunication Bharati Vidyapeeth's College of Engineering for Women Pune, 43 Savitribai Phule Pune University. e-mails: srpatil44@gmail.com, dipali.musleb@gmail.com There are two methods which are efficiently used. These methods are as follow:

2 II. Related Work

Dr. R.K. Sharma et al. [2] introduced Redundancy Array Logic and BISR mechanism used to low cost repair the fault and to improve the system reliability.

Bo-Cheng Charles Lai et al. [4] introduced designs of multiported memories that leverage BRAMs have been proposed to attain better utilization of FPGA resources as well as system performance. BRAMs in an FPGA can support two access ports that can be used as either a read or a write port.

3 A

Global Journal of Researches in Engineering () Volume XVII Issue II Version I Yash Jyothi et al. [1] introduced Asynchronous P-MBIST method for fault detection and repair of multiported memory. The main advantage is to get power efficient P-MBIST, it is being proposed to use handshaking signals instead of using clock and implemented on FPGA. Clocks are used to synchronize the test blocks on chip and handshaking signals are used to communicate between blocks of test controller.

41 **4 III. built-in self test (bist)**

42 Memory Built-In Self Test is test circuitry used to test on-chip memory devices. It contains finite state machine
 43 to generate test vectors to test memory during test mode. Test coller includes Address, Data,
 44 read/write control. This address, data and read/write control signal is given as input to comparator and
 45 multiplexer. Multiplexer uses two modes of operations: Normal mode-In normal mode memory acts as a normal
 46 memory. Test Mode-During test mode test coller provides data and address to memory for testing purpose. In
 47 test mode while performing read operation data from test coller and output of memory are given to comparator
 48 for fault detection. Then, comparator compares test vectors with memory output. If, memory is working properly
 49 then, No Fault is detected and it is declared as memory is fault free but, if fault pulse becomes high it shows
 50 that memory under test is faulty.

51 **5 Implementation of Asynchronous p-mbist**

52 The block diagram shown in Fig. 3 ?? . [1] Table No.1: Microcode Instruction [1] V.

53 **6 Flowchart of Asynchronous p-mbist**

54 The flow of asynchronous P-MBIST is as shown in fig . ??, fig. ??

55 **7 Asynchronous p-mbist Simulation**

56 The simulation of asynchronous P-MBIST is depending upon request signal and mode. Output Response: Normal
 57 Mode: When mode=0, MUX selects normal mode, then test controller is off so as comparator is off. At this
 58 moment memory acts as normal memory without under test and generates external address and data if rw=0(i.e.
 59 reads address and corresponding data).During this mode as comparator is off, no fault pulse is generated. In
 60 this mode, memoutdata (memory output) data is data (External data) provided for normal memory operation.
 61 Test Mode: If mode=1, Memory is under test. If req=1, microcode instruction storage generates Read/Write
 62 control for test collar. Test collar writes data if tcrw=0 otherwise read to memory through MUX. The data from
 63 test collar and output of memory is compared in comparator. If mismatch happens at output of comparator,
 64 comparator generates fault pulse=1 otherwise fault pulse=0 [1]. During the normal mode each incoming address
 65 is compared with the address field of programmed redundant words. If there is a match, the data field of
 66 the redundant word is used along with the faulty memory location for reading and writing data. The output
 67 multiplexer of Redundant Array Logic then ensures that in case of a match, the redundant word data field is
 68 selected over the data read out (= 0) of the faulty location in case of a read signal. This can be easily understood
 69 by the redundancy word detail shown in Figure 7. VII. Results

70 **8 VI.**

71 **9 Repair Module**

72 **10 Single port Memory**

The single port memory support single read and write operation. 1 2 3 4

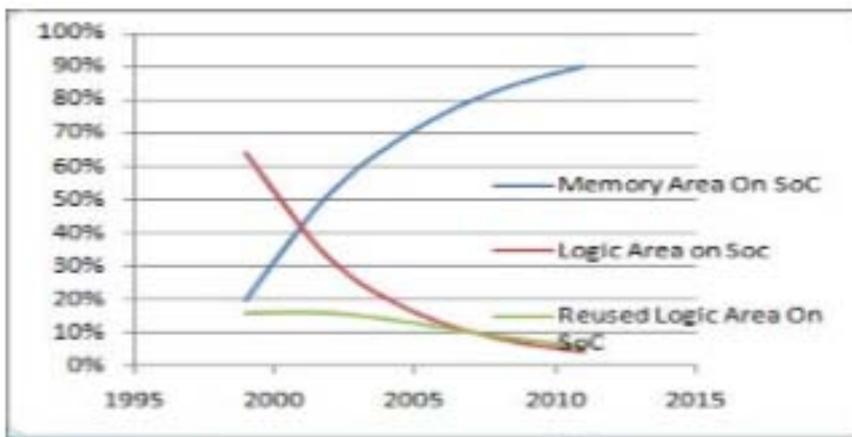


Figure 1: Fig. 2 :

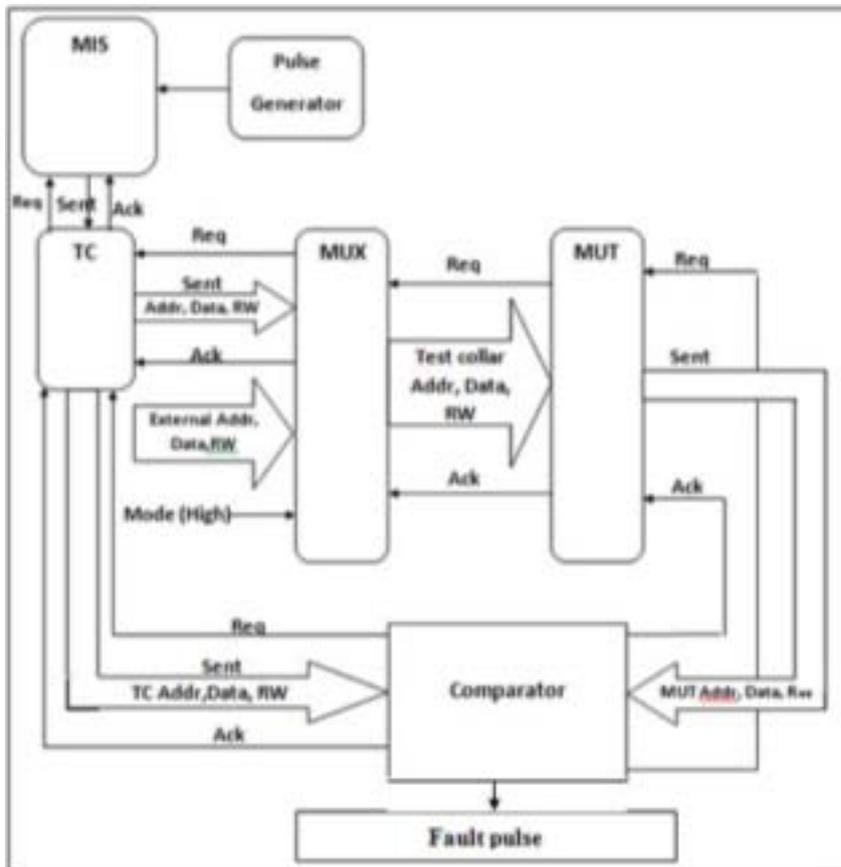


Figure 2:

Instruction	Description
R0	Read is low so no read operation occurs
R1	Read is high so read operation occurs
W0	Write is low so no write operation occurs
W1	Write is high so write operation occurs

3

Figure 3: Fig. 3 :

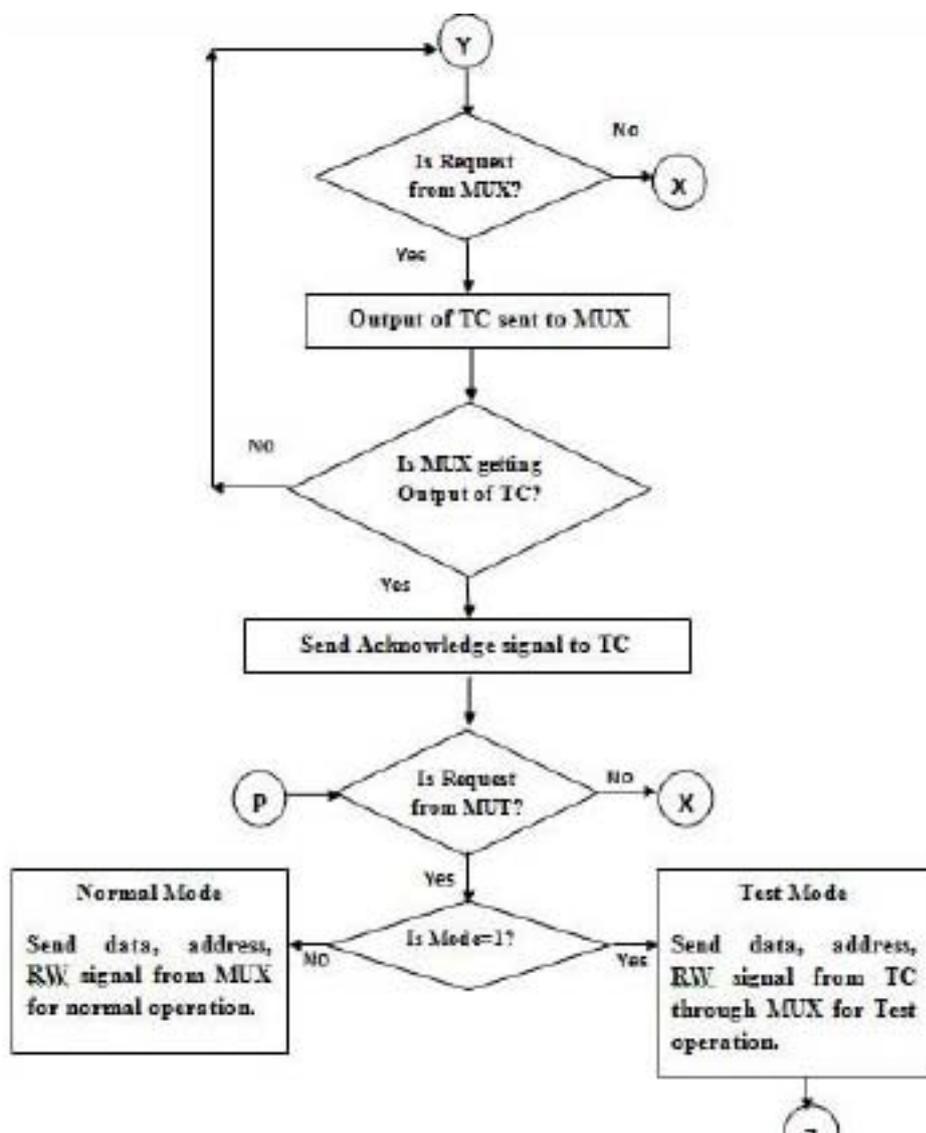
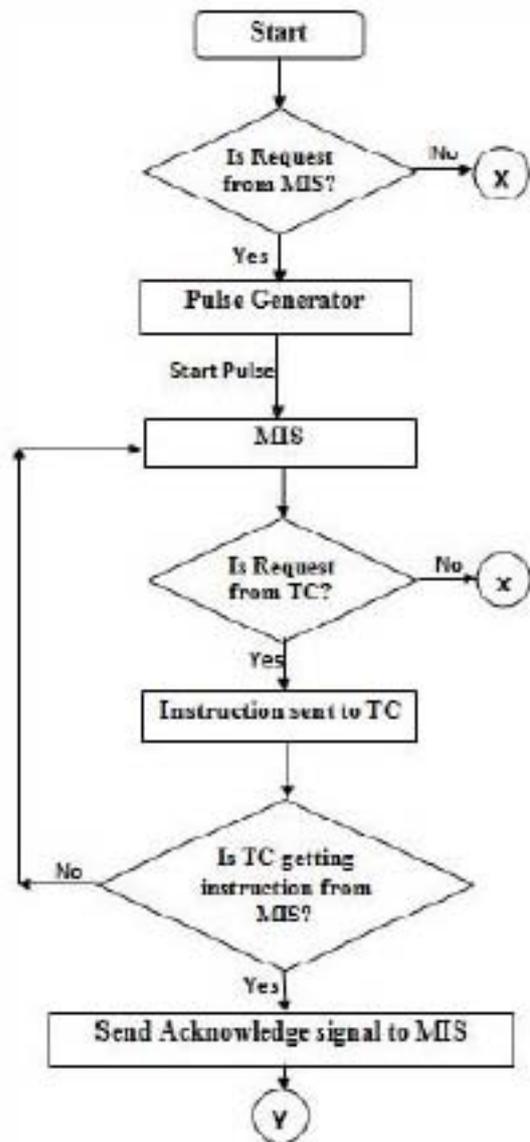


Figure 4: Address



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Figure 5: Fig. 4 :Fig. 5 :Fig. 6 :

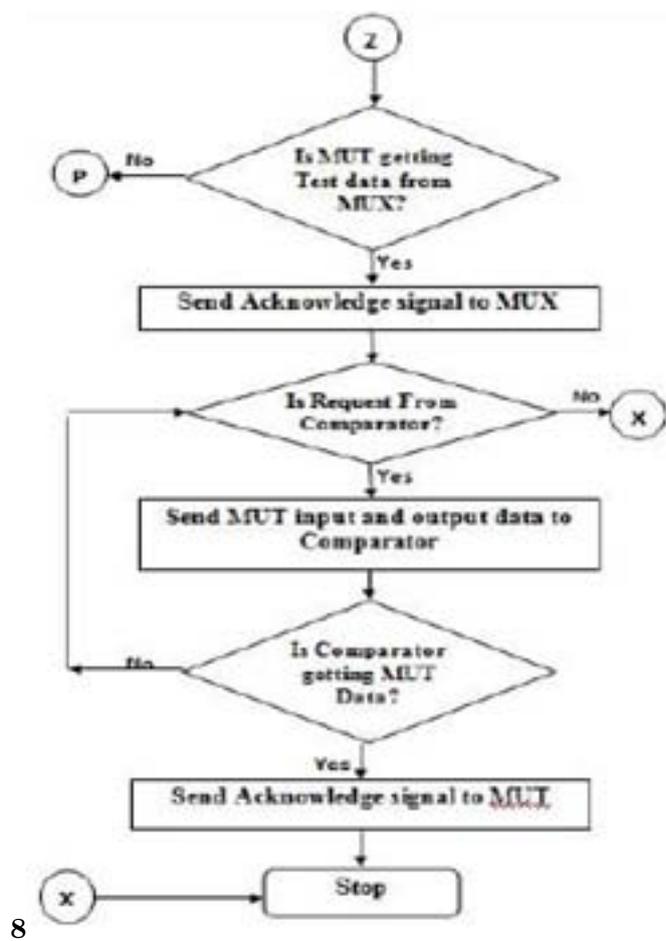
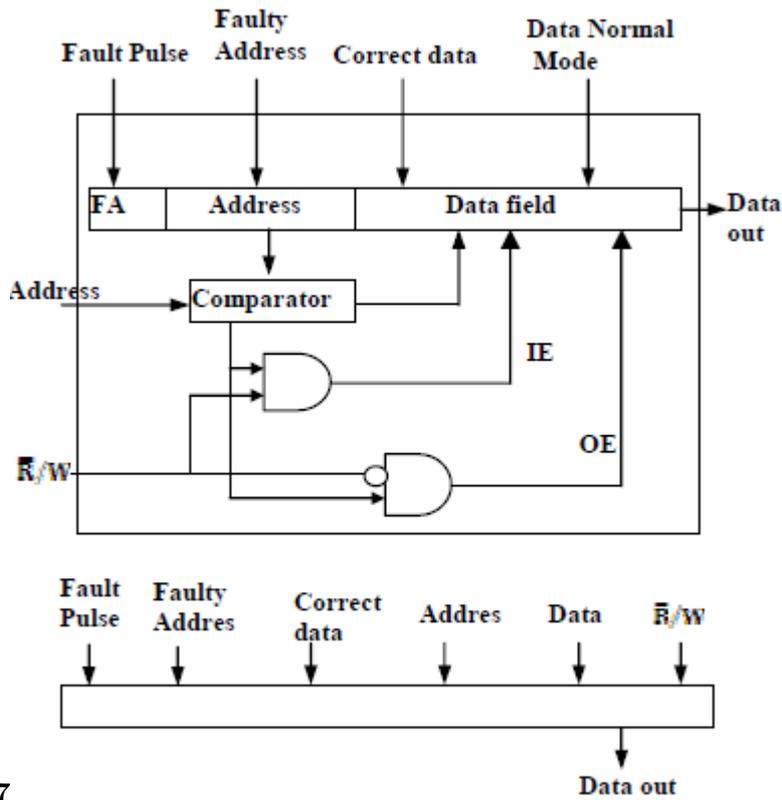


Figure 6: Fig. 8 .



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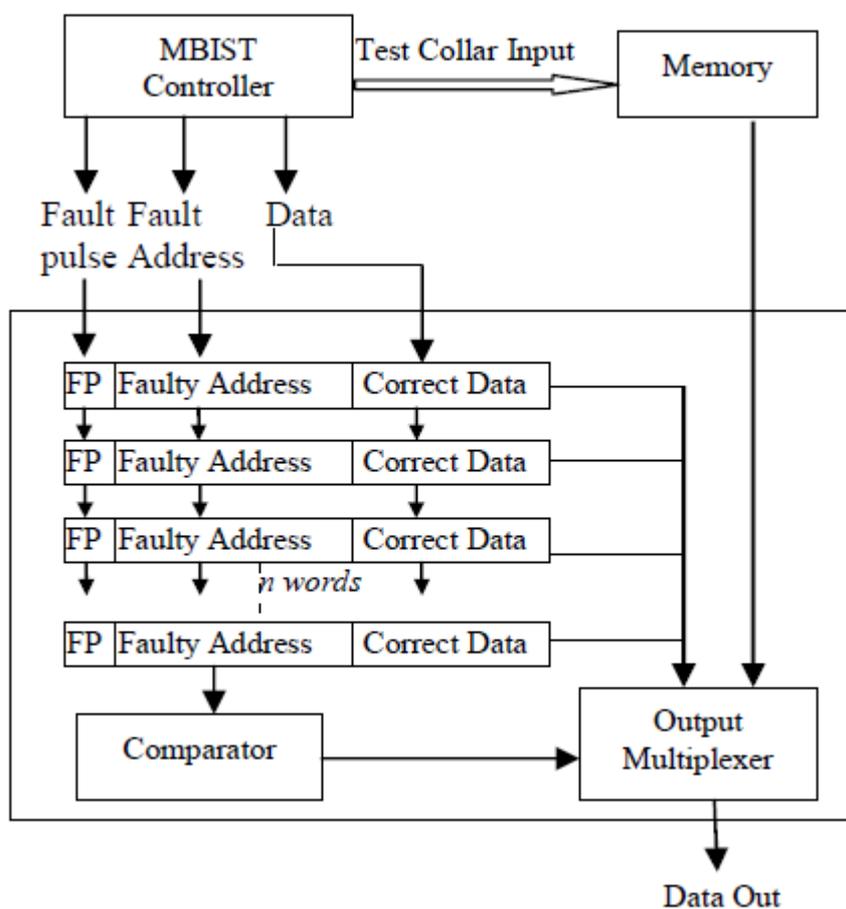
Figure 7: Fig. 7 :

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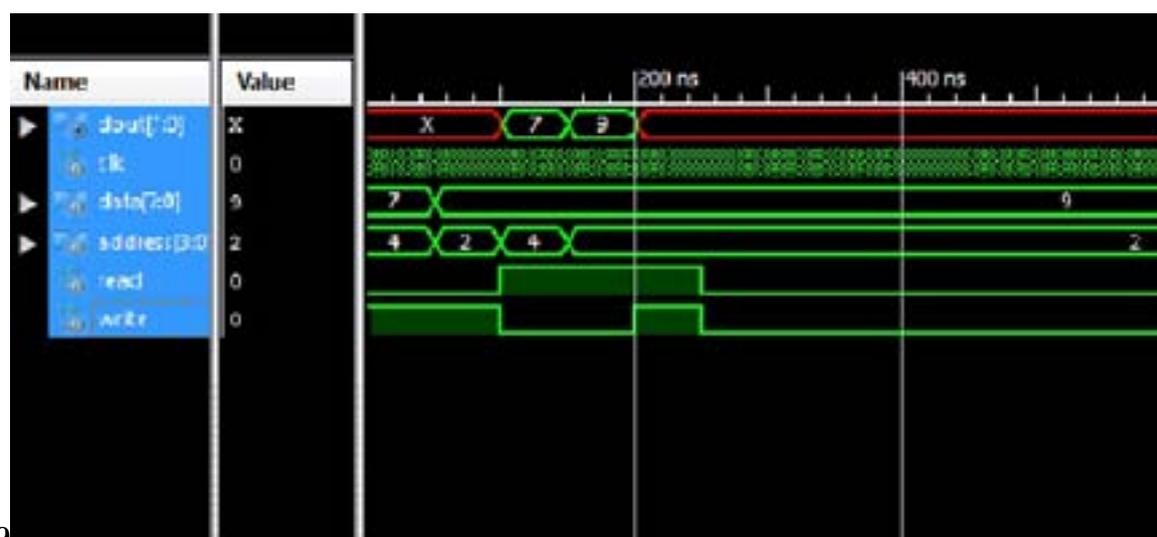
³Year 2017 F © 2017 Global Journals Inc. (US) Fig. 11:

⁴Year 2017 F



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Figure 8: Fig. 8 :Fig. 8 .



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Figure 9: Fig. 9 :

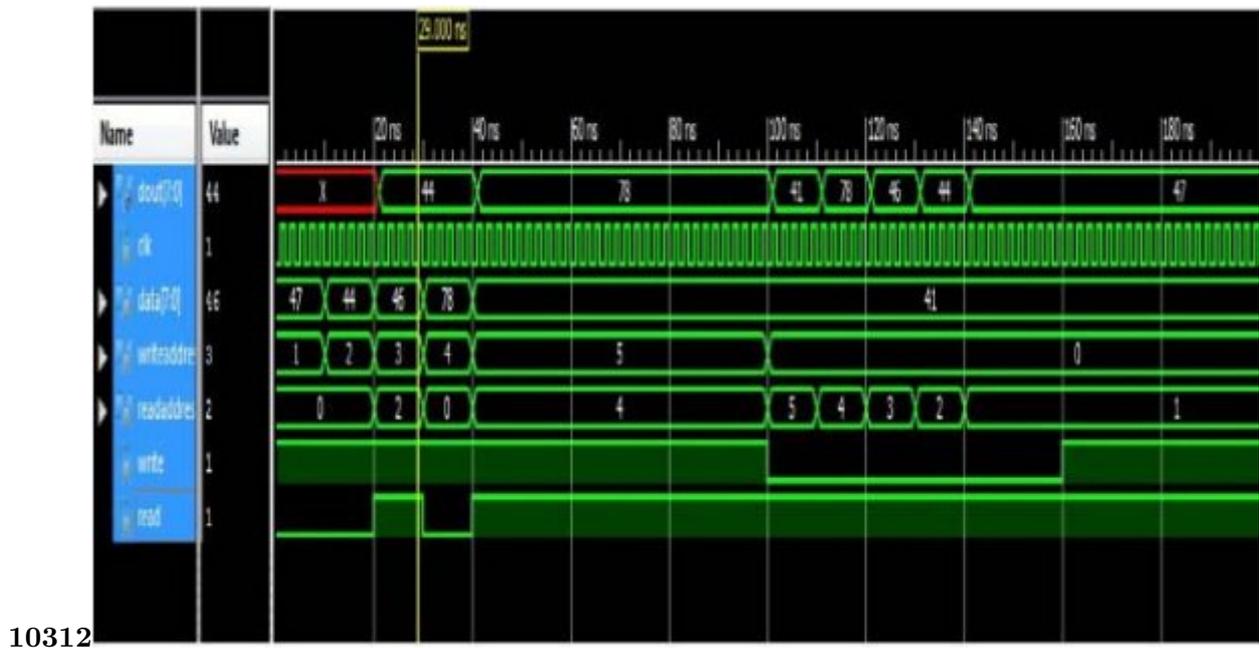


Figure 10: Fig. 10 :F 3 .Fig. 12 :

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MBIST
Controller
Redundancy
circuit

Data	R/W sig- nal
Input	MUX
Multiported	
Memory Output	MUX
Data Out	

[Note: F i. If there is request from Microcode Instruction Storage (MIS) to Pulse generator (PG), then PG sends Start Pulse to MIS to start the asynchronous operation. In next step MIS checks for request from Test Collar (TC), if so it sends microcode instructions to TC. TC then sends the acknowledgement signal to pulse generator indicates that TC is getting instructions from MIs. ii. Output of TC Data which includes test address, corresponding data and R/W control signals send to input multiplexer (MUX) if MUX sends high pulse of request. Multiplexer is originally not a multiplexer but concept used for this block is according to working of normal multiplexer. Here mode signal is select line for MUX. iii. If mode=1then PMBIST works in test mode then it selects TC data. If mode=0 then it is in normal mode, during this mode test circuitry is in ideal condition and memory works as normal memory without under test and sends output of external Address, corresponding data and R/W control signal. When MUX is under test mode then it sends TC data to memory if request signal is high from memory to MUX.]

Figure 11:

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