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1	Development of DC Motor Controlled Automated Manual
2	Transmission (AMT)
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7 Abstract

⁸ Automated Manual Transmission (AMT) has been the best competitive solution to address

⁹ the problem of increasing fuel prices and to meet the emission norms. Automotive world today

¹⁰ mostly uses Automated Manual Transmission (AMT) based on hydraulic actuators. Hydraulic

¹¹ actuators are costly, complex in design, bulky and invite drastic design changes in existing

¹² gearbox. AMT system which is low cost and fuel efficient has been developed using DC motor

¹³ controlled electro mechanical linear actuators. The AMT system consists of three

 $_{14}$ $\,$ electro-mechanical linear actuators, one for clutch and two for gear shift actuations which are

¹⁵ controlled by Transmission control unit (TCU). The wear of synchronizers can be easily taken

¹⁶ care by reprogramming the stroke lengths of linear actuators. This system can be retro fitted

¹⁷ in vehicle with existing manual gearbox and involve minor design changes. The focus of paper

- 18 is to introduce the system developed.
- 19

20 Index terms— actuator, AMT, automated manual transmission, transmission.

21 1 INTRODUCTION

oday the automobile industry is ruled by two forms of transmission, the Manual Transmission (MT) and the 22 Automatic Transmission (AT). The MT is the most efficient transmission available as it lends itself to providing 23 good fuel economy for the vehicles it is employed in. The MT is relatively easy to manufacture because it has very 24 few parts. Another plus point is that the MT is reliable and easy to maintain. However, the major drawback with 25 the MT is that it is less easy to drive than an AT especially, in congested traffic as it requires the driver to operate 26 the clutch for each gear shift. There has been clear trend in automotive industry in recent years towards increased 27 ride comfort and fuel efficiency keeping cost factor in mind. As the power transmission unit, transmissions play an 28 29 important role in vehicle performance and fuel economy. There are currently several types of transmissions and associated technologies that offer different priorities in vehicle. Manual transmission (MT) has overall efficiency 30 of 96 percent which is highest in all types. Belt type CVT (Continuously variable Transmission) has overall 31 efficiency of 85 percent. Automatic Transmission has Traditionally, the AMT has good fuel economy, inferior 32 performance as compared to the MT. The latter can be optimized by refining control strategy. By automating 33 the MT, a cheap and economic transmission is developed. The aim of this paper is to introduce the concept 34 of DC motor controlled AMT. This paper is split into following sections: First, the objective and feature are 35 discussed. Secondly, the concept and working principle are explained. Then gear shifting strategy is discussed. 36 Finally the system performance is evaluated by discussing simulation based results of DC motor controlled AMT. 37

38 2 II.

³⁹ 3 Objective and Features

The objective of this project was to develop a system that can be retro fitted on vehicle with existing MT. The developed system should be compact, simple to manufacture, low cost and should have efficiency par with MT. The developed DC motor controlled electromechanical AMT has many advantages over T conventional hydraulic
 AMT in terms of cost and complexity.

The Low cost AMT has three electro-mechanical linear actuators that are retro fitted on existing MT vehicle. Clutch actuation is done by clutch actuator by modifying existing clutch cable whereas gear select and shift actuation is done by select and shift actuators by modifying existing gear select and shift cables. The actuators are controlled by Transmission control unit efficiency of 86 percent and Automated manual transmission (AMT) has efficiency par with manual transmission. AMT is essentially a MT with an automated control system [1]. Combining the fuel efficiency of an MT with the seamless shifting of an AT, this approach shows excellent promise as a compact and costeffective transmission for future vehicles.

If a transmission could have the benefits of both the MT and AT and the weaknesses of either, this would 51 introduce a new option to the existing market segment. Many researches and studies are directed towards 52 developing AMT. To avoid torque interruption by use of Assist clutch (ACL) by replacing fifth gear synchronizer 53 in gearbox is add-on feature in AMT system [1]. System that allows gear shift in zero seconds was developed, 54 thus eliminating torque interruption during gear shifting [2]. Many researches on AMT Drivetrain modeling 55 and control have also been carried out. In studies devoted to gear shift control [3], considered reduced-order 56 57 driveline models, clutch and gearbox actuator dynamics have been described by simple models or have been 58 neglected. mechanical linear actuators. The AMT system consists of (TCU). This system helps in reducing torque interruption during gear shifts. Thus a low cost, simple and efficient AMT system has been developed 59 60 which can be retro fitted on existing MT vehicle.

61 **4 III.**

CONCEPT AND WORKING PRINCIPLE Fig. 1 shows DC motor based AMT system concept which uses a 62 conventional MT, actuators and TCU to automate the process of clutch actuation and gear shifting. The clutch 63 actuator is connected to clutch lever via clutch cable. Similarly the gear shift and select lever are connected 64 to gear shift and select actuators via shift and select cable respectively. The driver command for gear shift is 65 received by TCU and the corresponding command for actuators are generated after processing all input signals 66 through a gear shifting control strategy. Actuators are selected based on force and linear speed required for gear 67 shift operation. The forces were experimentally measured on clutch lever, gear shift lever and gear select lever 68 and linear speed was finalized from benchmarked standards. Accordingly the linear actuators were selected to 69 suit the purpose. 70

71

IV.

72 5 Gear Shifting Stratergy

Fig. 3 shows the core of control strategy for gear shifting process. First, control is transferred from the driver 73 to the TCU, entering the torque control phase. The engine is controlled to a torque level corresponding to zero 74 transferred torque in the transmission when the clutch is disengaged by clutch actuator. The gear shift actuator 75 actuates followed by actuation of select gear actuator for rank selection and neutral gear is engaged. Then the 76 speed synchronization phase is entered. Here the engine speed is controlled to track the transmission speed as 77 per new gear desired, and the new gear is engaged after select and shift actuator actuations. Finally, the torque 78 level is transferred back to the level that the driver demands when clutch is engaged with help of clutch actuator. 79 It is important to minimize the total time needed for a gear shift to reduce the torque interruption. The shifting 80

strategy is written such that gear shifting takes place in most efficient zone of engine operating condition.

⁸² 6 System Performance

In this section we will summarize our assessment of how well the DC motor controlled AMT achieves the seamless 83 shifting of an AT and the fuel economy of an MT. Fig. 4 shows the torque interruption in AMT and AT. It can 84 be seen that the total shifting time of AMT is less than MT. So traction loss is less in case of AMT and hence 85 greater efficiency. Fig. ?? compares the DC motor controlled AMT with a conventional AT across six different 86 performance measures which are made from the practical data collected on field. It can be seen that the up 87 and downshifting performance of the DC motor controlled AMT is almost the same as the AT. As there is no 88 slippage from the torque converter that is required by an AT, the fuel efficiency and acceleration response of the 89 DC motor controlled AMT are significantly better. On the other hand, the torque converter on the AT gives 90 somewhat smoother starts and more power when accelerating as compared to the DC motor controlled AMT 91 unit but we believe based on this overall assessment that the DC motor controlled AMT has excellent potential 92 as a compact and fuel-efficient next-generation transmission that is also affordable. This DC motor controlled 93 unit can be a good alternative for conventional AT unit. Cost is a major factor which can lead to a breakthrough 94 in the Year 2014 95

96 7 Conclusion

A low cost DC motor controlled AMT concept was developed and performance was evaluated by simulation
 results. The simulation clearly indicates that DC motor controlled AMT is efficient as compared to MT. Low
 cost coupled with high efficiency makes the DC motor controlled AMT an extremely appropriate alternative for

the conventional AMT. This type of alternative is a much desired and awaited demand of Asian and European
 Markets. Simplicity in packaging and uncomplicated serviceable design makes this concept a technology for
 future. This has the potential to become the next big tech revolution in the automobile world.

- ¹⁰³ The Conversion of an Existing MT to DC motor controlled AMT has the Following Benefits
- ¹⁰⁴ ? Automated gear shift in optimum engine efficiency zone with improved shift quality.
- ¹⁰⁵ ? Improved fuel economy compared with torque converter AT.
- 106 ? Improved acceleration performance and less traction losses.
- 107 ? Easy to manufacture and is retro fit to install.

Since this concept of AMT system separates the actuator from the gearbox, the actuators can be designed independently and applied to different types of manual transmission with the same capacity. However, non-ideal mechanical connection between the actuator and gearbox brings some technical difficulties, such as cable wear,

- $\scriptstyle 111$ $\,$ elasticity and mechanical clearance that need to be overcome.
- In conclusion, the low cost DC motor controlled AMT is technically feasible, but there is still a great deal of research to be performed before commercialization.

VII.



Figure 1: Figure 1 :

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Figure 2: Figure 2 :



Figure 3: Figure 3 :



Figure 4: Figure 4:









Figure 6: Figure 6: 2014 6

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